

# Adaptive Sampling for Quickselect



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# Introduction

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- Quickselect (Hoare, 1962) selects the  $m$ -th smallest element out of  $n$  elements

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# Introduction



- Quickselect (Hoare, 1962) selects the  $m$ -th smallest element out of  $n$  elements
- It partitions the given array around a **pivot** and continues into the appropriate subarray
- Quickselect is efficient: e.g. (Knuth, 1971)

$$\begin{aligned}C_{n,m} &= m_0(\alpha) \cdot n + o(n) = 2(1 + \mathcal{H}(\alpha)) \cdot n + o(n) \\&= (2 - 2(\alpha \ln \alpha + (1 - \alpha) \ln(1 - \alpha))) \cdot n + o(n),\end{aligned}$$

with  $0 \leq \alpha = \frac{m}{n} \leq 1$ .

# The Algorithm

```
Elem quickselect(vector<Elem>& A,
                  int m) {
    int l = 0; int u = A.size() - 1;
    int k, p;
    while (l <= u) {
        p = get_pivot(A, l, u, m);
        swap(A[p], A[l]);
        partition(A, l, u, k);
        if (m < k) u = k-1;
        else if (m > k) l = k+1;
        else return A[k];
    }
}
```

# Median-of-( $2t + 1$ )

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- Using a sample of  $s = 2t + 1$  in each iteration improves the performance and reduces the probability of worst-case

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- For median-of-3 quickselect (Kirschenhofer, Martínez, Prodinger, 1995)

$$m_1(\alpha) = 2 + 3\alpha(1 - \alpha).$$

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- For median-of-3 quickselect (Kirschenhofer, Martínez, Prodinger, 1995)

$$m_1(\alpha) = 2 + 3\alpha(1 - \alpha).$$

- For all  $\alpha$ ,  $0 \leq \alpha \leq 1$ ,  $m_0(\alpha) \leq m_1(\alpha)$ . Also,  $\bar{m}_0 = 3$  and  $\bar{m}_1 = 2.5$ .

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# Adaptive Sampling

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- Divide  $[0, 1]$  into  $\ell$  intervals with endpoints

$$0 = a_0 < a_1 < a_2 < \cdots < a_\ell = 1$$

and let  $r_k$  denote the value of  $r(\alpha)$  for  $\alpha$  in the  $k$ -th interval

# Adaptive Sampling

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- For proportion-from- $s$ :  $\ell = s$ ,  $a_k = k/s$  and  $r_k = k$

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- “Proportion-from”-like strategies:  $\ell = s$  and  $r_k = k$ , but the endpoints of the intervals  $a_k \neq k/s$

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- “Proportion-from”-like strategies:  $\ell = s$  and  $r_k = k$ , but the endpoints of the intervals  $a_k \neq k/s$
- A sampling strategy is **symmetric** if

$$r(\alpha) = s + 1 - r(1 - \alpha).$$

# The Recurrence



- Probability that the  $r$ -th element in a sample of size  $s$  is the  $j$ -th element of the  $n$  given elements:

$$\pi_{n,j}^{(s,r)} = \frac{\binom{j-1}{r-1} \binom{n-j}{s-r}}{\binom{n}{s}},$$
$$1 \leq r \leq s \leq n, \quad 1 \leq j \leq n.$$

# The Recurrence



- Average number of comparisons  $C_{n,m}$  to select the  $m$ -th out of  $n$ :

$$\begin{aligned} C_{n,m} &= n + \Theta(1) + \sum_{j=m+1}^n \pi_{n,j}^{(s,r)} \cdot C_{j-1,m} \\ &\quad + \sum_{j=1}^{m-1} \pi_{n,j}^{(s,r)} \cdot C_{n-j,m-j}. \end{aligned}$$

# A General Theorem



**Theorem 1.** Let  $f(\alpha) = \lim_{n \rightarrow \infty, m/n \rightarrow \alpha} \frac{C_{n,m}}{n}$ . Then

$$f(\alpha) = 1 + \frac{s!}{(r(\alpha) - 1)!(s - r(\alpha))!} \times \\ \left[ \int_{\alpha}^1 f\left(\frac{\alpha}{x}\right) x^{r(\alpha)} (1-x)^{s-r(\alpha)} dx + \int_0^{\alpha} f\left(\frac{\alpha-x}{1-x}\right) x^{r(\alpha)-1} (1-x)^{s+1-r(\alpha)} dx \right].$$

# Two Elementary Facts



- If  $r(\alpha)$  is symmetric then  $f(\alpha) = f(1 - \alpha)$ .

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- If  $r(\alpha)$  is symmetric then  $f(\alpha) = f(1 - \alpha)$ .
- Let  $r_0 = \lim_{\alpha \rightarrow 0} r(\alpha)$ . Then

$$\lim_{\alpha \rightarrow 0} f(\alpha) = \frac{s + 1}{s + 1 - r_0}.$$

In proportion-from strategies  $r_0 = 1$ ; hence,  
 $f(0) = 1 + 1/s$ , while for median-of- $(2t + 1)$ ,  
we have  $m_t(0) = 2$

# The General Differential Equation ..

Denote  $f_k$  the restriction of  $f(\alpha)$  to the  $k$ -th interval of  $[0, 1]$ .

**Lemma 1.** *For any adaptive sampling strategy*

$$\begin{aligned} \frac{d^{s+2}}{d\alpha^{s+2}} f_k(\alpha) &= \frac{(-1)^{s+1-r_k} \cdot s!}{\alpha^{s+1-r_k} (r_k - 1)!} \frac{d^{r_k+1}}{d\alpha^{r_k+1}} f_k(\alpha) \\ &\quad + \frac{s!}{(1 - \alpha)^{r_k} (s - r_k)!} \frac{d^{s+2-r_k}}{d\alpha^{s+2-r_k}} f_k(\alpha). \end{aligned}$$

# Two Problems and a Trick

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- Solving high-order linear differential equations

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- We do not know the initial values of the  $f_k$ 's and their derivatives

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# Two Problems and a Trick

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- Solving high-order linear differential equations
- We do not know the initial values of the  $f_k$ 's and their derivatives
- Plug the general form of the  $f_k$ 's back into the integral equation(s) and solve for the unknown constants

# Proportion-from-2



- The differential equation is

$$\frac{d^2\phi_1}{dx^2} - \frac{2}{1-x} \frac{d\phi_1}{dx} - \frac{2}{x^2}\phi_1 = 0$$

with  $\phi_1(x) = f_1''(x)$  and  $f_2(x) = f_1(1-x)$ .

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with  $\phi_1(x) = f_1''(x)$  and  $f_2(x) = f_1(1-x)$ .

- The solution is

$$f_1(x) = a \left( (x-1) \ln(1-x) + \frac{x^3}{6} + \frac{x^2}{2} - x \right) - b(1 + \mathcal{H}(x)) + cx + d.$$

# Proportion-from-2

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- Proportion-from-2 beats standard quickselect:  $f(\alpha) \leq m_0(\alpha)$
- Proportion-from-2 beats median-of-three in some regions:  $f(\alpha) \leq m_1(\alpha)$  if  $\alpha \leq 0.140\dots$  or  $\alpha \geq 0.860\dots$

# Proportion-from-2

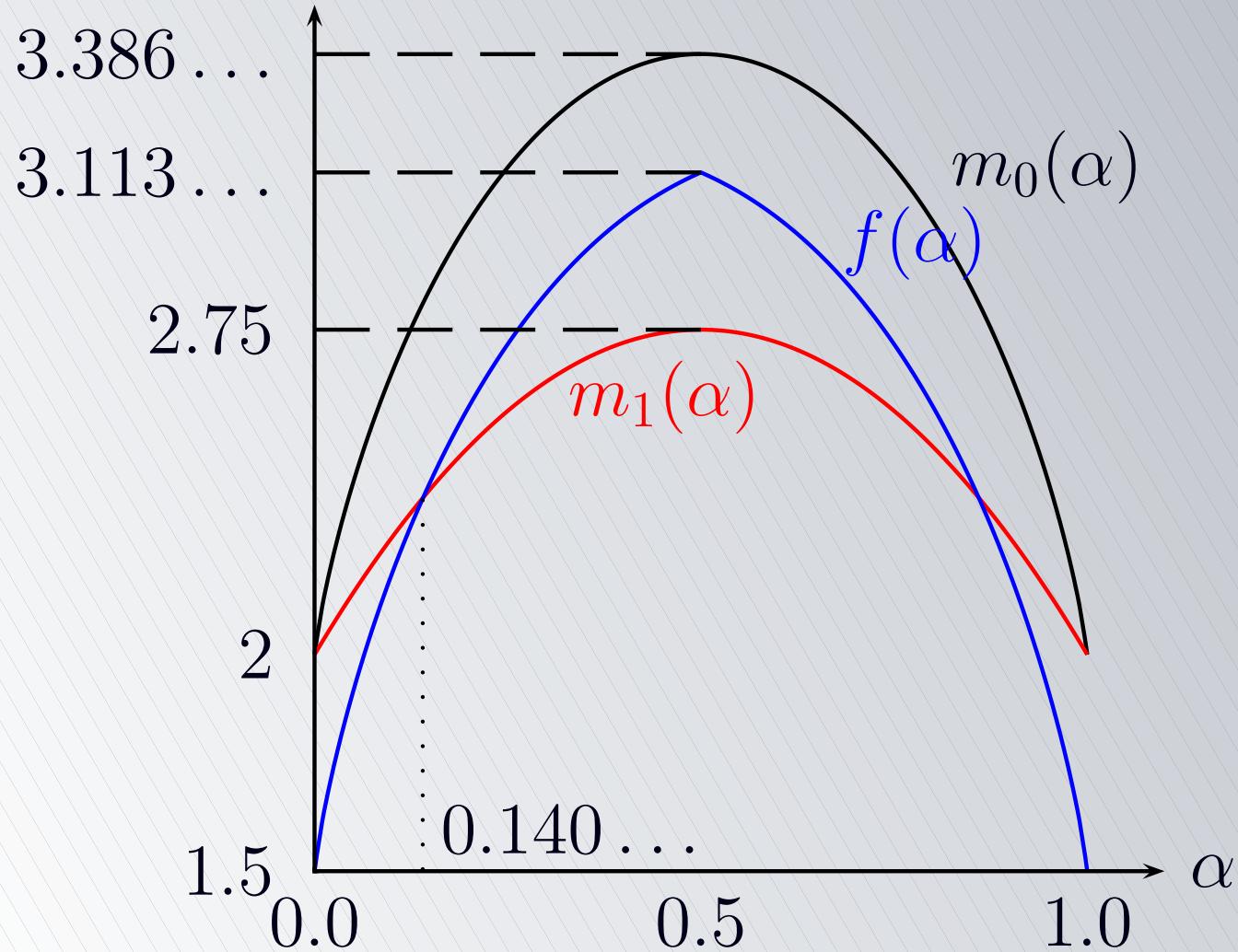


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- Proportion-from-2 beats median-of-three in some regions:  $f(\alpha) \leq m_1(\alpha)$  if  $\alpha \leq 0.140\dots$  or  $\alpha \geq 0.860\dots$
- The grand-average:  $C_n = \bar{f} \cdot n + o(n)$ , with

$$\bar{f} = 2.598\dots$$

# Proportion-from-2

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# Proportion-from-3



For proportion-from-3,

$$f_1(x) = -C_0(1 + \mathcal{H}(x)) + C_1 + C_2x + C_3K_1(x) + C_4K_2(x),$$

$$f_2(x) = -C_5(1 + \mathcal{H}(x)) + C_6x(1 - x) + C_7,$$

with

$$K_1(x) = \cos(\sqrt{2} \ln x) \cdot \sum_{n \geq 0} A_n x^{n+4} + \sin(\sqrt{2} \ln x) \cdot \sum_{n \geq 0} B_n x^{n+4},$$

$$K_2(x) = \sin(\sqrt{2} \ln x) \cdot \sum_{n \geq 0} A_n x^{n+4} - \cos(\sqrt{2} \ln x) \cdot \sum_{n \geq 0} B_n x^{n+4}.$$

# Proportion-from-3



- Two maxima at  $\alpha = 1/3$  and  $\alpha = 2/3$ . There  $f(1/3) = f(2/3) = 2.883\dots$

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 $f(1/2) = 2.723\dots$

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- The median is not the most difficult rank:  $f(1/2) = 2.723\dots$
- Proportion-from-3 beats median-of-three in some regions:  $f(\alpha) \leq m_1(\alpha)$  if  $\alpha \leq 0.201\dots$ ,  $\alpha \geq 0.798\dots$  or  $1/3 < \alpha < 2/3$

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$$\bar{f} = 2.421\dots$$

# Proportion-from-3: Batfind

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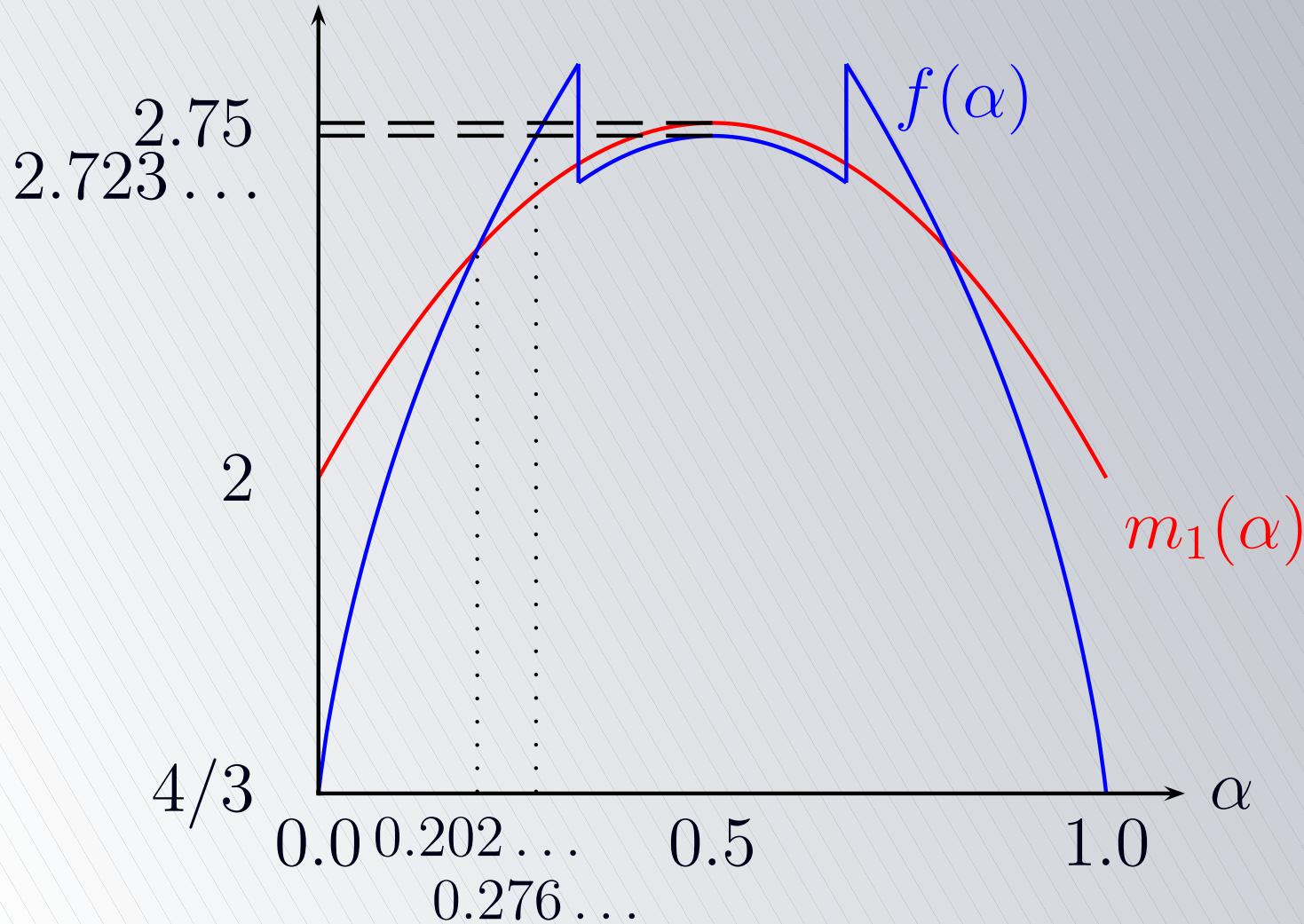
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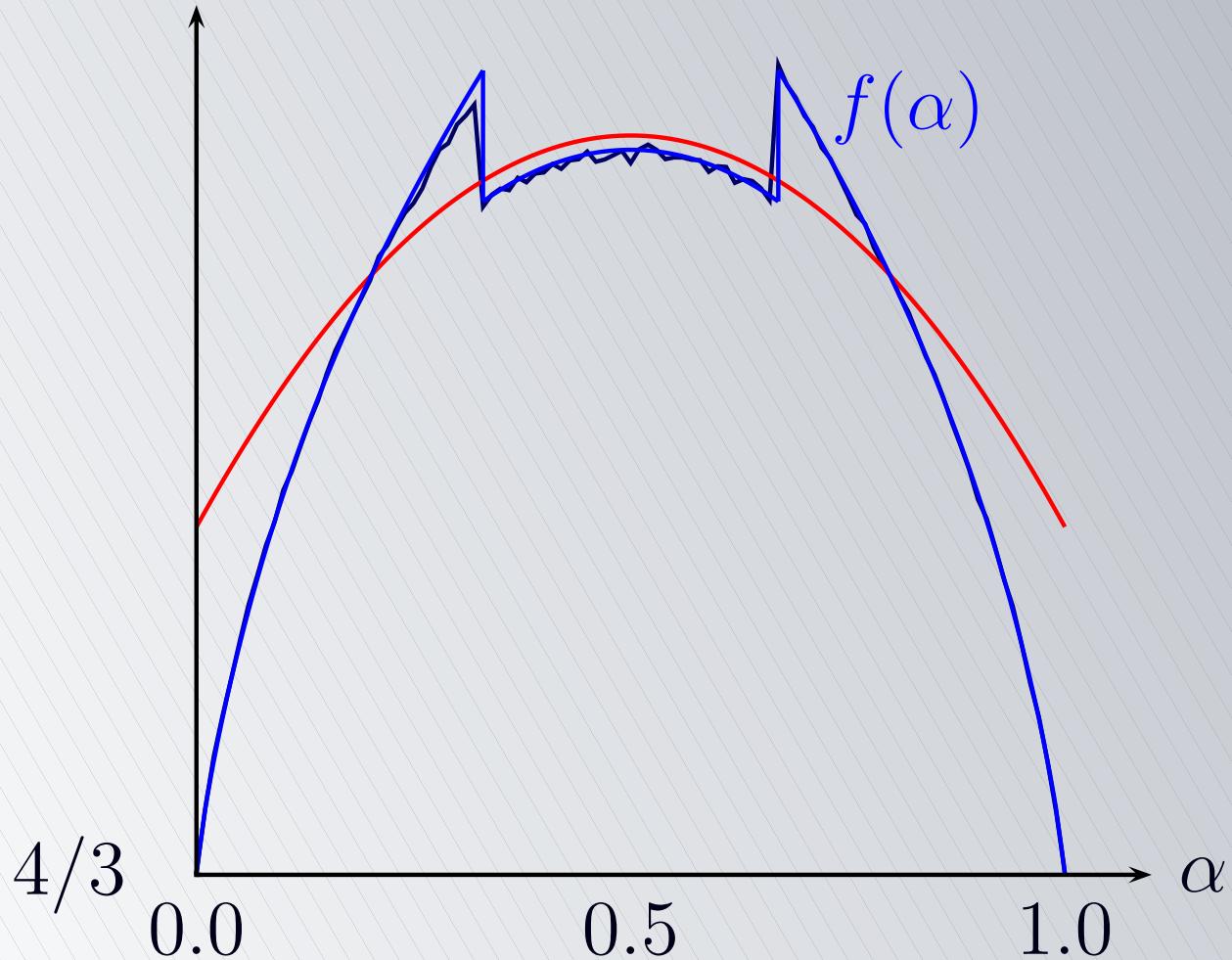
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# Proportion-from-3: Batfind

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- Like proportion-from-3, but  $a_1 = \nu$  and  $a_2 = 1 - \nu$

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- Same differential equation, same  $f_i$ 's, with  $C_i = C_i(\nu)$
- If  $\nu \rightarrow 0$  then  $f_\nu \rightarrow m_1$  (median-of-three)
- However, if  $\nu \rightarrow 1/2$  then  $f_\nu$  behaves like proportion-from-2, but it is not the same

# The optimal $\nu$



**Theorem 2.** *There exists a value  $\nu^*$ , namely,*

*$\nu^* = 0.182 \dots$ , such that for any  $\nu$ ,  $0 < \nu < 1/2$ , and any  $\alpha$ ,*

$$f_{\nu^*}(\alpha) \leq f_\nu(\alpha).$$

*Furthermore,  $\nu^*$  is the unique value of  $\nu$  such that  $f_\nu$  is continuous, i.e.,*

$$f_{\nu^*,1}(\nu^*) = f_{\nu^*,2}(\nu^*).$$

# More on $\nu$ -find

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- If  $\nu > \tilde{\nu} = 0.268\dots$  then  $f_\nu$  has two absolute maxima at  $\alpha = \nu$  and  $\alpha = 1 - \nu$ ; otherwise there is one absolute maximum at  $\alpha = 1/2$

# More on $\nu$ -find



- If  $\nu > \tilde{\nu} = 0.268\dots$  then  $f_\nu$  has **two absolute maxima** at  $\alpha = \nu$  and  $\alpha = 1 - \nu$ ; otherwise there is **one absolute maximum** at  $\alpha = 1/2$
- Obviously, the value  $\nu^*$  minimizes the maximum

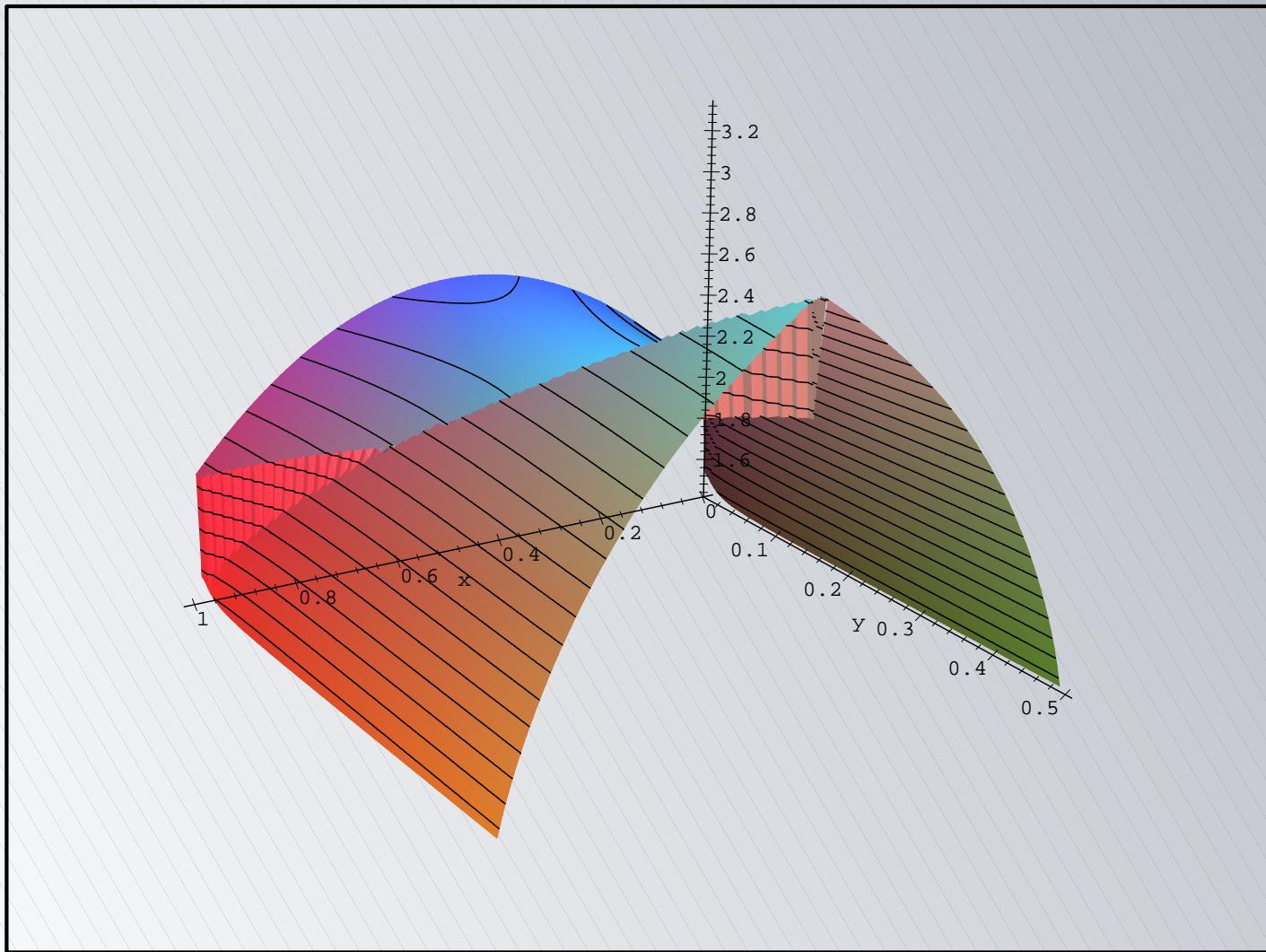
$$f_{\nu^*}(1/2) = 2.659\dots$$

and the mean

$$\bar{f}_{\nu^*} = 2.342\dots$$

# More on $\nu$ -find

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# More on $\nu$ -find

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- If  $\nu \leq \bar{\nu}' = 0.404\dots$  then  $\nu$ -find beats median-of-3 on average ranks:  $\bar{f}_\nu \leq 5/2$

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- If  $\nu \leq \nu'_m = 0.364 \dots$  then  $\nu$ -find beats median-of-3 to find the median:  
 $f_\nu(1/2) \leq 11/4$

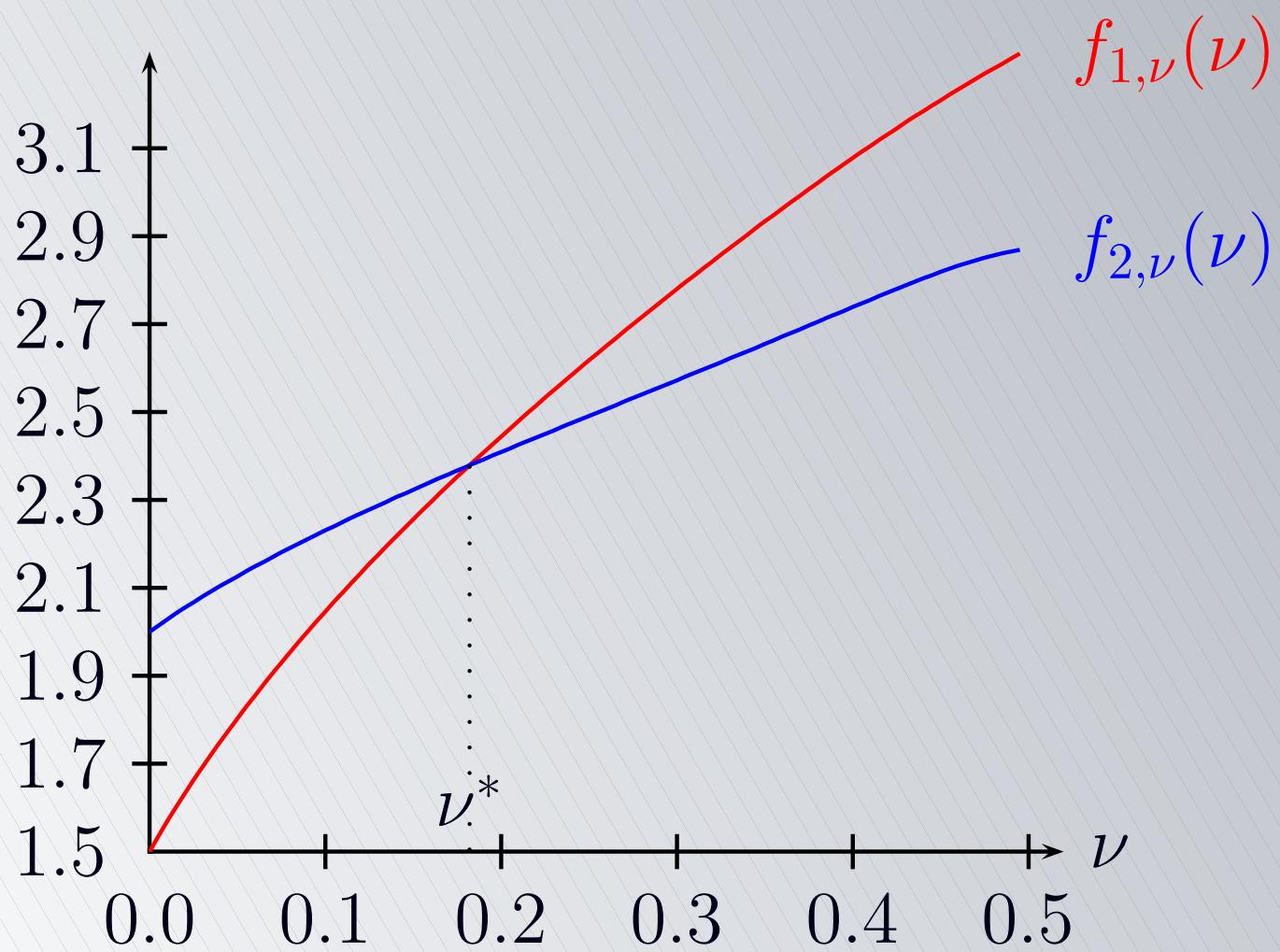
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- If  $\nu \leq \nu'_m = 0.364\dots$  then  $\nu$ -find beats median-of-3 to find the median:  
 $f_\nu(1/2) \leq 11/4$
- If  $\nu \leq \nu' = 0.219\dots$  then  **$\nu$ -find beats median-of-3 for all ranks**:  $f_\nu(\alpha) \leq m_1(\alpha)$

# More on $\nu$ -find

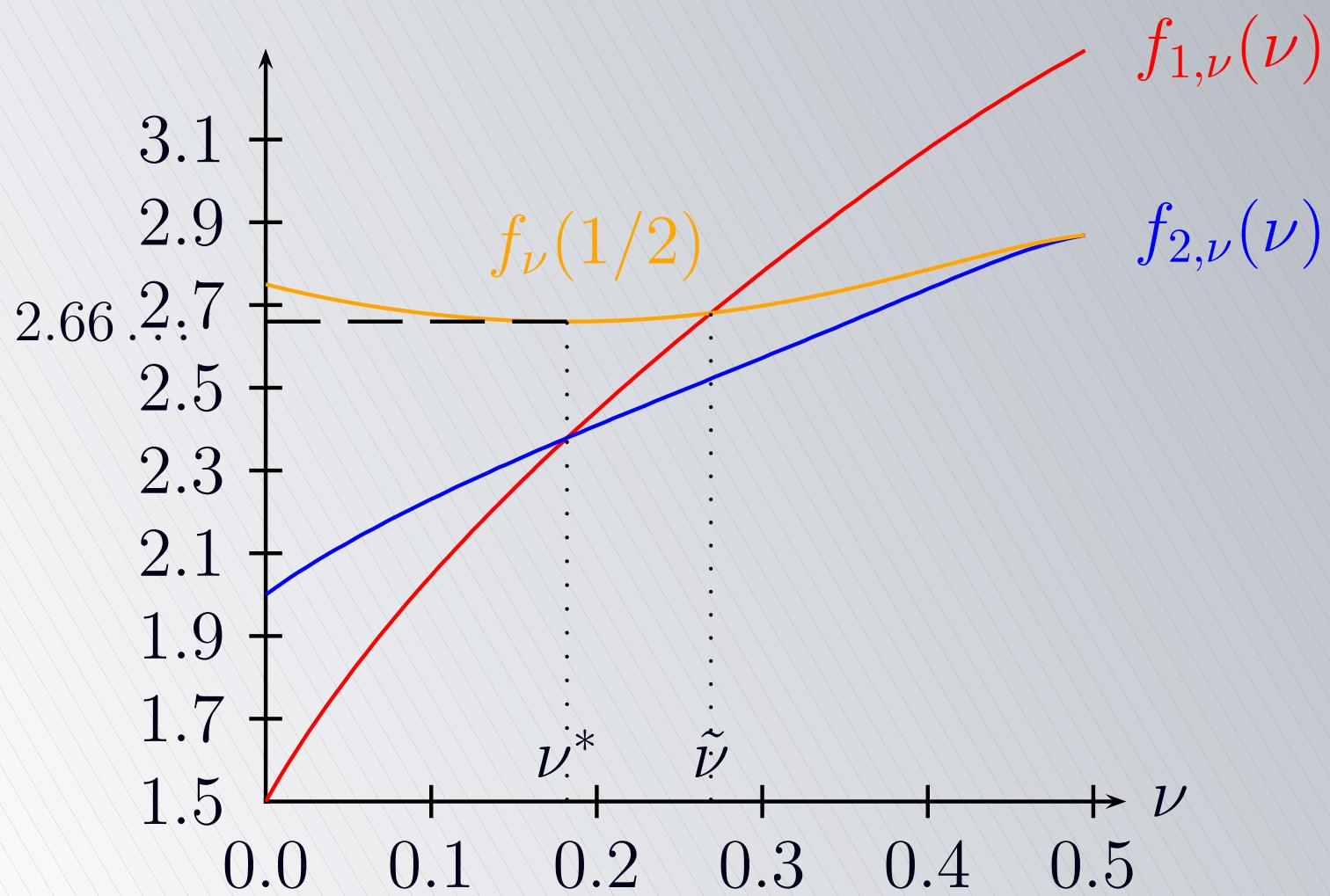
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# More on $\nu$ -find

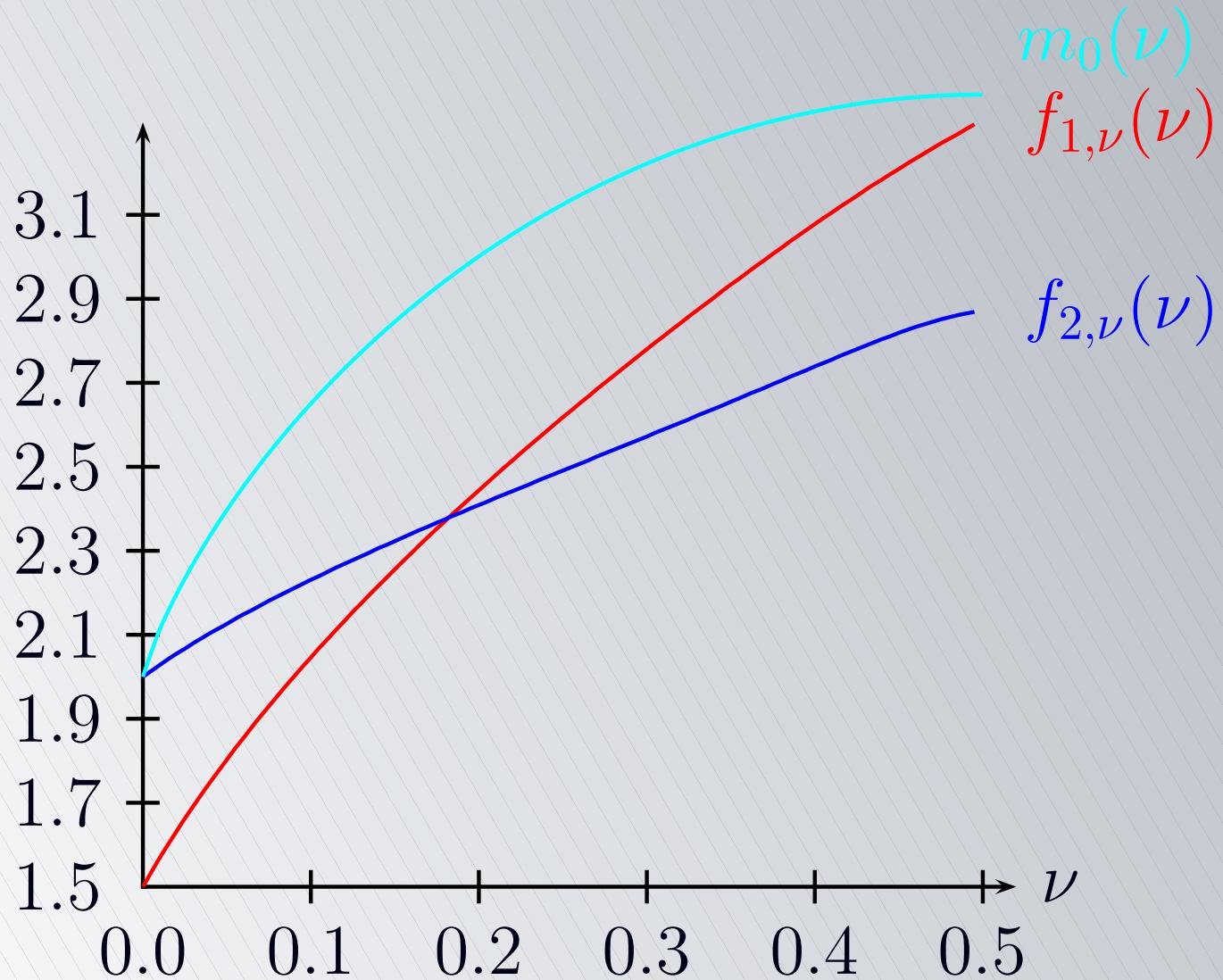
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# More on $\nu$ -find

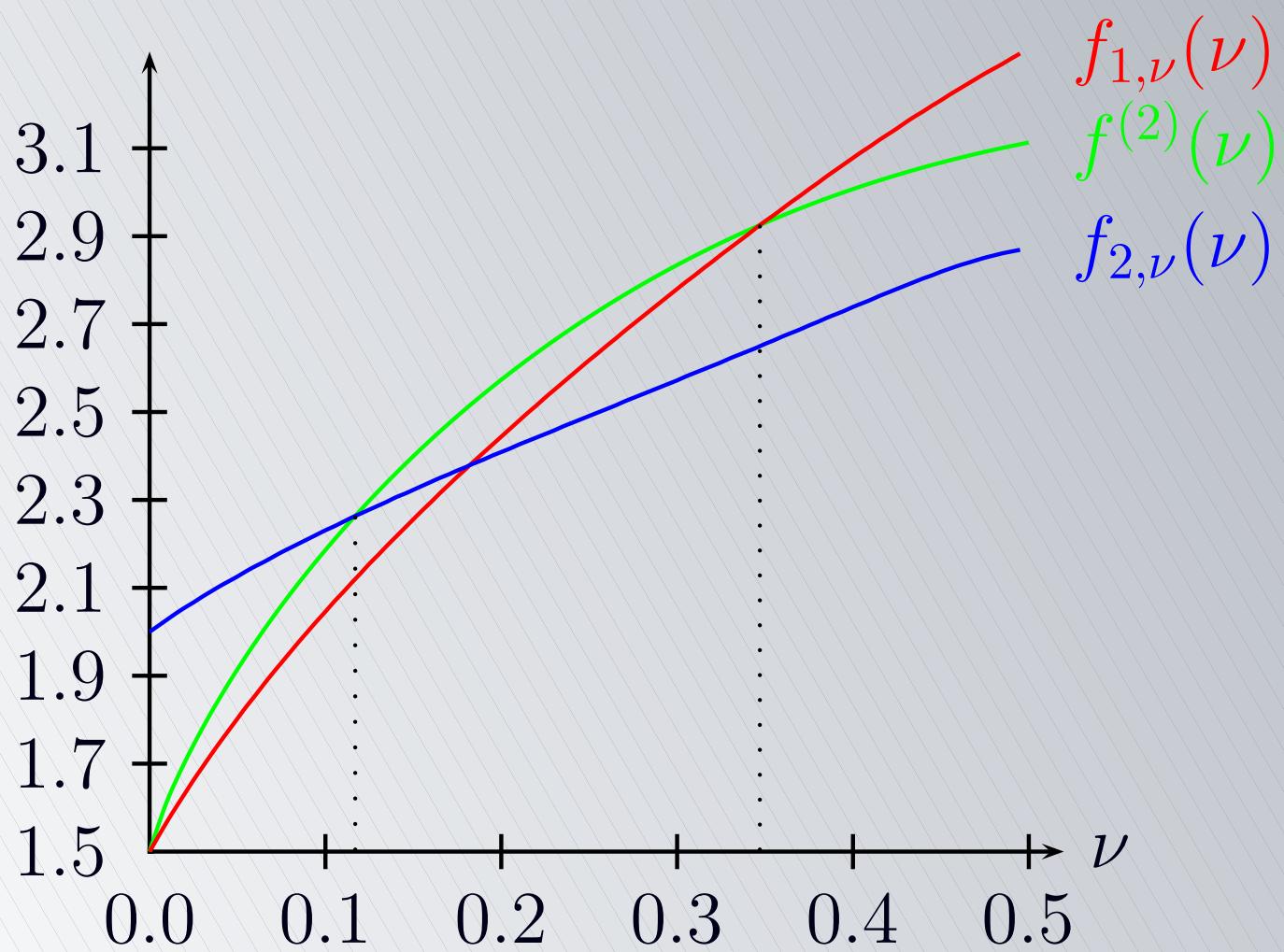
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# More on $\nu$ -find

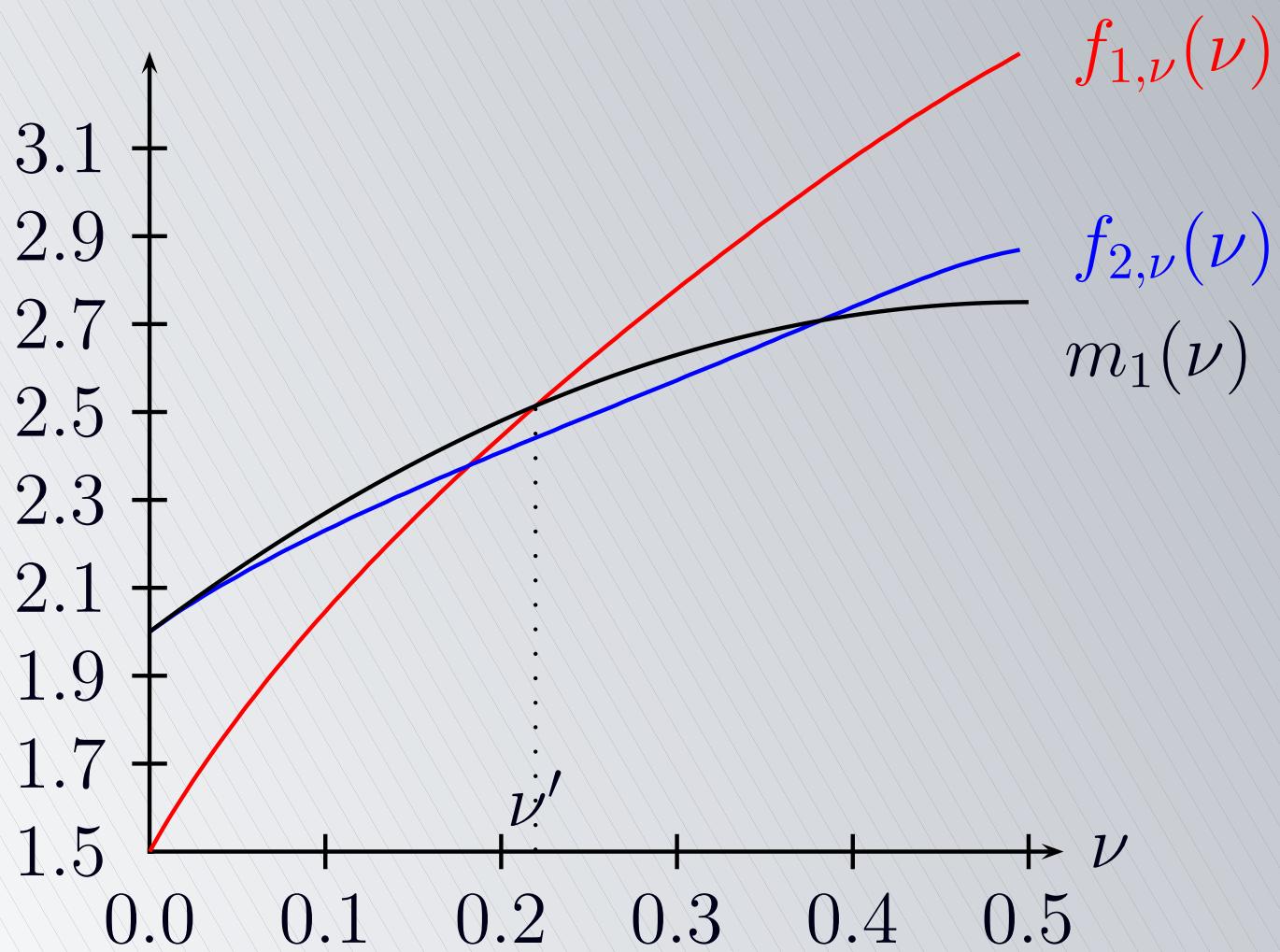
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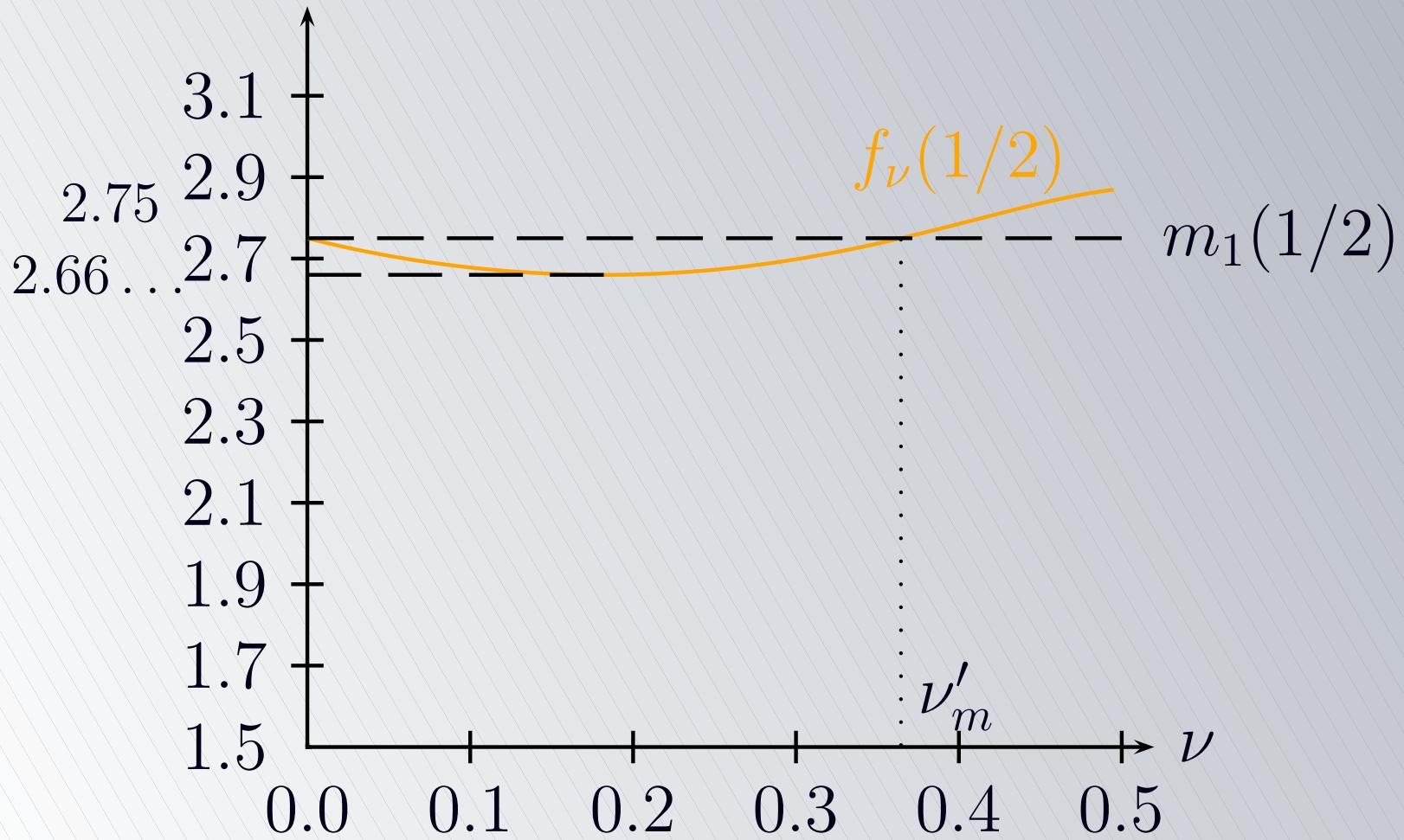
# More on $\nu$ -find

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# More on $\nu$ -find

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# More on $\nu$ -find

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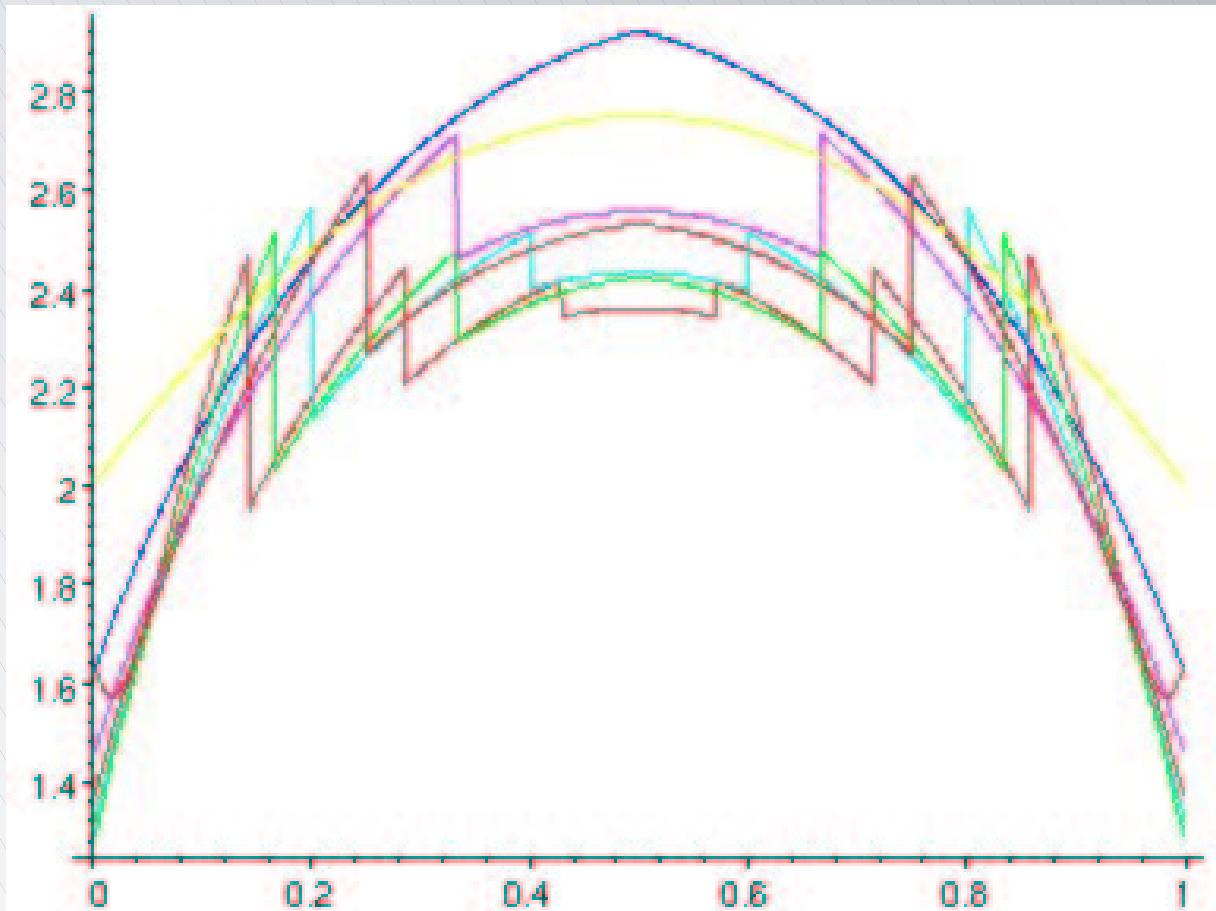
- We have investigated the average **total cost** of  $\nu$ -find

$$\lambda_1 \cdot \# \text{ of comparisons} + \lambda_2 \cdot \# \text{ of exchanges}$$

- The values of  $\nu^*$  (optimum),  $\nu'$  ( $\nu$ -find beats median-of-three), etc. now depend on  $\lambda_2/\lambda_1$ ; for instance, if  $\lambda_2/\lambda_1 = \infty$  we minimize the average number of exchanges with  $\nu^* = 0.43\dots$

# Proportion-from-s: Sharkfind

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# Proportion-from-s: $s \rightarrow \infty$

**Theorem 3.** Let  $f_s(\alpha) = \lim_{n \rightarrow \infty, m/n \rightarrow \alpha} \frac{C_{n,m}}{n}$  when using samples of size  $s$ . Then for any adaptive sampling strategy such that  $\lim_{s \rightarrow \infty} r(\alpha)/s = \alpha$

$$f_\infty(\alpha) = \lim_{s \rightarrow \infty} f_s(\alpha) = 1 + \min(\alpha, 1 - \alpha).$$

This is theoretically optimal for comparison-based selection algorithms.