

# Displacement Logic for Grammar

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Lecture 3

From Displacement Calculus to Displacement Logic:  
Polymorphism

Displacement *calculus* constitutes the ‘multiplicative’ fragment of a much wider non-commutative intuitionistic sublinear displacement *logic* for categorial grammar.

# 2nd-Order Displacement Logic

	cont. mult.	disc. mult.	secon. disc. mult.	add.	qu.	norm. mod.	brack. mod.	exp.	limited contr. & weak.
primitive	/ • 	↑ ⊙ J	↑↑ ⊙ K	& ⊕	∧ ∨	□ ◇	[ ] <sup>-1</sup> ⟨ ⟩	! ?	 W
sem. inactive variants	← ○    ○ → ●    ●	↑ ○    ○ ↓ ●    ●	↑↑ ○    ○ ↓↓ ●    ●	□ ⊔	∨ ∃	■ ◆			
det.	◁ <sup>-1</sup> ▷ <sup>-1</sup>	∨	≈						
synth.	◁    ▷	∧	≈						diff.
nondet.	÷	≡ ↓							
synth.	×	◇							-

# (1st-Order) Displacement Logic

	cont. mult.	disc. mult.	add.	qu.	norm. mod.	brack. mod.	exp.	limited contr. & weak.
primitive	$/$ $\bullet$ $ $	$\uparrow$ $\odot$ $J$	$\&$ $\oplus$	$\wedge$ $\vee$	$\square$ $\diamond$	$[\ ]^{-1}$ $\langle \rangle$	$!$ $?$	$ $ $W$
sem. inactive variants	$\bullet \dashv \circ$ $\circ \dashv \bullet$ $\bullet$ $\bullet$	$\uparrow \downarrow$ $\uparrow \downarrow$ $\bullet$ $\bullet$	$\square$ $\sqcup$	$\forall$ $\exists$	$\blacksquare$ $\blacklozenge$			
det. synth.	$\triangleleft^{-1}$ $\triangleright^{-1}$ $\triangleleft$ $\triangleright$	$\vee$ $\wedge$						diff.
nondet. synth.	$\div$ $\times$	$\triangleq$ $\diamond$						-

# Multiplicatives

$$1. \quad \frac{\Gamma \Rightarrow B \quad \Delta \langle \vec{C} \rangle \Rightarrow D}{\Delta \langle \vec{C/B}, \Gamma \rangle \Rightarrow D} /L \quad \frac{\Gamma, \vec{B} \Rightarrow C}{\Gamma \Rightarrow C/B} /R$$

$$2. \quad \frac{\Gamma \Rightarrow A \quad \Delta \langle \vec{C} \rangle \Rightarrow D}{\Delta \langle \Gamma, \vec{A \setminus C} \rangle \Rightarrow D} \setminus L \quad \frac{\vec{A}, \Gamma \Rightarrow C}{\Gamma \Rightarrow A \setminus C} \setminus R$$

$$3. \quad \frac{\Delta \langle \vec{A}, \vec{B} \rangle \Rightarrow D}{\Delta \langle \vec{A \bullet B} \rangle \Rightarrow D} \bullet L \quad \frac{\Gamma_1 \Rightarrow A \quad \Gamma_2 \Rightarrow B}{\Gamma_1, \Gamma_2 \Rightarrow A \bullet B} \bullet R$$

$$4. \quad \frac{\Delta \langle \Lambda \rangle \Rightarrow A}{\Delta \langle \vec{I} \rangle \Rightarrow A} IL \quad \frac{}{\Lambda \Rightarrow I} IR$$

$$5, k. \quad \frac{\Gamma \Rightarrow B \quad \Delta \langle \vec{C} \rangle \Rightarrow D}{\Delta \langle \vec{C} \uparrow_k \vec{B} \mid_k \Gamma \rangle \Rightarrow D} \uparrow_k L \quad \frac{\Gamma \mid_k \vec{B} \Rightarrow C}{\Gamma \Rightarrow C \uparrow_k B} \uparrow_k R$$

$$6, k. \quad \frac{\Gamma \Rightarrow A \quad \Delta \langle \vec{C} \rangle \Rightarrow D}{\Delta \langle \Gamma \mid_k \vec{A} \downarrow_k \vec{C} \rangle \Rightarrow D} \downarrow_k L \quad \frac{\vec{A} \mid_k \Gamma \Rightarrow C}{\Gamma \Rightarrow A \downarrow_k C} \downarrow_k R$$

$$7, k. \quad \frac{\Delta \langle \vec{A} \mid_k \vec{B} \rangle \Rightarrow D}{\Delta \langle \vec{A} \odot_k \vec{B} \rangle \Rightarrow D} \odot_k L \quad \frac{\Gamma_1 \Rightarrow A \quad \Gamma_2 \Rightarrow B}{\Gamma_1 \mid_k \Gamma_2 \Rightarrow A \odot_k B} \odot_k R$$

$$8. \quad \frac{\Delta \langle 1 \rangle \Rightarrow A}{\Delta \langle \vec{J} \rangle \Rightarrow A} JL \quad \frac{}{1 \Rightarrow J} JR$$

# Additives

$\mathcal{F}_i ::= \mathcal{F}_i \& \mathcal{F}_i \quad T(A \& B) = T(A) \& T(B)$  additive conjunction  
 $\mathcal{F}_i ::= \mathcal{F}_i \oplus \mathcal{F}_i \quad T(A \oplus B) = T(A) + T(B)$  additive disjunction

Approximate algebraic interpretation:

$$\begin{aligned} [[A \& B]] &= [[A]] \cap [[B]] \\ [[A \oplus B]] &= [[A]] \cup [[B]] \end{aligned}$$

$$9. \quad \frac{\Gamma \langle \vec{A} \rangle \Rightarrow C}{\Gamma \langle \vec{A \& B} \rangle \Rightarrow C} \&L_1 \quad \frac{\Gamma \langle \vec{B} \rangle \Rightarrow C}{\Gamma \langle \vec{A \& B} \rangle \Rightarrow C} \&L_2$$

$$\frac{\Gamma \Rightarrow A \quad \Gamma \Rightarrow B}{\Gamma \Rightarrow A \& B} \&R$$

$$10. \quad \frac{\Gamma \langle \vec{A} \rangle \Rightarrow C \quad \Gamma \langle \vec{B} \rangle \Rightarrow C}{\Gamma \langle \vec{A \oplus B} \rangle \Rightarrow C} \oplus L$$

$$\frac{\Gamma \Rightarrow A}{\Gamma \Rightarrow A \oplus B} \oplus R_1 \quad \frac{\Gamma \Rightarrow B}{\Gamma \Rightarrow A \oplus B} \oplus R_2$$



# Quantifiers

$\mathcal{F}_i ::= \bigwedge x \mathcal{F}_i$      $T(\bigwedge x A) = F \rightarrow T(A)$     universal quantifier  
 $\mathcal{F}_i ::= \bigvee \mathcal{F}_i$      $T(\bigvee x A) = F \& T(A)$     existential quantifier

Approximate algebraic interpretation:

$$\begin{aligned} [[\bigwedge A]] &= \bigcap_t [[A\{t/x\}]] \\ [[\bigvee A]] &= \bigcup_t [[A\{t/x\}]] \end{aligned}$$

$$11. \quad \frac{\Gamma \langle \overrightarrow{A[t/v]} \rangle \Rightarrow B}{\Gamma \langle \bigwedge vA \rangle \Rightarrow B} \wedge L \quad \frac{\Gamma \Rightarrow A[a/v]}{\Gamma \Rightarrow \bigwedge vA} \wedge R^{\dagger}$$

$$12. \quad \frac{\Gamma \langle \overrightarrow{A[a/v]} \rangle \Rightarrow B}{\Gamma \langle \bigvee vA \rangle \Rightarrow B} \vee L^{\dagger} \quad \frac{\Gamma \Rightarrow A[t/v]}{\Gamma \Rightarrow \bigvee vA} \vee R$$

$\dagger$  indicates that there is no  $a$  in the conclusion

# Semantically labelled continuous multiplicatives

1. 
$$\frac{\Gamma \Rightarrow B: \psi \quad \Delta \langle \vec{C}: z \rangle \Rightarrow D: \omega}{\Delta \langle \vec{C}/\vec{B}: x, \Gamma \rangle \Rightarrow D: \omega\{(x \psi)/z\}} /L \qquad \frac{\Gamma, \vec{B}: y \Rightarrow C: \chi}{\Gamma \Rightarrow C/B: \lambda y \chi} /R$$
2. 
$$\frac{\Gamma \Rightarrow A: \phi \quad \Delta \langle \vec{C}: z \rangle \Rightarrow D: \omega}{\Delta \langle \Gamma, \vec{A} \setminus \vec{C}: y \rangle \Rightarrow D: \omega\{(y \phi)/z\}} \setminus L \qquad \frac{\vec{A}: x, \Gamma \Rightarrow C: \chi}{\Gamma \Rightarrow A \setminus C: \lambda x \chi} \setminus R$$
3. 
$$\frac{\Delta \langle \vec{A}: x, \vec{B}: y \rangle \Rightarrow D: \omega}{\Delta \langle \vec{A} \bullet \vec{B}: z \rangle \Rightarrow D: \omega\{\pi_1 z/x, \pi_2 z/y\}} \bullet L \qquad \frac{\Gamma_1 \Rightarrow A: \phi \quad \Gamma_2 \Rightarrow B: \psi}{\Gamma_1, \Gamma_2 \Rightarrow A \bullet B: (\phi, \psi)} \bullet R$$
4. 
$$\frac{\Delta \langle \wedge \rangle \Rightarrow A: \phi}{\Delta \langle \vec{I}: x \rangle \Rightarrow A: \phi} /L \qquad \frac{}{\wedge \Rightarrow I: 0} /R$$

# Semantically labelled discontinuous multiplicatives

$$5. \frac{\Gamma \Rightarrow B: \psi \quad \Delta \langle \vec{C}: z \rangle \Rightarrow D: \omega}{\Delta \langle \vec{C} \uparrow_k \vec{B}: x \mid_k \Gamma \rangle \Rightarrow D: \omega \{(x \psi) / z\}} \uparrow_k L$$

$$\frac{\Gamma \mid_k \vec{B}: y \Rightarrow C: \chi}{\Gamma \Rightarrow C \uparrow_k B: \lambda y \chi} \uparrow_k R$$

$$6. \frac{\Gamma \Rightarrow A: \phi \quad \Delta \langle \vec{C}: z \rangle \Rightarrow D: \omega}{\Delta \langle \Gamma \mid_k \vec{A} \downarrow_k \vec{C}: y \rangle \Rightarrow D: \omega \{(y \phi) / z\}} \downarrow_k L$$

$$\frac{\vec{A}: x \mid_k \Gamma \Rightarrow C: \chi}{\Gamma \Rightarrow A \downarrow_k C: \lambda x \chi} \downarrow_k R$$

$$7. \frac{\Delta \langle \vec{A}: x \mid_k \vec{B}: y \rangle \Rightarrow D: \omega}{\Delta \langle \vec{A} \odot_k \vec{B}: z \rangle \Rightarrow D: \omega \{\pi_1 z / x, \pi_2 z / y\}} \odot_k L$$

$$\frac{\Gamma_1 \Rightarrow A: \phi \quad \Gamma_2 \Rightarrow B: \psi}{\Gamma_1 \mid_k \Gamma_2 \Rightarrow A \odot_k B: (\phi, \psi)} \odot_k R$$

$$8. \frac{\Delta \langle 1 \rangle \Rightarrow A: \phi}{\Delta \langle \vec{J}: x \rangle \Rightarrow A: \phi} JL \quad \frac{}{1 \Rightarrow J: 0} JR$$

# Semantically labelled additives

$$9. \quad \frac{\Delta \langle \vec{A}: x \rangle \Rightarrow C: \chi}{\Delta \langle \vec{A \& B}: z \rangle \Rightarrow C: \chi \{ \pi_1 z / x \}} \&L_1 \quad \frac{\Delta \langle \vec{B}: y \rangle \Rightarrow C: \chi}{\Delta \langle \vec{A \& B}: z \rangle \Rightarrow C: \chi \{ \pi_2 z / y \}} \&L_2$$

$$\frac{\Gamma \Rightarrow A: \phi \quad \Gamma \Rightarrow B: \psi}{\Gamma \Rightarrow A \& B: (\phi, \psi)} \&R$$

$$10. \quad \frac{\Delta \langle \vec{A}: x \rangle \Rightarrow C: \chi_1 \quad \Delta \langle \vec{B}: y \rangle \Rightarrow C: \chi_2}{\Delta \langle \vec{A \oplus B}: z \rangle \Rightarrow C: z \rightarrow x.\chi_1; y.\chi_2} \oplus L$$

$$\frac{\Delta \Rightarrow A: \phi}{\Gamma \Rightarrow A \oplus B: t_1 \phi} \oplus R_1 \quad \frac{\Gamma \Rightarrow B: \psi}{\Delta \Rightarrow A \oplus B: t_2 \psi} \oplus R_2$$

The additives of Lambek (1961[2]), Morrill (1990[3]), Kanazawa (1992[1]), have application to polymorphism. For example the additive conjunction  $\&$  can be used for **rice**:  $N\&CN$  as in **rice grows**:  $S$  and **the rice grows**:  $S$ .

Note the computational advantage of this approach over assuming an empty determiner: if empty operators were allowed they could occur any number of times in any positions.

The additive disjunction  $\oplus$  can be used for  
**is**:  $(N \setminus S) / (N \oplus (CN / CN))$  as in **Tully is Cicero**:  $S$  and  
**Tully is humanist**:  $S$ .

The additive disjunction can be used together with the  
continuous unit to express the optionality of a complement as in  
**eats**:  $(N \setminus S) / (N \oplus I)$  for **John eats fish**:  $S$  and **John eats**:  $S$ .

Note the advantage of this over simply listing intransitive and  
transitive lexical entries: empirically the latter does not capture  
the generalisation that in both cases the verb *eats* combines  
with a subject to the left, and computationally every lexical  
ambiguity doubles the lexical insertion search space. Appeal to  
lexical ambiguity is at best a promissory solution, unless there  
is true ambiguity.

# Semantically labelled quantifiers

$$\begin{array}{l}
 11. \quad \frac{\Delta \langle \overrightarrow{A[t/v]: x} \Rightarrow B: \psi \rangle}{\Delta \langle \bigwedge vA: z \Rightarrow B: \psi \{ (z \ t) / x \} \rangle} \wedge L \qquad \frac{\Gamma \Rightarrow A[a/v]: \phi}{\Gamma \Rightarrow \bigwedge vA: \lambda v \phi} \wedge R^+ \\
 \\
 12. \quad \frac{\Delta \langle \overrightarrow{A[a/v]: x} \Rightarrow B: \psi \rangle}{\Delta \langle \bigvee vA: z \Rightarrow B: \psi \{ \pi_2 z / x \} \rangle} \vee L^+ \qquad \frac{\Gamma \Rightarrow A[t/v]: \phi}{\Gamma \Rightarrow \bigvee vA: (t, \phi)} \vee R
 \end{array}$$



The quantifiers of Morrill (1994[4]) have application to features. For example, singular and plural number in **sheep**:  $\bigwedge nCNn$  for **the sheep grazes**:  $S$  and **the sheep graze**:  $S$ . And for a past, present or future tense finite sentence complement we can have **said**:  $(N \setminus S) / \bigvee tSf(t)$  in **John said Mary walked**:  $S$ , **John said Mary walks**:  $S$  and **John said Mary will walk**:  $S$ .

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