

# Sampling in data streams

RA-MIRI QT Curs 2020-2021

- 1 Data stream models
- 2 Sampling

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- Can't read again; or reading again has a cost.
- We abstract the data to a particular feature, the data field of interest **the label**.

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- **Goal** Compute a function of stream, e.g., median, number of distinct elements, longest increasing sequence.

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  - Links to communication complexity, compressed sensing, embeddings, pseudo-random generators, approximation, parallel computation, ...

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- **Theoretical Appeal:**
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  - Links to communication complexity, compressed sensing, embeddings, pseudo-random generators, approximation, parallel computation, ...
- Origins in 70's but has become popular in this century because of growing theory and very applicable.

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- **Semi-streaming model**
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- **Streaming with sorting**
  - Allows the creation of intermediate streams.
  - Streams can be sorted at no cost.
  - Algorithms run in phases reading and creating a stream

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- Algorithms use randomization and seek for an approximate answer.
- Typical approach:
  - Build up a **synopsis data structure**
  - It should be enough to compute answers with a high confidence level.



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- **Example:** To compute the median packet size of some IP packets, we could just sample some and use the median of the sample as an estimate for the true median. Statistical arguments relate the size of the sample to the accuracy of the estimate.
- **Challenge:** But how do you take a sample from a stream of unknown length or from a [sliding window](#)?

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- The proof is by induction on  $t$ .
  - **Base  $t = k$ :**  $Pr[x_i \in X] = 1$ , for  $i = 1, \dots, k$ .
  - **Induction hypothesis:** true for time steps up to  $t - 1$ 
    - $Pr[x_t \in X] = k/t$
    - For  $i < t$ ,  $x_i \in X$  when  $x_t$  is not selected and  $x_i$  was in the sample at step  $t - 1$ , or when  $x_t$  is selected,  $x_i$  was in the sample at step  $t - 1$  and  $x_i$  is not evicted.

$$\begin{aligned} Pr[x_i \in X] &= \left(1 - \frac{k}{t}\right) \frac{k}{t-1} + \frac{k}{t} \frac{k}{t-1} \left(1 - \frac{1}{k}\right) \\ &= \frac{k}{t-1} - \frac{k}{t} \frac{k}{t-1} \frac{1}{k} = \frac{k}{t-1} - \frac{1}{t} \frac{k}{t-1} = \frac{k}{t} \end{aligned}$$

# Reservoir Sampling for Sliding Windows

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- **Why reservoir sampling does not work?**
  - Suppose an element in the reservoir expires
  - Need to replace it with a randomly-chosen element from the current window
  - However, in the data stream model we have no access to past data
  - Could store the entire window but this would require  $O(w)$  memory.

# Sliding Windows: Replace-Sampling algorithm

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- **Analysis**
  - The algorithm solves the problem
  - 1 pass,  $O(k \log n)$  space and  $O(1)$  time per item.
- **Trouble:** The sample is highly periodic, this might look as unfair in many applications.

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  - The sample  $X$  of size  $k$  is obtained by an uniform sampling of  $k$  items from  $B$ .

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- **Analysis**
  - 1 pass,  $O((k + |B|) \log n)$  space and  $O(k)$  time per item.
  - $|B|$ ? Should be small compared to  $w$ .
  - **Quality?** The algorithm might fail if  $|B| < k$  at some step.

# Sliding Windows: Backing-Sample size

- **Exercise** Using Chernoff bounds, the size of the backing sample is **between  $k$  and  $4ck \log w$  with probability  $c'w^{-c}$** .
- Selecting the adequate  $c$ , with high probability the algorithm succeeds in keeping a large enough backing sample.

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- The bound on the space is  $O(k \log w)$  with high probability.



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  - For  $t > w$ , when  $t = i + j$ , set  $x = x_{i+j}$  (and choose the next replacement).

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- **Analysis**
  - 1 pass,  $O(\log n + \log w)$  space and  $O(1)$  time per item (some better bound?).
  - Provides a uniform sample.
- For higher values of  $k$  run  $k$  parallel chain samples.  
With high probability, for large enough  $w$ , such chains will not intersect.

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- With high probability the number of updates is  $O(\log m)$ .