### **Interval Sorting**

Conrado Martínez U. Politècnica Catalunya

#### GREYC, U. Caen, June 1st, 2010

Dedicated to Brigitte Vallée

Joint work with:



R.M. Jiménez

The problem:

Input: An array A[1..n] of n items drawn from a totally ordered domain; a set  $I = \{[\ell_t, u_t] \mid 1 \leqslant t \leqslant p\}$  of p disjoint intervals with

 $1 \leqslant \ell_1 \leqslant \mathfrak{u}_1 < \ell_2 \leqslant \mathfrak{u}_2 < \cdots < \ell_p \leqslant \mathfrak{u}_p \leqslant \mathfrak{n},$ 

Output: The array A rearranged in such a way that

- $A[\ell_t..u_t]$  contains the  $\ell_t$ th,..., $u_t$ th smallest elements of A in nondecreasing order, for all t,  $1 \leq t \leq p$
- $$\label{eq:alpha} \begin{split} & \& A[\mathfrak{u}_t+1..\ell_{t+1}-1] \text{ contains the } (\mathfrak{u}_t+1)\text{th},\\ & \ldots, \, (\ell_{t+1}-1)\text{th smallest elements of } A, \text{ for all } t, \, 0 \leqslant t \leqslant p \; (\mathfrak{u}_0=0,\,\ell_{p+1}=n+1) \end{split}$$





• Sorting:  $p = 1, I = \{[1, n]\}$ 

- Selection of the jth:  $p = 1, I = \{[j, j]\}$
- Multiple selection:  $I = \{[j_1, j_1], [j_2, j_2], \dots, [j_p, j_p]\}$
- Partial sorting: p = 1, I = {[1, m]}, m < n</li>

- Sorting:  $p = 1, I = \{[1, n]\}$
- Selection of the jth:  $p = 1, I = \{[j, j]\}$
- Multiple selection:  $I = \{[j_1, j_1], [j_2, j_2], \dots, [j_p, j_p]\}$
- Partial sorting:  $p = 1, I = \{[1, m]\}, m < n$

- Sorting:  $p = 1, I = \{[1, n]\}$
- Selection of the jth:  $p = 1, I = \{[j, j]\}$
- Multiple selection:  $I = \{[j_1, j_1], [j_2, j_2], \dots, [j_p, j_p]\}$
- Partial sorting:  $p = 1, I = \{[1, m]\}, m < n$

- Sorting:  $p = 1, I = \{[1, n]\}$
- Selection of the jth:  $p = 1, I = \{[j, j]\}$
- Multiple selection:  $I = \{[j_1, j_1], [j_2, j_2], \dots, [j_p, j_p]\}$
- Partial sorting:  $p = 1, I = \{[1, m]\}, m < n$

#### Other instances of interval sorting might be useful:

- Sort & filter:  $p = 1, I = [\beta n, (1 \beta)n], \beta < 1/2$
- Outliers:  $p = 2, I = \{[1, k], [n k + 1, n]\}$
- Sorting A in (expected) time Θ(n log n) solves the problem, but this is wasteful if m = |I<sub>1</sub>| + ... + |I<sub>p</sub>| ≪ n

#### • Other instances of interval sorting might be useful:

- Sort & filter:  $p = 1, I = [\beta n, (1 \beta)n], \beta < 1/2$
- Outliers:  $p = 2, I = \{[1, k], [n k + 1, n]\}$
- Sorting A in (expected) time  $\Theta(n \log n)$  solves the problem, but this is wasteful if  $m = |I_1| + \ldots + |I_p| \ll n$

- Other instances of interval sorting might be useful:
  - Sort & filter:  $p = 1, I = [\beta n, (1 \beta)n], \beta < 1/2$
  - Outliers:  $p = 2, I = \{[1, k], [n k + 1, n]\}$
- Sorting A in (expected) time  $\Theta(n \log n)$  solves the problem, but this is wasteful if  $m = |I_1| + \ldots + |I_p| \ll n$

- Other instances of interval sorting might be useful:
  - Sort & filter:  $p = 1, I = [\beta n, (1 \beta)n], \beta < 1/2$
  - Outliers:  $p = 2, I = \{[1, k], [n k + 1, n]\}$
- Sorting A in (expected) time  $\Theta(n \log n)$  solves the problem, but this is wasteful if  $m = |I_1| + \ldots + |I_p| \ll n$

# Chunksort: A simple divide & conquer algorithm for interval sorting

- Average performance of chunksort
- A simple lower bound for interval sorting
- Intermezzo:

- Optimal" chunksort
- Disgression: How far from optimal?

- Chunksort: A simple divide & conquer algorithm for interval sorting
- Average performance of chunksort
- A simple lower bound for interval sorting
- Intermezzo:
  - Optimal sampling strategies for quicksort
     Optimal sampling strategies for quickselect
- Optimal" chunksort
- Disgression: How far from optimal?

- Chunksort: A simple divide & conquer algorithm for interval sorting
- Average performance of chunksort
- A simple lower bound for interval sorting
  - Intermezzo:
    - Optimal sampling strategies for quicksort
       Optimal sampling strategies for quicksole
    - Optimal sampling strategies for quickselect
- Optimal" chunksort
- Disgression: How far from optimal?

- Chunksort: A simple divide & conquer algorithm for interval sorting
- Average performance of chunksort
- A simple lower bound for interval sorting
- Intermezzo:
  - Optimal sampling strategies for quicksort
  - Optimal sampling strategies for quickselect
- Optimal" chunksort
- Disgression: How far from optimal?

- Chunksort: A simple divide & conquer algorithm for interval sorting
- Average performance of chunksort
- A simple lower bound for interval sorting
- Intermezzo:
  - Optimal sampling strategies for quicksort
  - Optimal sampling strategies for quickselect
- Optimal" chunksort
- Disgression: How far from optimal?

- Chunksort: A simple divide & conquer algorithm for interval sorting
- Average performance of chunksort
- A simple lower bound for interval sorting
- Intermezzo:
  - Optimal sampling strategies for quicksort
  - Optimal sampling strategies for quickselect
- Optimal" chunksort
- Disgression: How far from optimal?

- Chunksort: A simple divide & conquer algorithm for interval sorting
- Average performance of chunksort
- A simple lower bound for interval sorting
- Intermezzo:
  - Optimal sampling strategies for quicksort
  - Optimal sampling strategies for quickselect
- Optimal" chunksort
- Disgression: How far from optimal?

- Chunksort: A simple divide & conquer algorithm for interval sorting
- Average performance of chunksort
- A simple lower bound for interval sorting
- Intermezzo:
  - Optimal sampling strategies for quicksort
  - Optimal sampling strategies for quickselect
- Optimal" chunksort
- Disgression: How far from optimal?

# Chunksort: A simple divide & conquer algorithm for interval sorting

- 2 Average cost of chunksort
- 3 A simple lower bound for interval sorting
- Intermezzo
- 5 "Optimal" chunksort
- Disgression: How far from optimal?

## Conclusions

```
procedure CHUNKSORT(A, i, j, I, r, s)
    if i \ge j then return \triangleright A contains one or no
elements
    if r \leq s then
         pv \leftarrow SELECTPIVOT(A, i, j)
         PARTITION(A, pv, i, j, k)
         t \leftarrow \text{LOCATE}(I, r, s, k)
\triangleright Locate the value t such that \ell_t \leq k \leq u_t with
\mathbf{I}_{\mathrm{t}} = [\ell_{\mathrm{t}}, \mathbf{u}_{\mathrm{t}}],
\triangleright or u_t < k < \ell_{t+1}
         if u_t < k then \triangleright k falls in the tth gap
              CHUNKSORT(A, i, k - 1, I, r, t)
              CHUNKSORT(A, k + 1, j, I, t + 1, s)
         else \triangleright k falls in the tth interval
              CHUNKSORT(A, i, k - 1, I, r, t)
              CHUNKSORT(A, k + 1, j, I, t, s)
```









#### Example (Using chunksort to sort)

• 
$$p = 1, I_1 = [1, n]$$

 $\bullet \ 1 \leqslant k \leqslant n \implies \ell_1 \leqslant k \leqslant u_1 \implies r = s = t = 1$ 

```
procedure CHUNKSORT(A, i, j, I, r, s)
```

```
if u_t < k then \triangleright k falls in the tth gap

CHUNKSORT(A, i, k - 1, I, r, t)

CHUNKSORT(A, k + 1, j, I, t + 1, s)

else \triangleright k falls in the tth interval

CHUNKSORT(A, i, k - 1, I, r, t)

CHUNKSORT(A, k + 1, j, I, t, s)
```

• 
$$p = 1, I_1 = [m, m]$$

• 
$$\mathfrak{m} < k \implies \mathfrak{t} = 1, \mathfrak{u}_1 < k$$

procedure CHUNKSORT(A, i, j, I, r, s)

```
\label{eq:characteristic} \begin{array}{l} \text{if } u_t < k \text{ then } \triangleright \text{ } k \text{ falls in the tth gap} \\ \text{CHUNKSORT}(A, i, k-1, I, r, t) \\ \text{CHUNKSORT}(A, k+1, j, I, t+1, s) \\ \text{else } \triangleright \text{ } k \text{ falls in the tth interval} \\ \text{CHUNKSORT}(A, i, k-1, I, r, t) \\ \text{CHUNKSORT}(A, k+1, j, I, t, s) \end{array}
```

• 
$$p = 1, I_1 = [m, m]$$

• 
$$\mathfrak{m} < k \implies \mathfrak{t} = 1, \mathfrak{u}_1 < k$$

procedure CHUNKSORT(A, i, j, I, r, s)

```
\label{eq:constraint} \begin{array}{l} \text{if } u_t < k \text{ then } \triangleright \text{ } k \text{ falls in the tth gap} \\ \text{CHUNKSORT}(A, i, k-1, I, r, t) \end{array}
```

CHUNKSORT(A, k + 1, j, I, t + 1, s)

else  $\triangleright$  k falls in the tth interval

CHUNKSORT(A, i, k - 1, I, r, t)CHUNKSORT(A, k + 1, j, I, t, s)

• 
$$p = 1, I_1 = [m, m]$$

• 
$$k < m \implies t = 0, u_0 < k < \ell_1$$

```
procedure CHUNKSORT(A, i, j, I, r, s)
```

```
\label{eq:chunksort} \begin{array}{l} \text{if } u_t < k \text{ then } \triangleright \text{ } k \text{ falls in the tth gap} \\ & \text{CHUNKSORT}(A, i, k-1, I, r, t) \\ & \text{CHUNKSORT}(A, k+1, j, I, t+1, s) \\ & \text{else } \triangleright \text{ } k \text{ falls in the tth interval} \\ & \text{CHUNKSORT}(A, i, k-1, I, r, t) \\ & \text{CHUNKSORT}(A, k+1, j, I, t, s) \end{array}
```

• 
$$p = 1, I_1 = [m, m]$$

• 
$$k < m \implies t = 0, u_0 < k < \ell_1$$

```
procedure CHUNKSORT(A, i, j, I, r, s)
```

```
if u_t < k then \triangleright k falls in the tth gap

CHUNKSORT(A, i, k - 1, I, r, t)

CHUNKSORT(A, k + 1, j, I, t + 1, s)

else \triangleright k falls in the tth interval

CHUNKSORT(A, i, k - 1, I, r, t)

CHUNKSORT(A, k + 1, j, I, t, s)
```

Example (Using chunksort for partial sorting)

• 
$$p = 1, I_1 = [1, m]$$

 $\bullet \ 1 \leqslant k \leqslant m \implies \ell_1 \leqslant k \leqslant u_1 \implies r = s = t = 1, k \leqslant u_1$ 

```
procedure CHUNKSORT(A, i, j, I, r, s)
```

```
if u_t < k then \triangleright k falls in the tth gap

CHUNKSORT(A, i, k - 1, I, r, t)

CHUNKSORT(A, k + 1, j, I, t + 1, s)

else \triangleright k falls in the tth interval

CHUNKSORT(A, i, k - 1, I, r, t)

CHUNKSORT(A, k + 1, j, I, t, s)
```

Example (Using chunksort for partial sorting)

• 
$$p = 1, I_1 = [1, m]$$

 $\bullet \ \mathfrak{m} < k \leqslant \mathfrak{n} \implies \mathfrak{u}_1 < k \leqslant \ell_2 \implies r = s = t = 1, \mathfrak{u}_1 < k$ 

**procedure** CHUNKSORT(A, i, j, I, r, s)

```
\label{eq:chunksort} \begin{array}{l} \text{if } u_t < k \text{ then } \triangleright \text{ k falls in the tth gap} \\ \text{CHUNKSORT}(A, i, k-1, I, r, t) \\ \text{CHUNKSORT}(A, k+1, j, I, t+1, s) \\ \text{else } \triangleright \text{ k falls in the tth interval} \\ \text{CHUNKSORT}(A, i, k-1, I, r, s) \\ \text{CHUNKSORT}(A, k+1, j, I, t, s) \\ \end{array}
```

Example (Using chunksort for partial sorting)

• 
$$p = 1, I_1 = [1, m]$$

 $\bullet \ \mathfrak{m} < k \leqslant \mathfrak{n} \implies \mathfrak{u}_1 < k \leqslant \ell_2 \implies r = s = t = 1, \mathfrak{u}_1 < k$ 

procedure CHUNKSORT(A, i, j, I, r, s)

if  $u_t < k$  then  $\triangleright k$  falls in the tth gap CHUNKSORT(A, i, k - 1, I, r, t)CHUNKSORT(A, k + 1, j, I, t + 1, s)else  $\triangleright k$  falls in the tth interval CHUNKSORT(A, i, k - 1, I, r, s)

CHUNKSORT(A, k + 1, j, I, t, s)

Chunksort: A simple divide & conquer algorithm for interval sorting

- 2 Average cost of chunksort
  - 3 A simple lower bound for interval sorting
- Intermezzo
- 5 "Optimal" chunksort
- Disgression: How far from optimal?

### Conclusions



C.A.R. Hoare

- Probability that the selected pivot is the k-th of n elements:  $\pi_{n,k}$ ; for the basic variants here  $\pi_{n,k} = 1/n$
- Average number of comparisons Q<sub>n</sub> to sort n elements:

$$Q_n = n - 1 + \sum_{k=1}^n \pi_{n,k} \cdot (Q_{k-1} + Q_{n-k})$$

 Average number of comparisons Q<sub>n</sub> to sort n elements (Hoare, 1962):

$$\begin{split} Q_n &= 2(n+1)H_n - 4n = 2n\ln n + (2\gamma - 4)n + 2\ln n + O(1) \\ \text{where } H_n &= \sum_{1\leqslant k\leqslant n} 1/k = \ln n + O(1) \text{ is the $n$-th} \\ \text{harmonic number.} \end{split}$$


#### D.E. Knuth

 Average number of comparisons C<sub>n,m</sub> to select the m-th out of n:

$$C_{n,m} = n - 1 + \sum_{k=m+1}^{n} \pi_{n,k} \cdot C_{k-1,m} + \sum_{k=1}^{m-1} \pi_{n,k} \cdot C_{n-k,m-k}$$

 Average number of comparisons C<sub>n,m</sub> to select the m-th out of n elements (Knuth, 1971):

$$\begin{split} C_{n,m} = & 2 \big( n + 3 + (n+1) H_n \\ & - (n+3-m) H_{n+1-m} - (m+2) H_m \big) \end{split}$$

## Partial quicksort: Average cost

 Average number of comparisons P<sub>n,m</sub> to sort the m smallest elements out of n:

$$P_{n,m} = n - 1 + \sum_{k=m+1}^{n} \pi_{n,k} \cdot P_{k-1,m} + \sum_{k=1}^{m} \pi_{n,k} \cdot (P_{k-1,k-1} + P_{n-k,m-k})$$

• The solution is (Martínez, 2004):

$$P_{n,m} = 2n + 2(n+1)H_n - 2(n+3-m)H_{n+1-m} - 6m + 6$$

#### • $I_t = [\ell_t, u_t]$ : the tth interval, $1 \leqslant t \leqslant p$

- $\bar{I}_t = [\mathfrak{u}_t + 1..\ell_{t+1} 1]$ : the tth gap,  $0 \leqslant t \leqslant p$
- $\mathfrak{m}_t = |I_t| = \mathfrak{u}_t \ell_t + 1$ : size of the tth interval
- $\overline{\mathfrak{m}}_t = |\overline{I}_t| = \ell_{t+1} \mathfrak{u}_t 1$ : size of the tth gap
- $m = m_1 + \ldots + m_p$ : # of elements to be sorted
- $\overline{\mathfrak{m}} = \overline{\mathfrak{m}}_0 + \ldots + \overline{\mathfrak{m}}_p = \mathfrak{n} \mathfrak{m}$ : # of elements not sorted

- $I_t = [\ell_t, u_t]$ : the tth interval,  $1 \leqslant t \leqslant p$
- $\overline{I}_t = [\mathfrak{u}_t + 1..\ell_{t+1} 1]$  : the tth gap, 0  $\leqslant t \leqslant p$
- $\mathfrak{m}_t = |I_t| = \mathfrak{u}_t \ell_t + 1$ : size of the tth interval
- $\overline{\mathfrak{m}}_t = |\overline{I}_t| = \ell_{t+1} \mathfrak{u}_t 1$ : size of the tth gap
- $m = m_1 + \ldots + m_p$ : # of elements to be sorted
- $\overline{\mathfrak{m}} = \overline{\mathfrak{m}}_0 + \ldots + \overline{\mathfrak{m}}_p = \mathfrak{n} \mathfrak{m}$ : # of elements not sorted

- $I_t = [\ell_t, u_t]$ : the tth interval,  $1 \leqslant t \leqslant p$
- $\bar{I}_t = [\mathfrak{u}_t + 1..\ell_{t+1} 1]$ : the tth gap,  $0 \leqslant t \leqslant p$
- $m_t = |I_t| = u_t \ell_t + 1$ : size of the tth interval
- $\overline{\mathfrak{m}}_t = |\overline{I}_t| = \ell_{t+1} \mathfrak{u}_t 1$ : size of the tth gap
- $m = m_1 + \ldots + m_p$ : # of elements to be sorted
- $\overline{m} = \overline{m}_0 + \ldots + \overline{m}_p = n m$ : # of elements not sorted

- $I_t = [\ell_t, u_t]$ : the tth interval,  $1 \le t \le p$ •  $\overline{I}_t = [u_t + 1 .. \ell_{t+1} - 1]$ : the tth gap,  $0 \le t \le p$ •  $m_t = |I_t| = u_t - \ell_t + 1$ : size of the tth interval
- $\mathbf{e}_{\mathbf{r}} = |\mathbf{r}_{\mathbf{r}}| = u_{\mathbf{r}} \quad \mathbf{e}_{\mathbf{r}} + \mathbf{r} \quad \mathbf{b}_{\mathbf{r}} = \mathbf{e}_{\mathbf{r}} + \mathbf{e}_{\mathbf{$
- $\overline{\mathfrak{m}}_t = |\overline{I}_t| = \ell_{t+1} \mathfrak{u}_t 1$ : size of the tth gap
- $m = m_1 + \ldots + m_p$ : # of elements to be sorted
- $\overline{m} = \overline{m}_0 + \ldots + \overline{m}_p = n m$ : # of elements not sorted

•  $I_t = [\ell_t, u_t]$ : the tth interval,  $1 \le t \le p$ •  $\overline{I}_t = [u_t + 1..\ell_{t+1} - 1]$ : the tth gap,  $0 \le t \le p$ •  $m_t = |I_t| = u_t - \ell_t + 1$ : size of the tth interval •  $\overline{m}_t = |\overline{I}_t| = \ell_{t+1} - u_t - 1$ : size of the tth gap •  $m = m_1 + \ldots + m_p$ : # of elements to be sorted •  $\overline{m} = \overline{m}_0 + \ldots + \overline{m}_p = n - m$ : # of elements not sorted

• 
$$I_t = [\ell_t, u_t]$$
: the tth interval,  $1 \le t \le p$   
•  $\overline{I}_t = [u_t + 1..\ell_{t+1} - 1]$ : the tth gap,  $0 \le t \le p$   
•  $m_t = |I_t| = u_t - \ell_t + 1$ : size of the tth interval  
•  $\overline{m}_t = |\overline{I}_t| = \ell_{t+1} - u_t - 1$ : size of the tth gap  
•  $m = m_1 + \ldots + m_p$ : # of elements to be sorted  
•  $\overline{m} = \overline{m}_0 + \ldots + \overline{m}_p = n - m$ : # of elements not sorted

#### • We only count element comparisons

- Each partitioning stage needs n 1 comparisons of the pivot with all the other elements
- We assume that pivots are chosen at random  $(\pi_{n,k} = 1/n)$
- C<sub>n;[I<sub>r</sub>,...,I<sub>s</sub>]</sub> = the average number of comparisons needed to do interval sort on n elements for the given set of intervals {I<sub>r</sub>,..., I<sub>s</sub>}

- We only count element comparisons
- Each partitioning stage needs n 1 comparisons of the pivot with all the other elements
- We assume that pivots are chosen at random  $(\pi_{n,k} = 1/n)$
- C<sub>n;[I<sub>r</sub>,...,I<sub>s</sub>]</sub> = the average number of comparisons needed to do interval sort on n elements for the given set of intervals {I<sub>r</sub>,..., I<sub>s</sub>}

- We only count element comparisons
- Each partitioning stage needs n 1 comparisons of the pivot with all the other elements
- We assume that pivots are chosen at random  $(\pi_{n,k} = 1/n)$
- C<sub>n;{Ir,...,Is</sub>} = the average number of comparisons needed to do interval sort on n elements for the given set of intervals {Ir,...,Is}

- We only count element comparisons
- Each partitioning stage needs n 1 comparisons of the pivot with all the other elements
- We assume that pivots are chosen at random  $(\pi_{n,k} = 1/n)$
- $C_{n;\{I_r,...,I_s\}}$  = the average number of comparisons needed to do interval sort on n elements for the given set of intervals  $\{I_r, \ldots, I_s\}$

$$\begin{split} C_{n;\{I_{r},...,I_{s}\}} &= n - 1 + \sum_{t=r-1}^{s} \sum_{k \in \overline{I}_{t}} \pi_{n,k} \big( C_{k-1;\{I_{r},...,I_{t}\}} + C_{n-k;\{I_{t+1},...,I_{s}\}} \big) \\ &+ \sum_{t=r}^{s} \sum_{k \in I_{t}} \pi_{n,k} \big( C_{k-1;\{I_{r},...,I_{t}\}} + C_{n-k;\{I_{t},...,I_{s}\}} \big), \end{split}$$

- We can solve this problem "iteratively", using generating functions
- First we have p = 1 and  $I_1 = [i, j]$  and we translate the recurrence for  $C_{n;\{[i,j]\}}$  into a functional equation for

$$C(z; x, y) = \sum_{n \ge 0} \sum_{1 \leqslant i \leqslant j \leqslant n} C_{n; \{[i,j]\}} z^n x^i y^j,$$

which is actually a first-order linear differential equation

- We can solve this problem "iteratively", using generating functions
- First we have p = 1 and  $I_1 = [i, j]$  and we translate the recurrence for  $C_{n;\{[i,j]\}}$  into a functional equation for

$$C(z; x, y) = \sum_{n \ge 0} \sum_{1 \leqslant i \leqslant j \leqslant n} C_{n; \{[i,j]\}} z^n x^i y^j,$$

which is actually a first-order linear differential equation

• Then you can do a similar thing for p = 2, by introducing

$$C(z; x_1, y_1, x_2, y_2) = \sum_{n \ge 0} \sum_{1 \leqslant i \leqslant j \leqslant i' \leqslant j' \leqslant n} C_{n; \{[i,j], [i',j']\}} z^n x_1^i y_1^j x_2^{i'} y_2^j$$

which satisfies a similar ODE involving  $C(z;\boldsymbol{x}_r,\boldsymbol{y}_r)$ 

- A pattern emerges here, so that one can obtain a general form for the ODE satisfied by C(z; x<sub>1</sub>, y<sub>1</sub>,..., x<sub>p</sub>, y<sub>p</sub>)
- Solve and extract the coefficients

• Then you can do a similar thing for p = 2, by introducing

$$C(z; x_1, y_1, x_2, y_2) = \sum_{n \ge 0} \sum_{1 \le i \le j \le i' \le j' \le n} C_{n; \{[i,j], [i',j']\}} z^n x_1^i y_1^j x_2^{i'} y_2^j$$

which satisfies a similar ODE involving  $C(z; x_r, y_r)$ 

- A pattern emerges here, so that one can obtain a general form for the ODE satisfied by C(z; x<sub>1</sub>, y<sub>1</sub>,..., x<sub>p</sub>, y<sub>p</sub>)
- Solve and extract the coefficients

• Then you can do a similar thing for p = 2, by introducing

$$C(z; x_1, y_1, x_2, y_2) = \sum_{n \ge 0} \sum_{1 \le i \le j \le i' \le j' \le n} C_{n; \{[i,j], [i',j']\}} z^n x_1^i y_1^j x_2^{i'} y_2^j$$

which satisfies a similar ODE involving  $C(z; x_r, y_r)$ 

- A pattern emerges here, so that one can obtain a general form for the ODE satisfied by C(z; x<sub>1</sub>, y<sub>1</sub>,..., x<sub>p</sub>, y<sub>p</sub>)
- Solve and extract the coefficients

We guessed the solution from the known solutions for quicksort, quickselect, partial quicksort and multiple quickselect, some trial-and-error, and finally proved it by induction...

#### Theorem

The average number of element comparisons  $C_n := C_{n;\{I_1,...,I_p\}}$ needed by chunksort given the intervals  $\{I_1, \ldots, I_p\}$  is

$$\begin{split} C_n &= 2n + u_p - \ell_1 + 2(n+1)H_n - 7m - 2 + 15p \\ &- 2(\ell_1 + 2)H_{\ell_1} - 2(n+3 - u_p)H_{n+1 - u_p} \\ &- 2\sum_{k=1}^{p-1}(\overline{m}_k + 5)H_{\overline{m}_k + 2}, \end{split}$$

Chunksort: A simple divide & conquer algorithm for interval sorting

- 2 Average cost of chunksort
- A simple lower bound for interval sorting
  - Intermezzo
- 5 "Optimal" chunksort
- 6 Disgression: How far from optimal?

#### Conclusions

- Λ(n, m, m) = minimum # of comparisons needed on average to solve interval sorting of intervals with sizes m = (m<sub>1</sub>,..., m<sub>p</sub>) and gaps m = (m<sub>0</sub>,..., m<sub>p</sub>)
- The two vectors **m**, **m** and the value n univocally determining the interval sorting instance
- Suppose we perform an optimal interval sort of the array of n elements, then we sort optimally the gaps; hence

$$\Lambda(n, \boldsymbol{m}, \overline{\boldsymbol{m}}) + \sum_{t=0}^p \text{log}_2(\overline{\boldsymbol{m}}_t!) \geqslant \text{log}_2(n!)$$

- Λ(n, m, m) = minimum # of comparisons needed on average to solve interval sorting of intervals with sizes m = (m<sub>1</sub>,..., m<sub>p</sub>) and gaps m = (m<sub>0</sub>,..., m<sub>p</sub>)
- The two vectors **m**, **m** and the value n univocally determining the interval sorting instance
- Suppose we perform an optimal interval sort of the array of n elements, then we sort optimally the gaps; hence

$$\Lambda(n, \boldsymbol{m}, \boldsymbol{\overline{m}}) + \sum_{t=0}^{p} \log_{2}(\boldsymbol{\overline{m}}_{t}!) \geqslant \log_{2}(n!)$$

- Λ(n, m, m) = minimum # of comparisons needed on average to solve interval sorting of intervals with sizes m = (m<sub>1</sub>,..., m<sub>p</sub>) and gaps m = (m<sub>0</sub>,..., m<sub>p</sub>)
- The two vectors **m**, **m** and the value n univocally determining the interval sorting instance
- Suppose we perform an optimal interval sort of the array of n elements, then we sort optimally the gaps; hence

$$\Lambda(n, \boldsymbol{m}, \overline{\boldsymbol{m}}) + \sum_{t=0}^p \text{log}_2(\overline{\boldsymbol{m}}_t!) \geqslant \text{log}_2(n!)$$

#### Lemma

$$\begin{split} \Lambda(n, \boldsymbol{m}, \overline{\boldsymbol{m}}) & \geqslant \sum_{t=1}^{p} m_t \log_2 m_t \\ & + n \mathcal{H}\left(\{\overline{m}_0/n, m_1/n, \overline{m}_1/n, \dots, m_p/n, \overline{m}_p/n\}\right) \\ & - m \log_2 e + o(n) \end{split}$$

with  $\mathcal{H}(\{q_t\}) = -\sum_t q_t \log_2 q_t$  denoting the entropy of the discrete probability distribution  $\{q_t\}$  and  $m = m_1 + \ldots + m_p$ .

Chunksort: A simple divide & conquer algorithm for interval sorting

- 2 Average cost of chunksort
  - A simple lower bound for interval sorting

Intermezzo

- 5 "Optimal" chunksort
- 6 Disgression: How far from optimal?

## 7 Conclusions



M. H. van Emden

- Using the median of a small sample as the pivot of each recursive call of quicksort improves the average cost of quicksort (Singleton's median-of-3, 1969)
- Van Emden (1970) and Hennequin (1989) have studied the performance of quicksort with median-of-(2t + 1) showing an steady improvement of performance

$$C_n^{(t)} = c_t n \log_2 n,$$
  $c_0 = 2 \ln 2 = 1.386, c_1 = 1.188, \dots, c_{\infty} = 100$ 



M. H. van Emden

- Using the median of a small sample as the pivot of each recursive call of quicksort improves the average cost of quicksort (Singleton's median-of-3, 1969)
- Van Emden (1970) and Hennequin (1989) have studied the performance of quicksort with median-of-(2t + 1) showing an steady improvement of performance

$$C_n^{(t)} = c_t n \log_2 n, \qquad c_0 = 2 \ln 2 = 1.386, c_1 = 1.188, \dots, c_\infty = 1$$







C. C. McGeoch S. Roura J.D. Tygar

- McGeoch and Tygar (1995) considered using the median of a variable-size sample for the first round, then fixed size samples on subsequent calls
- Martínez and Roura (2001) studied the use of variable-size sampling for quicksort and quickselect, showing that optimal expected performance can be achieved







C. C. McGeoch S. Roura J.D. Tygar

- McGeoch and Tygar (1995) considered using the median of a variable-size sample for the first round, then fixed size samples on subsequent calls
- Martínez and Roura (2001) studied the use of variable-size sampling for quicksort and quickselect, showing that optimal expected performance can be achieved

#### Theorem (Martínez, Roura, 2001)

The expected performance of quicksort using as pivots the median of samples of size s = s(n), such that  $s \to \infty$  and  $s/n \to 0$  as  $n \to \infty$  is

 $n \log_2 n + \textit{lower order terms}$ 

# **Optimal quicksort**



- The lower order terms are minimized by choosing samples of size  $\Theta(\sqrt{n})$
- The constant hidden in Θ(√n) depends on the (linear) time algorithm used to find the median of the samples

# **Optimal quicksort**



- The lower order terms are minimized by choosing samples of size  $\Theta(\sqrt{n})$
- The constant hidden in Θ(√n) depends on the (linear) time algorithm used to find the median of the samples

# **Optimal quickselect**







R. Grübel P. Kirschenhofer H. Prodinger

- $\bullet \mbox{ Median-of-}(2t+1)$  sampling can also be used for quickselect
- The improvements on the performance have been studied by several authors: Kirschenhofer, Prodinger, Martínez (1997), Grübel (1999), Martínez and Roura (2001)
- But ... is the median of the sample a good choice?

# **Optimal quickselect**







R. Grübel P. Kirschenhofer H. Prodinger

- $\bullet \mbox{ Median-of-}(2t+1)$  sampling can also be used for quickselect
- The improvements on the performance have been studied by several authors: Kirschenhofer, Prodinger, Martínez (1997), Grübel (1999), Martínez and Roura (2001)
- But ... is the median of the sample a good choice?

# **Optimal quickselect**







R. Grübel P. Kirschenhofer H. Prodinger

- Median-of-(2t + 1) sampling can also be used for quickselect
- The improvements on the performance have been studied by several authors: Kirschenhofer, Prodinger, Martínez (1997), Grübel (1999), Martínez and Roura (2001)
- But ... is the median of the sample a good choice?


D. N. Panario A. T. Viola

 In 2004, Martínez, Panario and Viola consider variants of quickselect where the rank r of the pivot within the sample of size s is proportional to the rank j of the sought element in the array n:

$$r\approx \frac{j}{n}\cdot s$$

• More in general, they consider all variants where r is a function of  $\alpha=j/n$ 

#### **Optimal quickselect**

For all variants

$$C_{n,j} = f(\alpha) \cdot n + o(n), \alpha = j/n,$$

for instance,  $f(\alpha)=m_0(\alpha)=2+2\mathcal{H}(\alpha)$  for standard quickselect and  $f(\alpha)=m_1(\alpha)=2+3\alpha(1-\alpha)$  for median-of-three



- Optimal expected performance can be achieve with 3 basic "ingredients:"
  - Using variable-sample sizes s = s(n) with  $s \to \infty$ ,  $s/n \to 0$
  - The rank of the pivot withis the sample must be  $r \sim \alpha \cdot s$
  - If the soundst element has rank j > n/2 take r = α ⋅ s − δ; if j < n/2 then r = α ⋅ s + δ, for some "small" δ, say δ = √s</li>
  - You want the chosen pivot to land very close to j on the correct side with high probability

- Optimal expected performance can be achieve with 3 basic "ingredients:"
  - Using variable-sample sizes s=s(n) with  $s\rightarrow\infty,\,s/n\rightarrow0$
  - The rank of the pivot withis the sample must be  $r \sim \alpha \cdot s$
  - If the soundst element has rank j > n/2 take r = α ⋅ s − δ; if j < n/2 then r = α ⋅ s + δ, for some "small" δ, say δ = √s</li>
  - You want the chosen pivot to land very close to j on the correct side with high probability

- Optimal expected performance can be achieve with 3 basic "ingredients:"
  - Using variable-sample sizes s=s(n) with  $s\rightarrow\infty,\,s/n\rightarrow0$
  - The rank of the pivot withis the sample must be  $r\sim \alpha\cdot s$
  - If the souhgt element has rank j > n/2 take  $r = \alpha \cdot s \delta$ ; if j < n/2 then  $r = \alpha \cdot s + \delta$ , for some "small"  $\delta$ , say  $\delta = \sqrt{s}$
  - You want the chosen pivot to land very close to j on the correct side with high probability

- Optimal expected performance can be achieve with 3 basic "ingredients:"
  - Using variable-sample sizes s=s(n) with  $s\rightarrow\infty,\,s/n\rightarrow0$
  - The rank of the pivot withis the sample must be  $r\sim \alpha\cdot s$
  - If the soundst element has rank j > n/2 take r = α ⋅ s − δ; if j < n/2 then r = α ⋅ s + δ, for some "small" δ, say δ = √s</li>
  - You want the chosen pivot to land very close to j on the correct side with high probability

- Optimal expected performance can be achieve with 3 basic "ingredients:"
  - Using variable-sample sizes s=s(n) with  $s\rightarrow\infty,\,s/n\rightarrow0$
  - The rank of the pivot withis the sample must be  $r\sim \alpha\cdot s$
  - If the souhgt element has rank j > n/2 take  $r = \alpha \cdot s \delta$ ; if j < n/2 then  $r = \alpha \cdot s + \delta$ , for some "small"  $\delta$ , say  $\delta = \sqrt{s}$
  - You want the chosen pivot to land very close to j on the correct side with high probability

#### Theorem (Martínez, Panario, Viola, 2004)

Any variant of quickselect using biased proportion-from-s with variable-size sampling has

$$f(\alpha) = 1 + \min(\alpha, 1 - \alpha)$$

Thus  $C_{n,j} \sim n + min(j, n - j) + \textit{lower order terms}$ 

- Chunksort: A simple divide & conquer algorithm for interval sorting
- 2 Average cost of chunksort
- 3 A simple lower bound for interval sorting
- Intermezzo
- 5 "Optimal" chunksort
  - 6 Disgression: How far from optimal?

#### Conclusions

- Merge small gaps: replace two intervals separated by a gap of size o(n) by a single interval
- If there is only one interval to sort and it contains m = n - o(n) elements pick a pivot whose rank is close to n/2; use the median of a large (\sqrt{n}) sample
- If not, choose some endpoint  $l_r$ ,  $u_r$ , ...,  $l_s$ ,  $u_s$ , say  $\rho$ 
  - If  $\rho = r_{c}$  pick is pixel from a large sample with value proportional to  $\rho$  and biased to land to the left of  $\rho$ . If  $\rho = r_{c}$  pick is pixel from a large sample with rank proportional to  $\rho$  and biased to lead to the right of  $\rho$ .

- Merge small gaps: replace two intervals separated by a gap of size o(n) by a single interval
- If there is only one interval to sort and it contains
   m = n o(n) elements pick a pivot whose rank is close to n/2; use the median of a large (\sqrt{n}) sample
- If not, choose some endpoint l<sub>r</sub>, u<sub>r</sub>, ..., l<sub>s</sub>, u<sub>s</sub>, say ρ
   If ρ = l<sub>i</sub>, pick a pivot from a large sample with rank proportional to p and biased to land to the left of p
   If ρ = u<sub>i</sub> pick a pivot from a large sample with rank proportional to p and biased to land to the nett of p

- Merge small gaps: replace two intervals separated by a gap of size o(n) by a single interval
- If there is only one interval to sort and it contains
   m = n o(n) elements pick a pivot whose rank is close to n/2; use the median of a large (\sqrt{n}) sample
- **③** If not, choose some endpoint  $\ell_r$ ,  $u_r$ , ...,  $\ell_s$ ,  $u_s$ , say  $\rho$ 
  - If  $\rho = \ell_t$ , pick a pivot from a large sample with rank proportional to  $\rho$  and biased to land to the left of  $\rho$
  - If  $\rho = u_t$ , pick a pivot from a large sample with rank proportional to  $\rho$  and biased to land to the right of  $\rho$

- Merge small gaps: replace two intervals separated by a gap of size o(n) by a single interval
- If there is only one interval to sort and it contains
   m = n o(n) elements pick a pivot whose rank is close to n/2; use the median of a large (\sqrt{n}) sample
- **3** If not, choose some endpoint  $\ell_r$ ,  $u_r$ , ...,  $\ell_s$ ,  $u_s$ , say  $\rho$ 
  - If  $\rho = \ell_t$ , pick a pivot from a large sample with rank proportional to  $\rho$  and biased to land to the left of  $\rho$
  - If  $\rho = u_t$ , pick a pivot from a large sample with rank proportional to  $\rho$  and biased to land to the right of  $\rho$

- Merge small gaps: replace two intervals separated by a gap of size o(n) by a single interval
- If there is only one interval to sort and it contains
   m = n o(n) elements pick a pivot whose rank is close to n/2; use the median of a large (\sqrt{n}) sample
- If not, choose some endpoint  $\ell_r$ ,  $u_r$ , ...,  $\ell_s$ ,  $u_s$ , say  $\rho$ 
  - If  $\rho = \ell_t$ , pick a pivot from a large sample with rank proportional to  $\rho$  and biased to land to the left of  $\rho$
  - If  $\rho = u_t$ , pick a pivot from a large sample with rank proportional to  $\rho$  and biased to land to the right of  $\rho$













- The problem is thus to find the optimal order programming
- Given the collection of endpoints ρ<sub>i</sub> = u<sub>r-1</sub>, ρ<sub>i+1</sub> = l<sub>r</sub>, ..., ρ<sub>j-1</sub> = u<sub>s</sub>, ρ<sub>j</sub> = l<sub>s+1</sub> find the endpoint ρ<sub>k</sub> such that minimizes c(i, j):

$$c(i,j) = \rho_j - \rho_i + \min_{i < k < j} (c(i,k) + c(k,j))$$

- The problem is thus to find the optimal order programming
- Given the collection of endpoints  $\rho_i = u_{r-1}$ ,  $\rho_{i+1} = \ell_r$ , ...,  $\rho_{j-1} = u_s$ ,  $\rho_j = \ell_{s+1}$  find the endpoint  $\rho_k$  such that minimizes c(i, j):

$$c(i,j) = \rho_j - \rho_i + \min_{i < k < j} (c(i,k) + c(k,j))$$



F.F. Yao

- The dynamic programming to find the optimal order to "cut the bar" has cost O(p<sup>3</sup>); it is almost analogous to building an optimal search tree where the weights of the leaves are the sizes of the intervals
- The efficiency of the algorithm can be greatly improved to O(p<sup>2</sup>) using Knuth-Yao's technique

- We can use some heuristic to find a near-optimal solution to the "cut the bar" problem with cost  $O(p \log p)$
- For instance, at each step, we can choose the endpoint l<sub>k</sub> or u<sub>k</sub> which is closer to (ρ<sub>j</sub> ρ<sub>i</sub>)/2; some care must be taken if we have ties, e.g., if l<sub>k</sub> = u<sub>k</sub>
- The analysis of the heuristic provides a useful upper bound on *c*(0, 2p + 1), the optimal cost of the "cut the bar" phase
- The total cost of chunksort becomes

$$\begin{split} \sum_{i=1}^{p} m_t \log_2 m_t + c(0, 2p + 1) + O(p\sqrt{n}) \\ \leqslant \sum_{t=1}^{p} m_t \log_2 m_t + n \cdot H + n + \text{lower order terms} \end{split}$$

- We can use some heuristic to find a near-optimal solution to the "cut the bar" problem with cost O(p log p)
- For instance, at each step, we can choose the endpoint ℓ<sub>k</sub> or u<sub>k</sub> which is closer to (ρ<sub>j</sub> ρ<sub>i</sub>)/2; some care must be taken if we have ties, e.g., if ℓ<sub>k</sub> = u<sub>k</sub>
- The analysis of the heuristic provides a useful upper bound on c(0, 2p + 1), the optimal cost of the "cut the bar" phase
- The total cost of chunksort becomes

$$\begin{split} \sum_{i=1}^{p} m_t \log_2 m_t + c(0, 2p+1) + O(p\sqrt{n}) \\ \leqslant \sum_{t=1}^{p} m_t \log_2 m_t + n \cdot H + n + \text{lower order terms} \end{split}$$

- We can use some heuristic to find a near-optimal solution to the "cut the bar" problem with cost O(p log p)
- For instance, at each step, we can choose the endpoint ℓ<sub>k</sub> or u<sub>k</sub> which is closer to (ρ<sub>j</sub> ρ<sub>i</sub>)/2; some care must be taken if we have ties, e.g., if ℓ<sub>k</sub> = u<sub>k</sub>
- The analysis of the heuristic provides a useful upper bound on c(0, 2p + 1), the optimal cost of the "cut the bar" phase

• The total cost of chunksort becomes

$$\sum_{i=1}^{p} m_t \log_2 m_t + c(0, 2p + 1) + O(p\sqrt{n})$$
$$\leqslant \sum_{t=1}^{p} m_t \log_2 m_t + n \cdot H + n + \text{lower order terms}$$

- We can use some heuristic to find a near-optimal solution to the "cut the bar" problem with cost O(p log p)
- For instance, at each step, we can choose the endpoint ℓ<sub>k</sub> or u<sub>k</sub> which is closer to (ρ<sub>j</sub> ρ<sub>i</sub>)/2; some care must be taken if we have ties, e.g., if ℓ<sub>k</sub> = u<sub>k</sub>
- The analysis of the heuristic provides a useful upper bound on c(0, 2p + 1), the optimal cost of the "cut the bar" phase
- The total cost of chunksort becomes

$$\begin{split} \sum_{t=1}^p m_t \log_2 m_t + c(0, 2p+1) + O(p\sqrt{n}) \\ \leqslant \sum_{t=1}^p m_t \log_2 m_t + n \cdot H + n + \text{lower order terms} \end{split}$$

• Together with the lower bound for  $\Lambda$ 

$$\begin{split} \sum_{t=1}^p m_t \log_2 m_t + n \cdot H - m \log_2 e + o(n) \leqslant \Lambda(n, \boldsymbol{m}, \overline{\boldsymbol{m}}) \\ \leqslant \sum_{t=1}^p m_t \log_2 m_t + c(0, 2p+1) + O(p\sqrt{n}) \\ \leqslant \sum_{t=1}^p m_t \log_2 m_t + n \cdot H + n + \text{lower order terms.} \end{split}$$

• The lower and upper bounds differ by n + o(n) comparisons if  $p \ll \sqrt{n}$  (which indeed is the case, as we collapsed all "small" gaps!)

• Together with the lower bound for  $\Lambda$ 

$$\begin{split} \sum_{t=1}^p m_t \log_2 m_t + n \cdot H - m \log_2 e + o(n) &\leq \Lambda(n, \boldsymbol{m}, \overline{\boldsymbol{m}}) \\ &\leq \sum_{t=1}^p m_t \log_2 m_t + c(0, 2p+1) + O(p\sqrt{n}) \\ &\leq \sum_{t=1}^p m_t \log_2 m_t + n \cdot H + n + \text{lower order terms.} \end{split}$$

• The lower and upper bounds differ by n + o(n) comparisons if  $p \ll \sqrt{n}$  (which indeed is the case, as we collapsed all "small" gaps!)



K. Kaligosi K. Mehlhorn J. I. Munro P. Sanders

- Kaligosi, Mehlhorn, Munro and Sanders (2005) have considered optimal multiple selection; they use similar techniques, but they propose an algorithm which picks a pivot close to the median for each recursive stage
- This yields a solution (for multiple selection) which is off by O(n) comparisons from the optimal; our solution —which generalizes multiple selection— is off by at most n + o(n) comparisons



K. Kaligosi K. Mehlhorn J. I. Munro P. Sanders

- Kaligosi, Mehlhorn, Munro and Sanders (2005) have considered optimal multiple selection; they use similar techniques, but they propose an algorithm which picks a pivot close to the median for each recursive stage
- This yields a solution (for multiple selection) which is off by O(n) comparisons from the optimal; our solution —which generalizes multiple selection— is off by at most n + o(n) comparisons

- Chunksort: A simple divide & conquer algorithm for interval sorting
- 2 Average cost of chunksort
- 3 A simple lower bound for interval sorting
- Intermezzo
- 5 "Optimal" chunksort
- Disgression: How far from optimal?

#### 7 Conclusions

 $\textcircled{\ }$  The lower bound for  $\Lambda(n,m,\overline{m})$  is not tight, for instance, for selection

$$\begin{split} \Lambda(n, \langle 1 \rangle, \langle j-1, n-j \rangle) &= n + \min(j-1, n-j) + l.o.t. &\leftarrow \text{ on avg!} \\ &\gg n \mathcal{H}\left(\{(j-1)/n, 1/n, (n-j)/n\}\right) + l.o.t. \end{split}$$

The upper bound corresponds to the heuristic for "cutting the bar", and isn't tight either

 The lower bound for  $\Lambda(n,m,\overline{m})$  is not tight, for instance, for selection

$$\begin{split} \Lambda(n, \langle 1 \rangle, \langle j-1, n-j \rangle) &= n + \min(j-1, n-j) + \text{l.o.t.} &\leftarrow \text{ on avg!} \\ & \gg n \mathcal{H}\left(\{(j-1)/n, 1/n, (n-j)/n\}\right) + \text{l.o.t.} \end{split}$$

The upper bound corresponds to the heuristic for "cutting the bar", and isn't tight either

- The algorithm that we propose optimally solves sorting and selection
- We conjecture that it is optimal up to o(n) comparisons for all interval sort instances, not just sorting and selection

- The algorithm that we propose optimally solves sorting and selection
- We conjecture that it is optimal up to o(n) comparisons for all interval sort instances, not just sorting and selection
- Chunksort: A simple divide & conquer algorithm for interval sorting
- 2 Average cost of chunksort
- 3 A simple lower bound for interval sorting
- Intermezzo
- 5 "Optimal" chunksort
- 6 Disgression: How far from optimal?

## Conclusions

- Interval sort's main interest is that it smoothly generalizes several fundamental problems: sorting, selection, multiple selection and partial sorting
- Chunksort (its basic variant) is a simple and elegant algorithm in the spirit of quicksort; its average performance is  $\leq 2 + 2 \ln 2 = 3.386$  times the optimal

- Interval sort's main interest is that it smoothly generalizes several fundamental problems: sorting, selection, multiple selection and partial sorting
- Chunksort (its basic variant) is a simple and elegant algorithm in the spirit of quicksort; its average performance is  $\leq 2 + 2 \ln 2 = 3.386$  times the optimal

- Carefully choosing the pivots yields near-optimal performance; we conjecture it is optimal up to o(n) comparisons
- For the choice of pivots we need to "orchestrate" two ingredients:
  - large samples and proportion-from to choose pivots landing near the places where we need them
  - dynamic programming/heuristic to find the optimal order to "cut the bar"

- Carefully choosing the pivots yields near-optimal performance; we conjecture it is optimal up to o(n) comparisons
- For the choice of pivots we need to "orchestrate" two ingredients:
  - large samples and proportion-from to choose pivots landing near the places where we need them
  - dynamic programming/heuristic to find the optimal order to "cut the bar"

- Carefully choosing the pivots yields near-optimal performance; we conjecture it is optimal up to o(n) comparisons
- For the choice of pivots we need to "orchestrate" two ingredients:
  - large samples and proportion-from to choose pivots landing near the places where we need them
  - dynamic programming/heuristic to find the optimal order to "cut the bar"

- Carefully choosing the pivots yields near-optimal performance; we conjecture it is optimal up to o(n) comparisons
- For the choice of pivots we need to "orchestrate" two ingredients:
  - large samples and proportion-from to choose pivots landing near the places where we need them
  - dynamic programming/heuristic to find the optimal order to "cut the bar"

## • There are several open problems remaining:

## Better lower bounds

- Proving the conjecture
- Other randomized or deterministic algorithms

• . . .

- There are several open problems remaining:
  - Better lower bounds
  - Proving the conjecture
  - Other randomized or deterministic algorithms
  - . . .

- There are several open problems remaining:
  - Better lower bounds
  - Proving the conjecture
  - Other randomized or deterministic algorithms

• . . .

- There are several open problems remaining:
  - Better lower bounds
  - Proving the conjecture
  - Other randomized or deterministic algorithms
  - ...

## purea icc!uMoboe

Merci beaucoup!