Linear Programming approximation: Primal Dual

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AA-GEI: Approx, Param and Stream Linear Programming approximation: Primal Dual



2 Primal-Dual algorithms

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Primal Dual

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Primal Dual

• Many real-life problems can be modeled as Integer Linear Programs (IP).

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Primal Dual

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- Since IPs are NP-hard to solve, they are often relaxed to a linear program (shortened as LP).
- Modus operandi: solve the linear program in polynomial time, and extract useful information about an integer optimum solution.

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Primal Dual

- Many real-life problems can be modeled as Integer Linear Programs (IP).
- Since IPs are NP-hard to solve, they are often relaxed to a linear program (shortened as LP).
- Modus operandi: solve the linear program in polynomial time, and extract useful information about an integer optimum solution.
- However, for certain problems, we do not need to even solve the LP to get good (reasonable approximation factor or even optimal) solutions to our problem using duality to control improvements.

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History

Dantzig

- George Dantzig started linear programming (1947), and his ideas contain the first germs of primal dual algorithms. The Hungarian method was an application of the paradigm.
- Jack R. Edmonds gave the first (sophisticated) application of the paradigm in his work on maximum weight matchings in arbitrary graphs (1965).
- Bar-Yehuda and Even first enunciated the paradigm in their work on the weighted Vertex Cover problem (1981).



Edmonds



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Primal, Dual and Weak Duality

Consider a LP in *n* variables $x = (x_1, ..., x_n)$ with *m* constraints represented by matrix *A*, independent terms *b*, and objective function *b*.

Primal	
min	c ^T x
s.t.	$Ax \ge b$
	$x \ge 0$

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The dual is an effort to construct the best lower bound for the primal objective function.

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Searching for a lower bound: The best one?

LP (PRIMAL)

$$\begin{array}{ll} \min & c^{\mathsf{T}}x\\ \text{s.t.} & Ax \ge b\\ & x \ge 0 \end{array}$$

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if x^* opt, $y^T A x$ is a general linear combination of equations, if we can select y so that $y^T A x^* = c^T x^*$, $c^T x^* > y^T b$

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The best lower bound, for any x?

$$\begin{array}{ll} \min & c^T x \\ \text{s.t.} & Ax \ge b \\ & x \ge 0 \end{array}$$

 $\begin{array}{ll} \max & b^T y \\ \text{s.t.} & A^T y = c \\ y > 0 \end{array}$

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But as we are maximizing this is equivalent to

$$\begin{array}{ll} \max & b^T y \\ \text{s.t.} & A^T y \leq c & \mathsf{DUAL} \\ & y \geq 0 \end{array}$$

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Primal - Dual: an example

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Primal - Dual: an example

• Working from the dual trying to get the best lower bound we come back to the primal.

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Primal - Dual: an example

- Working from the dual trying to get the best lower bound we come back to the primal.
- Another example that you know is the pair MaxFlow-MinCut if you write the LP formulation of MaxFlow you can check that the dual is a LP formulation for MinCut

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Strong and Weak duality theorem

There are additional conditions for a pair (x, y) of primal-dual optimal/feasible solutions.

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Strong and Weak duality theorem

There are additional conditions for a pair (x, y) of primal-dual optimal/feasible solutions.

Theorem (Strong duality)

If the primal has an optimal solution x^* then the dual has an optimal solution y^* such that $c^T x^* = b^T y^*$

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Strong and Weak duality theorem

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If the primal has an optimal solution x^* then the dual has an optimal solution y^* such that $c^T x^* = b^T y^*$

Theorem (Weak Duality)

For every feasible solution x to the primal and every solution z to the dual,

$$\sum_{i=1}^n c_i x_i \geq \sum_{j=1}^m b_j z_j$$

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Conditions for optimality: Complementary slackness

Let x be a feasible solution to the primal and let z be a feasible solution to the dual.

Primal complementary slackness

If $x_i > 0$, then $\sum_{j=1}^m a_{ij}z_j = c_i$.

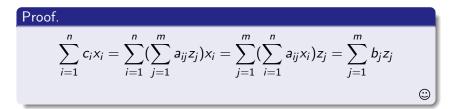
Dual complementary slackness

If $z_j > 0$, then $\sum_{i=1}^n a_{ij}x_i = b_j$.

Conditions for optimality: Complementary slackness

Theorem

If (x, y) satisfies complementary slackness, then x and y are optimal solutions for primal and dual problems, respectively.



Relaxed complementary slackness

Let x be a feasible solution to the primal and let z be a feasible solution to the dual.

Primal relaxed complementary slackness

If $x_i > 0$, then $\sum_{j=1}^m a_{ij} z_j \ge c_i / \alpha$.

Dual relaxed complementary slackness

If $z_j > 0$, then $\sum_{i=1}^n a_{ij} x_i \leq \beta b_j$.

for some factors $\alpha, \beta \geq 1$

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If x is integral and primal and dual relaxed complementary slackness hold?

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Relaxed complementary slackness

Theorem

Let Π be a minimization integer program and Π -LP its LP-relaxation. Suppose a primal (integer) feasible solution x of Π and a dual feasible solution y of Π -LP satisfy the primal-dual relaxed complementary slackness, for some $\alpha, \beta > 1$, and x is integral, then x is a $\alpha\beta$ -approximation.

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Relaxed complementary slackness

Proof.

$$\sum_{i=1}^n c_i x_i \leq \alpha \sum_{i=1}^n (\sum_{j=1}^m a_{ij} z_j) x_i = \alpha \sum_{j=1}^m (\sum_{i=1}^n a_{ij} x_i) z_j \leq \alpha \beta \sum_{j=1}^m b_j z_j$$

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By weak duality $\sum_{j=1}^{m} b_j z_j \leq \sum_{i=1}^{n} c_i x'_i$ for any feasible x', in particular for the optimal solution of the IP, therefore

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$$\sum_{i=1}^{n} c_{i} x_{i} \leq \alpha \beta \sum_{j=1}^{m} b_{j} z_{j} \leq \frac{\alpha \beta}{\alpha \beta} \operatorname{opt}$$

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