

# Beyond Shortest Paths: Node Fairness in Route Recommendation

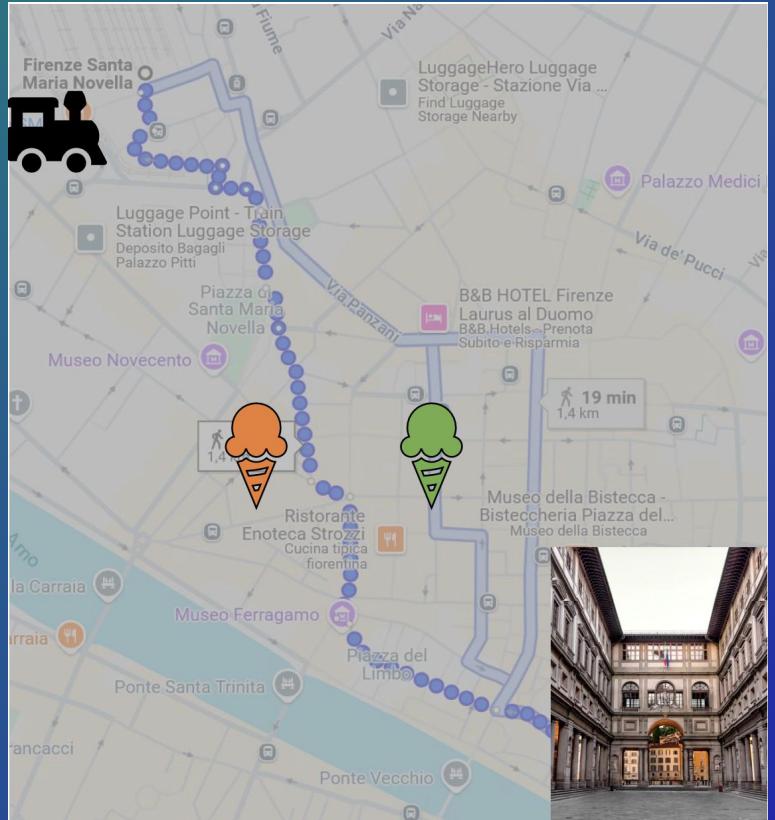
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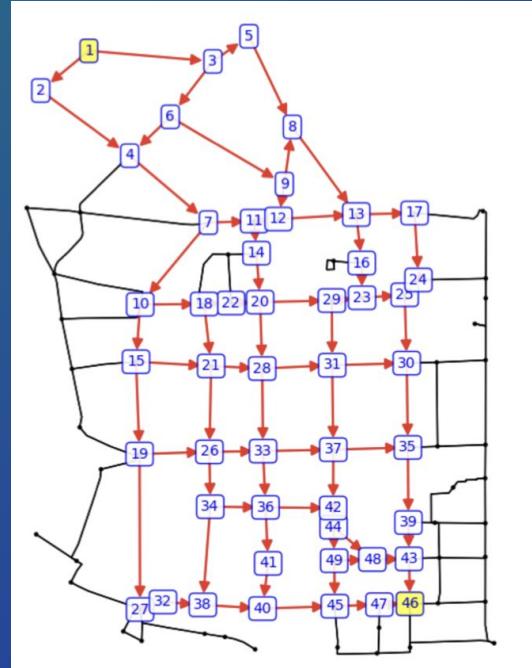
# Motivating Scenario

The tourism office of the municipality of Florence produces an **app for helping tourists walking around the city center**, moving in between the key attractions and historic landmarks. Shortly after the introduction of the app, an **ice-cream parlor**, located in a strategic position for tourists flowing in between the Central Train Station and the Uffizi Gallery, sees a sudden **drop of its sales**. Investigating the issue, they realize that the new app was routing all the tourists moving in between the two landmarks, **always through the same shortest path**, greatly reducing the visibility of the ice-cream parlor which was located along a slightly longer path. At the same time, a newly opened ice-cream parlor located on the recommended shortest path, sees its sales skyrocketing.

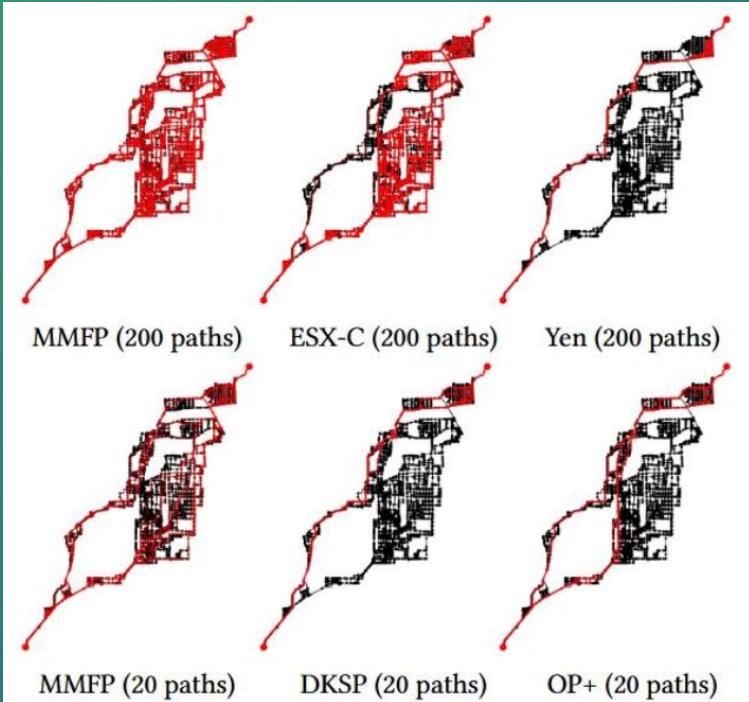


## Goal:

**“Guarantee a fair distribution of visits across network nodes while maintain near-optimal routes.”**



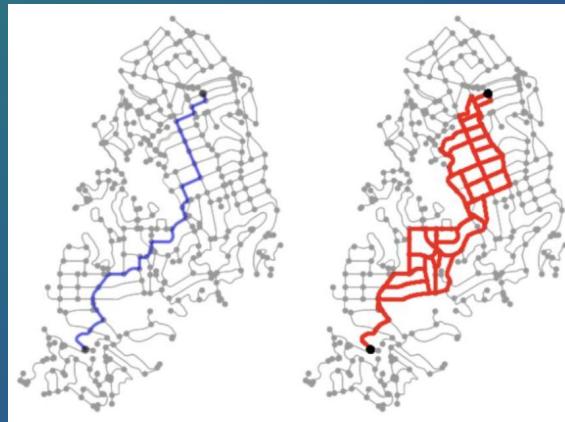
# Related work: Diversity in point-to-point path queries



- Lots of work, several slightly different problem statements:
  - E.g., find a set of  $k$  paths that are sufficiently dissimilar and as short as possible
- Diversity and Fairness are related notions, however:
  - Fairness guarantees some level of diversity
  - while diversity does not provide any fairness guarantee
- Diversity is necessary yet not sufficient condition for fairness

# What kind of paths should be allowed?

- In a weighted graph the **s-t shortest path** is often unique
- We need to relax the requirement of being the shortest to have a basis for fairness
- Instead of using a tolerance parameter, we define **forward paths**

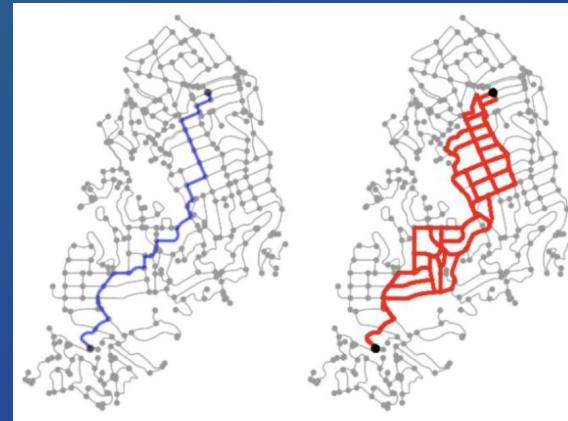
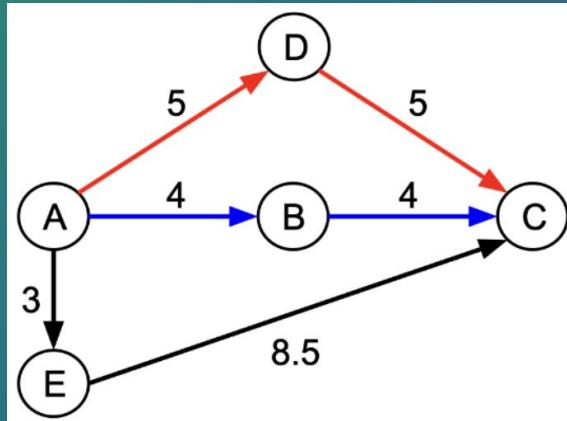


# First contribution: Forward Paths

Definition:

A *s-t forward path* is a path that, at each step, decreases the distance to the target

- Aligns well with user preferences in real-world applications
  - Always progressing toward their destination, no backtracking or moving in circles



# First contribution: Forward Paths

**Definition 1 (s-t-Forward path).** An  $s$ - $t$ -path  $P = (v_1 = s, \dots, v_k = t)$  in a graph  $G$  is called **forward** if for  $i = 1, \dots, k - 1$ ,

$$d(v_{i+1}, t) < d(v_i, t) ,$$

where  $d$  represents the shortest path distance in  $G$ .

**Proposition 1:** Let  $G$  be a directed (weighted or unweighted) graph. Any **shortest path** in  $G$  is a **forward path**.

**Proposition 2:** Let  $G$  be a directed unweighted graph. An  $s$ - $t$ -path is a **shortest path** if and only if it is a **forward path**.

# First contribution: Forward Paths

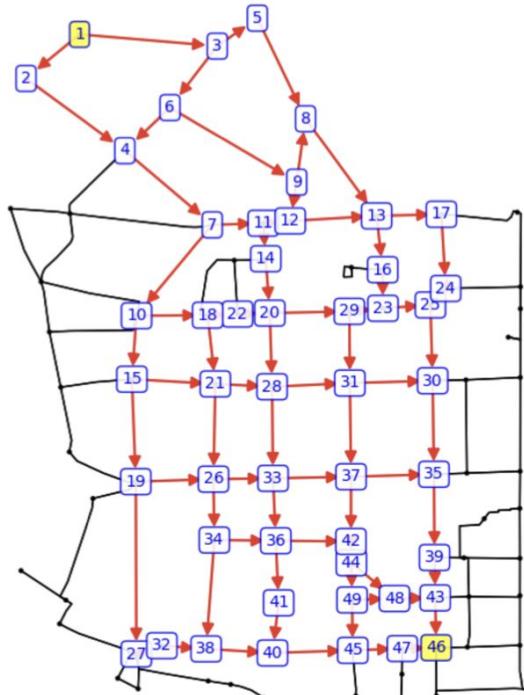
- We empirically show that in many real-world weighted graphs, **forward paths are very close in length to the shortest path** and **they're many more**
  - with a minimal increase in the worst-case forward path length
  - the number of locations visited by the union of all forward paths increases significantly

Dataset	# nodes	# edges	SP length	LFP length	LFP/SP length	SP nodes	FP nodes	FP/SP nodes
Piedmont, California	352	937	1 860.07	2 061.58	$1.11 \pm 0.11$	19.91	39.48	$1.81 \pm 0.66$
Essaouira, Morocco	1 277	3 429	3 650.36	3 967.11	$1.13 \pm 0.14$	37.20	107.03	$2.52 \pm 1.33$
Florence, Italy	6 096	11 737	6 909.52	7 287.29	$1.05 \pm 0.05$	75.10	121.27	$1.58 \pm 0.65$
Buenos Aires, Argentina	17 890	37 474	9 065.83	9 642.57	$1.06 \pm 0.04$	89.10	387.50	$4.00 \pm 2.12$
Kyoto, Japan	44 828	118 087	8 501.42	9 243.75	$1.09 \pm 0.06$	117.90	536.77	$4.16 \pm 2.21$
Florida, USA	1 070 376	2 687 902	$4.12 \cdot 10^6$	$4.22 \cdot 10^6$	$1.02 \pm 0.02$	1 194.27	2 720.63	$2.33 \pm 0.95$
Eastern USA	3 598 623	8 708 058	$4.39 \cdot 10^6$	$4.57 \cdot 10^6$	$1.04 \pm 0.02$	1 924.43	7 046.97	$3.28 \pm 1.45$



# Our Problem

Given a weighted graph (road network), a source node  $s$ , a destination node  $t$ , produce a **probabilistic distribution over forward paths** from  $s$  to  $t$  such that it is **maxmin-fair** for all the eligible nodes (those that belong to at least a forward path).



Path	Probability (%)
[1, 2, 4, 7, 10, 15, 19, 27, 32, 38, 40, 45, 47, 46]	10.4
[1, 3, 6, 9, 12, 13, 16, 23, 25, 30, 35, 39, 43, 46]	8.3
[1, 3, 6, 9, 12, 13, 17, 24, 25, 30, 35, 39, 43, 46]	8.3
[1, 3, 5, 8, 13, 16, 23, 25, 30, 35, 39, 43, 46]	8.3
[1, 3, 5, 8, 13, 17, 24, 25, 30, 35, 39, 43, 46]	8.3
[1, 3, 6, 4, 7, 10, 15, 19, 27, 32, 38, 40, 45, 47, 46]	6.2
[1, 2, 4, 7, 10, 18, 22, 20, 29, 31, 37, 42, 44, 49, 48, 43, 46]	5.2
[1, 2, 4, 7, 11, 14, 20, 29, 31, 37, 42, 44, 49, 48, 43, 46]	5.2
[1, 2, 4, 7, 10, 18, 22, 20, 28, 33, 36, 41, 40, 45, 47, 46]	3.5
[1, 2, 4, 7, 11, 14, 20, 28, 33, 36, 41, 40, 45, 47, 46]	3.5
[1, 2, 4, 7, 10, 15, 21, 26, 34, 36, 41, 40, 45, 47, 46]	3.5
[1, 2, 4, 7, 10, 18, 21, 26, 34, 36, 41, 40, 45, 47, 46]	3.5
[1, 3, 6, 4, 7, 10, 18, 22, 20, 29, 31, 37, 42, 44, 49, 48, 43, 46]	3.1
[1, 3, 6, 4, 7, 11, 14, 20, 29, 31, 37, 42, 44, 49, 48, 43, 46]	3.1
[1, 3, 6, 4, 7, 10, 18, 22, 20, 28, 33, 36, 41, 40, 45, 47, 46]	2.1
[1, 3, 6, 4, 7, 11, 14, 20, 28, 33, 36, 41, 40, 45, 47, 46]	2.1
[1, 3, 6, 4, 7, 10, 15, 21, 26, 34, 36, 41, 40, 45, 47, 46]	2.1
[1, 3, 6, 4, 7, 10, 18, 21, 26, 34, 36, 41, 40, 45, 47, 46]	2.1
[1, 2, 4, 7, 10, 18, 22, 20, 28, 33, 37, 42, 44, 49, 48, 43, 46]	1.7
[1, 2, 4, 7, 11, 14, 20, 28, 33, 37, 42, 44, 49, 48, 43, 46]	1.7
[1, 2, 4, 7, 10, 15, 21, 26, 34, 38, 40, 45, 47, 46]	1.7
[1, 2, 4, 7, 10, 18, 21, 26, 34, 38, 40, 45, 47, 46]	1.7
[1, 3, 6, 4, 7, 10, 18, 22, 20, 28, 33, 37, 42, 44, 49, 48, 43, 46]	1.0
[1, 3, 6, 4, 7, 11, 14, 20, 28, 33, 37, 42, 44, 49, 48, 43, 46]	1.0
[1, 3, 6, 4, 7, 10, 15, 21, 26, 34, 38, 40, 45, 47, 46]	1.0
[1, 3, 6, 4, 7, 10, 18, 21, 26, 34, 38, 40, 45, 47, 46]	1.0

# Technical challenges and contributions

## 1. How to enumerate all forward paths (which can be exponential in number)?

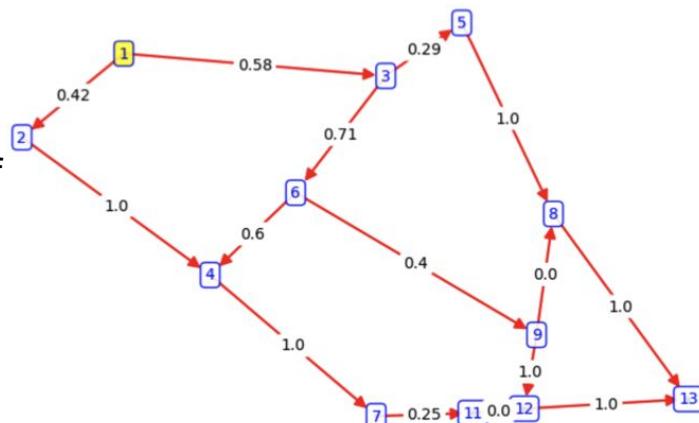
- We can compute a Directed Acyclic Graph (**DAG**) representing all the forward paths
- Avoid the need to explicitly enumerate the set of all possible forward paths

## 2. How to compute the maxmin-fair distribution over forward paths?

- We design a **Linear Programming Flow Problem** which allows us to derive the maxmin-fair distribution over forward paths

## 3. How to store and sample from the maxmin-fair distribution?

- Our method does not materialize the distribution explicitly
- Just assigns the correct transition probability to each arc of the DAG
- We show that a **random-walk** on this probabilistic graph from  $s$  to  $t$  is equivalent to sampling from the underlying maxmin-fair distribution



# Algorithm 1: DAG of Forward Paths

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**Algorithm 1** DAG-FP: Creates a DAG containing the Forward Paths from  $s$  to  $t$

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**Input:** Graph  $G = (V, E, \ell)$ , source node  $s$ , target node  $t$

**Output:** DAG with Forward Paths

```
1: dist_from_s  $\leftarrow$  distance( $G, s, V$ )
2: dist_to_t  $\leftarrow$  distance( $G, V, t$ )
3: reachable_from_s  $\leftarrow \{i \mid \text{dist\_from\_s}[i] < \infty\}$ 
4: reachable_to_t  $\leftarrow \{i \mid \text{dist\_to\_t}[i] < \infty\}$ 
5: reachable  $\leftarrow \text{reachable\_from\_s} \cap \text{reachable\_to\_t}$ 
6:  $G' \leftarrow G.\text{induced\_subgraph}(\text{reachable})$ 
7: for all  $(u, v)$  in  $G'.\text{edges}$  do
8:   if  $\text{dist\_to\_t}[u] \leq \text{dist\_to\_t}[v]$  then
9:     remove  $(u, v)$  from  $G'$ 
10:   end if
11: end for
12: return  $G'$ 
```

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Same asymptotic computational runtime as solving a single shortest-path query

# Algorithm 2: Maxmin-Fair Forward Paths

maximize  $\lambda \in \mathbb{R}$  subject to

$$\begin{aligned}
 & \sum_{u|(u,t) \in E} f_{u,t} = 1 \\
 & \sum_{u|(s,u) \in E} -f_{s,u} = -1 \\
 & \sum_{u|(u,v) \in E} f_{u,v} - \sum_{w|(v,w) \in E} f_{v,w} = 0 \quad \forall v \neq s, t \\
 & \lambda - \sum_{u|(u,v) \in E} f_{u,v} \leq 0 \quad \forall v \notin K \\
 & - \sum_{u|(u,v) \in E} f_{u,v} \leq -\alpha_v \quad \forall v \in K \\
 & f_{u,v} \geq 0 \quad \forall (u,v) \in E
 \end{aligned} \tag{1}$$

minimize  $d_t - d_s - \sum_{v \in K} \alpha_v w_v$  subject to

$$\begin{aligned}
 & d_v - d_u - w_v \geq 0 \quad \forall (u,v) \in E \\
 & \sum_{v \notin K} w_v = 1 \\
 & w_v \geq 0 \quad \forall v \in V \\
 & d_v \in \mathbb{R} \quad \forall v \in V
 \end{aligned} \tag{2}$$

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### Algorithm 2 MMFP - MaxMin Fair Forward Paths

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**Input:** DAG  $G$ , source node  $s$ , target node  $t$

**Output:** Encoding of a maxmin-fair distribution for  $s, t$ -forward paths

- 1:  $K \leftarrow \emptyset$
- 2: **while**  $K \neq V$  **do**
- 3:     Solve LP (1) and its dual LP (2);
- 4:     let  $\lambda^*$ ,  $\{f_{u,v}^*\}$ ,  $\{w_v^*\}$  be the optimum values
- 5:      $K' \leftarrow \{v \notin K \mid w_v^* > 0\}$
- 6:      $K \leftarrow K \cup K'$
- 7:     **for all**  $v \in K'$  **do**
- 8:          $\alpha_v \leftarrow \lambda^*$
- 9:     **end for**
- 10: **end while**
- 11: Return the flow values  $f_{u,v}^*$

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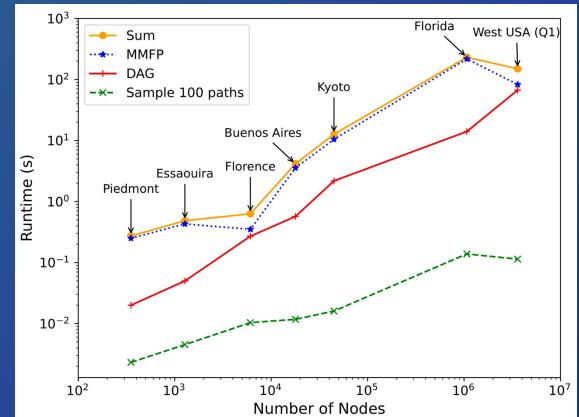
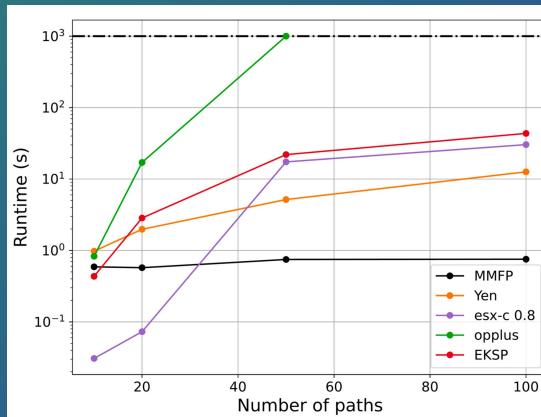
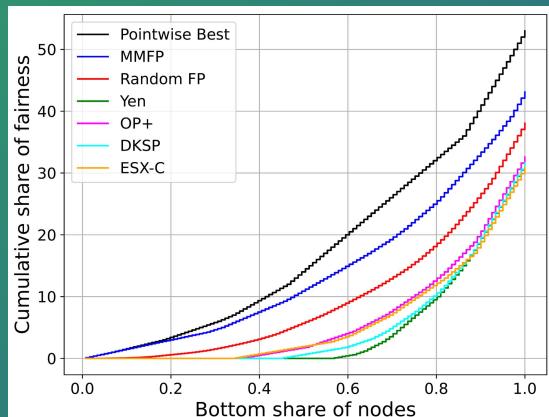
- It can be solved in **polynomial time** by solving a sequence of small linear programs
- MMFP is **Optimal**

# Practical implications and deployment

- Same query can be served many times for different users
  - Well suited when computing high volumes of different alternative paths
  - Methods from the literature on diverse path recommendations face significant challenges to recommend several different alternative paths
- Each  $s-t$  pair defines its own problem instance
  - Highly parallelizable
- The maxmin-fair distribution for an  $s-t$  pair needs only be computed once and stored
  - At query time only sampling from the distribution is needed

# Main results and takeaways

- MMFP reduces inequalities
- Well suited to serve a high amount of paths
- Empirical results confirm theoretical runtimes



# THANKS!



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