Computació i Sistemes Intel·ligents Part III: Machine Learning

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Dept. CS, UPC

Fall 2023

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Website

Please go to http://www.cs.upc.edu/~csi for all course's material, schedule, lab work, etc.

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Announcements through https://raco.fib.upc.edu

Class logistics

- ▶ Theory slots on Tuesdays.
- Laboratory slots on Thursdays.
- ▶ 1 exam (multiple choice exam): Monday Dec. 19th, in class

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▶ 1 project (due after Christmas break, date TBD)

Check http://www.cs.upc.edu/~csi for details about the schedule.

Lab

Environment for practical work

We will use python3 and jupyter and the following libraries:

▶ pandas, numpy, scipy, scikit-learn, seaborn, matplotlib

During the first session we will cover how to install these in case you use your laptop. Libraries are already installed in the schools' computers.

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... so, let's get started!

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What is Machine Learning?

An example: digit recognition

Input: image e.g. 4 Output: corresponding class label [0..9]

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Very hard to program yourself

Easy to assing *labels*

What is Machine Learning?

An example: flower classification (the famous "iris" dataset)

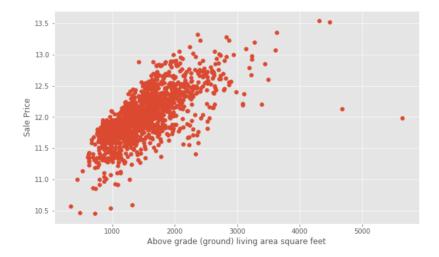


Sepal.Length	Sepal.Width	Petal.Length	Petal.Width	Species
5.1	3.5	1.4	0.2	setosa
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What is Machine Learning?

An example: predicting housing prices (regression)



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Is Machine Learning useful?

Applications of ML

- Web search
- Computational biology
- Finance
- E-commerce (recommender systems)
- Robotics
- Autonomous driving
- Fraud detection

- Information extraction
- Social networks
- Debugging
- Face recognition
- Credit risk assessment
- Medical diagnosis

... etc

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About this course

A gentle introduction to the world of ML

This course will teach you:

- Basic into concepts and intuitions on ML
- To apply off-the-shelf ML methods to solve different kinds of prediction problems
- ▶ How to use various python tools and libraries

This course will *not*:

- Cover the underlying theory of the methods used
- Cover many existing algorithms, in particular will not cover neural networks or deep learning

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Types of Machine Learning

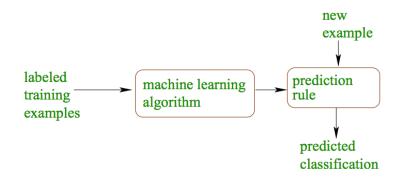
- Supervised learning:
 - regression, classification
- Unsupervised learning:
 - clustering, dimensionality reduction, association rule mining, outlier detection

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- Reinforcement learning:
 - learning to act in an environment

Supervised learning in a nutshell

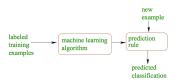
Typical "batch" supervised machine learning problem..



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Prediction rule = model

Try it! Examples are animals



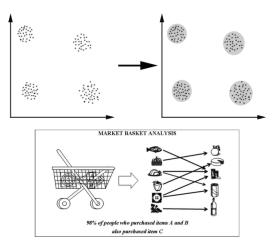
- positive training examples: bat, leopard, zebra, mouse
- negative training examples: ant, dolphin, sea lion, shark, chicken

Come up with a classification rule, and predict the "class" of: tiger, tuna.

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Unsupervised learning

Clustering, association rule mining, dimensionality reduction, outlier detection



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ML in practice

Actually, there is much more to it ..

- Understand the domain, prior knowledge, goals
- Data gathering, integration, selection, cleaning, pre-processing
- Create models from data (machine learning)
- Interpret results
- Consolidate and deploy discovered knowledge

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... start again!

ML in practice

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... start again!

Representing objects

Features or attributes, and target values

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Typical representation for supervised machine learning:

 Features or attributes: sepal length, sepal width, petal length, petal width

▶ Target value (class): species

Main objective in classification: predict class from features values

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Some basic terminology

The following are terms that should be clear:

- dataset
- features
- target values (for classification)
- example, labelled example (a.k.a. sample, datapoint, etc.)

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class

- model (hypothesis)
- learning, training, fitting
- classifier
- prediction

Today we will cover decision trees and the nearest neighbors algorithm

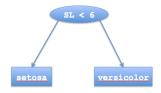
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Decision Tree: Hypothesis Space

A function for classification

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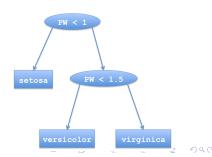


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Decision Tree: Hypothesis Space

A function for classification

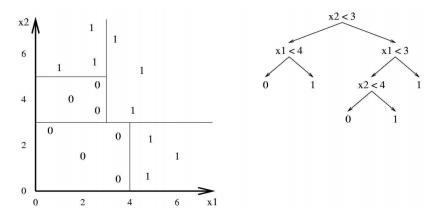
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$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	2	high	0	d	bad	0					
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	3	high	0	с	good	1					
6 low 1 d good 0 high high low high low	4	low	1	с	bad	1					
6 low 1 d good 0 high	5	low	1	е	good	1		(×.		
sh low high low	6	low	1	d	good	0				1	
	high	x 1	lov	N.	hie		low		_		

Exercise: Count many classification errors each tree makes.

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Decision Tree Decision Boundary

Decision trees divide the feature space into **axis-parallel** rectangles and label each rectangle with one of the classes.



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The greedy algorithm for boolean features

```
	ext{GROWTREE}(S)

if y = 0 for all (x, y) \in S then

return new leaf(0)

else if y = 1 for all (x, y) \in S then

return new leaf(1)

else

choose best attribute x_j
```

```
S_0 \leftarrow 	ext{all } (	ext{x}, y) 	ext{ with } x_j = 0
```

 $S_1 \leftarrow ext{all } (ext{x}, y) ext{ with } x_j = 1$

return new $node(GROWTREE(S_0), GROWTREE(S_1))$ end if

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The greedy algorithm for boolean features

```
egin{aligned} & \operatorname{GROWTREE}(S) \ & \operatorname{if}\ y = 0\ & \operatorname{for}\ & \operatorname{all}\ (\mathrm{x},y) \in S\ & \operatorname{then}\ & \operatorname{return}\ & \operatorname{new}\ & leaf(0) \ & \operatorname{else}\ & \operatorname{if}\ y = 1\ & \operatorname{for}\ & \operatorname{all}\ (\mathrm{x},y) \in S\ & \operatorname{then}\ & \operatorname{return}\ & \operatorname{new}\ & leaf(1) \ & \operatorname{else}\ & \operatorname{choose}\ & \operatorname{best}\ & \operatorname{attribute}\ & x_j \ & S_0 \leftarrow & \operatorname{all}\ (\mathrm{x},y)\ & \operatorname{with}\ & x_j = 0 \end{aligned}
```

 $S_1 \leftarrow ext{all } (ext{x}, y) ext{ with } x_j = 1$

return new $node(GROWTREE(S_0), GROWTREE(S_1))$ end if

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What about attributes that are non-boolean?

Multi-class categorical attributes

In the examples we have seen cases with *categorical* (a.k.a. discrete) attributes, in this case we can chose to

- Do a multiway split (like in the examples), or
- Test single category against others
- Group categories into two disjoint subsets

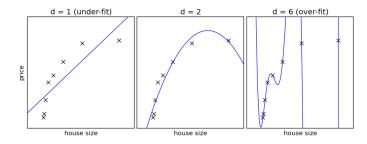
Numerical attributes

 Consider thresholds using observed values, and split accordingly

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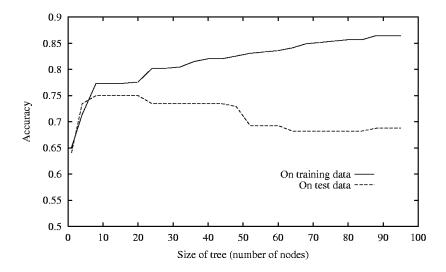
The problem of overfitting

- Define training error of tree T as the number of mistakes we make on the training set
- Define test error of tree T as the number of mistakes our model makes on examples it has not seen during training
 Overfitting happens when our model has very small training error, but very large test error



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Overfitting in decision tree learning



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Main idea: prefer smaller trees over long, complicated ones. Two strategies

Stop growing tree when split is not statistically significant

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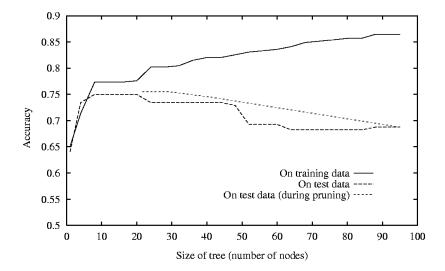
Grow full tree, and then post-prune it

Reduced-error pruning

- 1. Split data into disjoint training and validation set
- 2. Repeat until no further improvement of validation error
 - Evaluate validation error of removing each node in tree
 - Remove node that minimizes validation error the most

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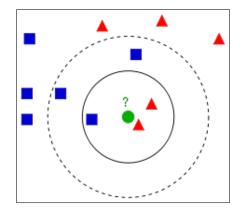
Pruning and effect on train and test error



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Nearest Neighbor

- \blacktriangleright k-NN, parameter k is number of neighbors to consider
- \blacktriangleright prediction is based on majority vote of k closest neighbors



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How to find "nearest neighbors"

Distance measures

Numeric attributes

 \blacktriangleright Euclidean, Manhattan, L^n -norm

$$L^{n}(\mathbf{x}^{1},\mathbf{x}^{2}) = \sqrt[n]{\sum_{i=1}^{dim} \left|\mathbf{x}_{i}^{1}-\mathbf{x}_{i}^{2}
ight|^{n}}$$

Normalized by range, or standard deviation

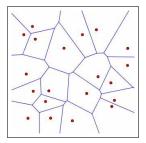
Categorical attributes

- Hamming/overlap distance
- ▶ Value Difference Measure

$$\delta(\textit{val}_i,\textit{val}_j) = \sum_{c \in \textit{classes}} \left| P(\textit{c}|\textit{val}_i) - P(\textit{c}|\textit{val}_j) \right|^n$$

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Decision boundary for 1-NN Voronoi diagram



- ▶ Let S be a training set of examples
- ► The Voronoi cell of x ∈ S is the set of points in space that are closer to x than to any other point in S
- The Region of class C is the union of Voronoi cells of points with class C

Distance-Weighted k-NN

A generalization

Idea: put more weight to examples that are close

$$\widehat{f}(\mathbf{x}') \leftarrow rac{\sum_{i=1}^k w_i f(\mathbf{x}^i)}{\sum_{i=1}^k w_i}$$

where

$$w_i \stackrel{ ext{def}}{=} rac{1}{d(\mathrm{x}',\mathrm{x}^i)^2}$$

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Avoiding overfitting

- \blacktriangleright Set k to appropriate value
- Remove noisy examples
 - E.g., remove x if all k nearest neighbors are of different class

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Construct and use prototypes as training examples

This is a hard question ... how would you do it?

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This is a hard question ... how would you do it?

- Typically, we need to "evaluate" classifiers, namely, how well they make predictions on unseen data
- One possibility is by splitting available data into training (70%) and test (30%) of course there are other ways
- ▶ Then, check how well different options work on the test set

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... more on this this Friday in the lab session!