

Parameterized Complexity

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Fall 2025

Parameterized complexity

- Possibility to give evidence that certain problems are not FPT.
- Parameterized reduction.
- The W-hierarchy.
- Tighter lower bounds.
- Relation to approximation
- Kernel size lower bounds
- Metatheorems

FPT-reductions

- Let (L, κ) and (L', κ') be two parameterized problems (on the same alphabet Σ)
- A **FPT-reduction** from (L, κ) to (L', κ') is a mapping $R : \Sigma^* \rightarrow \Sigma^*$ where
 - $\forall x \in \Sigma^* \ x \in L$ iff $R(x) \in L'$
 - There is an FPT-algorithm with respect to κ computing R (in $f(\kappa(x))p(|x|)$)
 - There is a computable function $g : \mathbb{N} \rightarrow \mathbb{N}$ such that $\forall x \in \Sigma^* \ \kappa'(R(x)) \leq g(\kappa(x))$
- We note $(L, \kappa) \leq^{fpt} (L', \kappa')$ when there is a FPT-reduction from (L, κ) to (L', κ')

FPT-reductions

Lemma

FPT is closed under FPT-reductions

FPT-reductions and complexity classes

- **FPT-equivalence**

$$(L, \kappa) \equiv^{fpt} (L', \kappa'): (L, \kappa) \leq^{fpt} (L', \kappa') \text{ and } (L', \kappa') \leq^{fpt} (L, \kappa)$$

- P-INDEPENDENT SET \equiv^{fpt} P-CLIQUE

$$R(G, k) = (\overline{G}, k)$$

Works for both directions

- P-HITTING SET \equiv^{fpt} P-DOMINATING SET

Exercise

FPT-reductions and complexity classes

- Closure under FPT-reductions

$$[(L, \kappa)]^{fpt} = \{(L', \kappa') \mid (L', \kappa') \leq^{fpt} (L, \kappa)\}$$

- If \mathcal{C} is a class of parameterized problems

- (L, κ) is \mathcal{C} -hard if $\mathcal{C} \subseteq [(L, \kappa)]^{fpt}$.
- (L, κ) is \mathcal{C} -complete if $(L, \kappa) \in \mathcal{C}$ and (L, κ) is \mathcal{C} -hard.

- $[(L, \kappa)]^{fpt}$ defines a class of parameterized problems for which (L, κ) is complete

- if (L, κ) is \mathcal{C} -complete and \mathcal{C} is closed under FPT reductions, then $\mathcal{C} = [(L, \kappa)]^{fpt}$

FPT-equivalent problems

The class paraNP

- Let (L, κ) be a parameterized problem
- (L, κ) belongs to paraNP if there is a **non-deterministic** algorithm \mathcal{A} that decides $x \in L$ in time $f(\kappa(x))p(|x|)$, for some **computable** function f and **polynomial** function p .
- If $L \in \text{NP}$, for each parameterization κ , $(L, \kappa) \in \text{paraNP}$
p-Clique, p-Vertex Cover, ... belong to paraNP.

paraNP-completeness

- Let (L, κ) be a parameterized problem
- (L, κ) is trivial if $L = \emptyset$ or $L = \Sigma^*$.
- The i -th slice of (L, κ) is the decision problem
 $(L, \kappa)_i = \{x \in L \mid \kappa(x) = i\}$

Theorem

If $(L, \kappa) \in \text{paraNP}$ is not trivial and has a NP-complete slice, then (L, κ) is paraNP-complete under FPT reductions.

paraNP-completeness: problems

- P-VERTEX COLORING is paraNP-complete.
 - P-CLIQUE is not paraNP-complete, unless $P = NP$.
 - $P\#\text{VAR-SAT}$ is not paraNP-complete, unless $P = NP$.
 - $P\text{MAX}\#\text{LIT-SAT}$ is paraNP-complete.
-
- paraNP-completeness separates *all slices* in P from *a slice* is NP-hard.

The class XP

- Let (L, κ) be a parameterized problem.
- (L, κ) belongs to (uniform) XP if there is an algorithm \mathcal{A} that decides L in time $O(|x|^{f(\kappa(x))})$, for some **computable** function f .
- P-CLIQUE, P-VERTEX COVER, P-HITTING SET, P-HITTING SET, P-DOMINATING SET belong to XP.
- XP is the counterpart of EXP in classic complexity.

XP-complete problems

P-EXP-DTM-HALT

Input: A deterministic TM M , $x \in \Sigma^*$ and an integer k ,

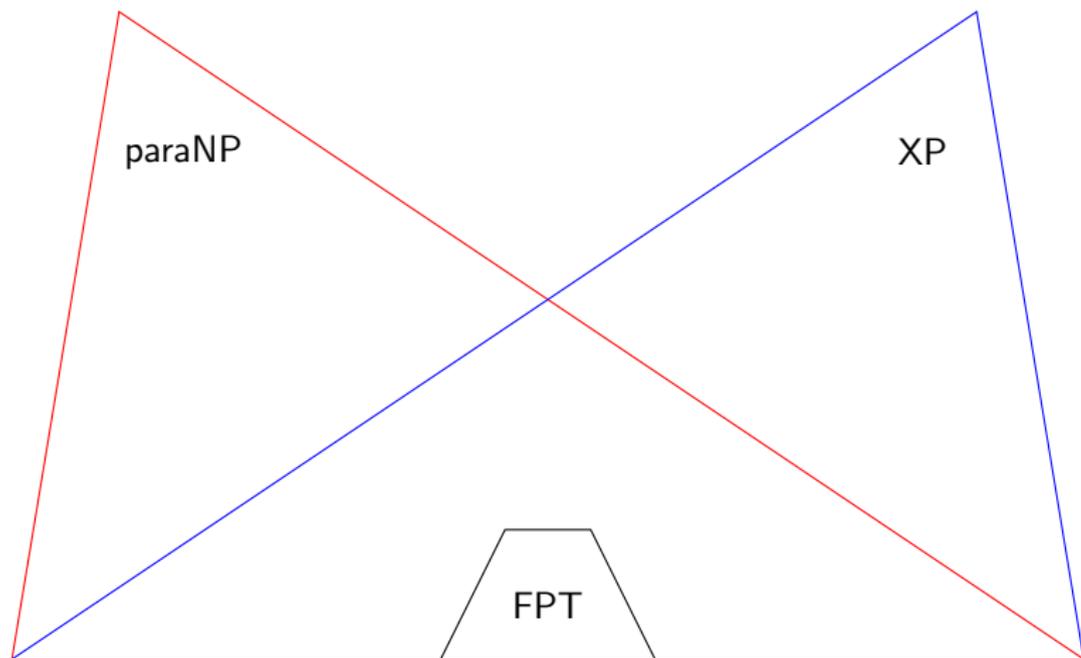
Parameter: k

Question: Does M on input x stop in no more than $|x|^k$ steps?

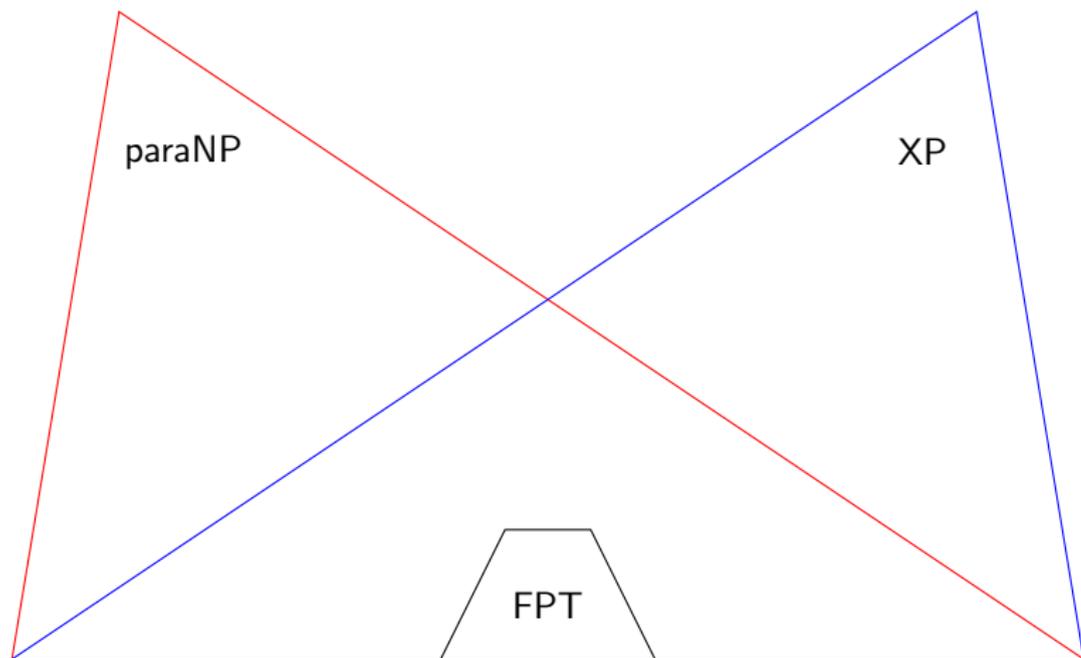
Theorem

P-EXP-DTM-HALT is XP-complete but does not belong to FPT unless $P = NP$.

Relationships among classes



The W-hierarchy



Circuits: Depth and Weft

- Let C be a **boolean circuit**: AND OR NOT gates.
- A **gate is small** if it has only two or one input **otherwise the gate is big**
- The **depth of C** is the maximum distance from an input gate to an output gate.
- The **weft of C** the maximum number of big gates in a path from an input gate to an output gate.
- Note that $\text{depth}(C) \geq \text{weft}(C)$

Variations on SAT

- The weight of an assignment $x = x_1 \dots x_n \in \{0, 1\}^n$ is $W(x) = \sum_{i=1}^n x_i$; i.e., the **number of ones**
- A circuit C is **k -satisfiable** if there is a satisfying assignment with weight k .
- A formula F is **k -satisfiable** if there is a satisfying assignment with weight k .

P-WSAT(FAM)

Input: A circuit/formula C/F in family FAM and an integer k ,

Parameter: k

Question: Is C/F k -satisfiable?

W-classes

Families of circuits/formulas

- CIRC all boolean circuits
- PROP all propositional formulas
- For $d \geq t \geq 0$, define

$$\mathcal{C}_{t,d} = \{c \mid C \in \text{CIRC and } \text{width}(C) \leq t \text{ and } \text{depth}(C) \leq d\}$$

We define the following classes:

- $W[P] = [\text{P-WSAT}(\text{CIRC})]^{fpt}$
- $W[\text{SAT}] = [\text{P-WSAT}(\text{PROP})]^{fpt}$
- For $t \geq 1$, $W[t] = \{[\text{P-WSAT}(\mathcal{C}_{t,d})]^{fpt} \mid d \geq 1\}$

W-hierarchy

- $W[P] = [P\text{-WSAT}(\text{CIRC})]^{fpt}$
- $W[\text{SAT}] = [P\text{-WSAT}(\text{PROP})]^{fpt}$
- For $t \geq 1$, $W[t] = \{[P\text{-WSAT}(C_{t,d})]^{fpt} \mid d \geq 1\}$

Theorem

- $W[P] \subseteq \text{paraNP} \cap \text{XP}$
- $W[\text{SAT}] \subseteq W[P]$
- For $i \geq 1$, $W[i] \subseteq W[\text{SAT}]$ and $W[i] \subseteq W[i + 1]$

W-hierarchy

Theorem

$FPT \subseteq W[1]$

Theorem

- If, for some $i \geq 1$, $FPT \neq W[i]$ then $P \neq NP$
- If $FPT \neq W[SAT]$ then $P \neq NP$
- If $FPT \neq W[P]$ then $P \neq NP$

Any of those conditions imply $FPT \neq paraNP$.

Theorem

If $FPT = W[P]$ then $CIRCUITSAT$ for circuits with n inputs and m gates can be decided in $2^{o(n)} m^{O(1)}$ time.

W[P]-hard problems

Some problems in $W[P]$

- P-CLIQUE, P-DOMINANTSET, P-SETCOVER

But in which level of the W-hierarchy?

- P-CLIQUE $\in W[1]$

To prove this statement it is enough to show a circuit with weft 1 solving the problem (see blackboard)

In fact the problem is $W[1]$ -complete

- P-DOMINATING SET $\in W[2]$ and P-SETCOVER $\in W[2]$
(Exercise)

In fact both problems are $W[2]$ -complete

Exponential Time Hypothesis

Exponential Time Hypothesis (ETH)

n -variable 3-SAT cannot be solved in time $2^{o(n)}$.

- We wish to get results like:
If there is an $f(k) n^{o(k)}$ time algorithm for problem XXX, then ETH fails.

Lower bounds for FPT algorithms

- We know that VERTEX COVER can be solved in time $O^*(c^k)$.
- Can we do it much faster, for example in time $O^*(c^{\sqrt{k}})$ or $O^*(c^{k/\log k})$?

Lemma

If VERTEX COVER can be solved in time $2^{o(k)} n^{O(1)}$, then ETH fails.

Proof.

There is a polynomial-time reduction from m -clause 3SAT to m -vertex VERTEX COVER. The assumed algorithm would solve the latter problem in time $2^{o(m)} n^{O(1)}$, violating ETH. □

Efficient approximation schemes

- Polynomial-time approximation scheme (PTAS):
Input: Instance $x, \epsilon > 0$
Output: $(1 + \epsilon)$ -approximate solution
Running time: polynomial in $|x|$ for every fixed ϵ
- PTAS: running time is $|x|^{f(1/\epsilon)}$
- **Efficient PTAS (EPTAS)** running time is $f(1/\epsilon)|x|^{O(1)}$
- For some problems, there is a PTAS, but no EPTAS is known.
Can we show that no EPTAS is possible?

No EPTAS?

Lemma

If the standard parameterization of an optimization problem is $W[1]$ -hard, then there is no EPTAS for the optimization problem, unless $FPT = W[1]$.

Proof.

Suppose an $f(1/\epsilon) n^{O(1)}$ time EPTAS exists.

Running this EPTAS with $\epsilon = 1/(k + 1)$ decides if the optimum is at most/at least k . □

Closure properties

- A **contraction of an edge (u, v)** in a graph G consists in replacing u, v by a new vertex w which keeps as neighbors $N(u) \cup N(v)$
- A graph H is a **minor of G** if H can be obtained from G by a series of edge contractions.
- **If H is a minor of G then $tw(H) \leq tw(G)$**
(T, X) is a tree decomposition. Contract xy into z . The tree decomposition (T, X') in which we replace x, y by z in any bag containing x or z (or both) is a valid tree decomposition.
- **If H is a subgraph of G then $tw(H) \leq tw(G)$**

Algorithmic theorems

- Algorithmic Theorems provide a proof of the existence of an algorithm.
 - Vertex Cover, Dominating Set, 3-Coloring are solvable in linear time on graphs of constant treewidth.
 - Vertex Cover, Feedback Vertex Set can be solved in sub-exponential time on planar graphs
- To get an algorithm, as we have done, you should working out all the details!

Algorithmic meta theorems

- Algorithmic Meta Theorems. No algorithm is constructed!
- But the existence of an algorithm is proved
- Main uses: quick complexity classification tools, mapping the limits of applicability for specific techniques.
- Usually they are grounded in logics or other properties

First Order Logic on graphs

- We express graph properties using logic
- Basic vocabulary
 - Vertex variables: x, y, z, \dots
 - Edge predicate $E(x, y)$, Equality $x = y$
 - Boolean connectives \vee, \wedge, \neg
 - Quantifiers \forall, \exists
- Example: Dominating Set of size 2

$$\exists x_1 \exists x_2 \forall y E(x_1, y) \vee E(x_2, y) \vee x_1 = y \vee x_2 = y$$

First Order Logic on graphs

- We express graph properties using logic
- Basic vocabulary
 - Vertex variables: x, y, z, \dots
 - Edge predicate $E(x, y)$, Equality $x = y$
 - Boolean connectives \vee, \wedge, \neg
 - Quantifiers \forall, \exists
- Example: Vertex Cover of size 2

$$\exists x_1 \exists x_2 \forall y \forall z E(y, z) \rightarrow (y = x_1 \vee y = x_2 \vee z = x_1 \vee z = x_2)$$

First Order Logic on graphs

- We express graph properties using logic
- Basic vocabulary
 - Vertex variables: x, y, z, \dots
 - Edge predicate $E(x, y)$, Equality $x = y$
 - Boolean connectives \vee, \wedge, \neg
 - Quantifiers \forall, \exists
- Example: Clique of size 3

$$\exists x_1 \exists x_2 \exists x_3 E(x_1, x_2) \wedge E(x_1, x_3) \wedge E(x_2, x_3)$$

First Order Logic on graphs

- We express graph properties using logic
- Basic vocabulary
 - Vertex variables: x, y, z, \dots
 - Edge predicate $E(x, y)$, Equality $x = y$
 - Boolean connectives \vee, \wedge, \neg
 - Quantifiers \forall, \exists
- Many standard (parameterized) problems can be expressed in FO logic.
- But some easy problems are inexpressible (e.g. connectivity).
- Rule of thumb: FO = local properties

Monadic Second Order Logic

- MSO logic: we add to FO logic
 - set variables S_1, S_2, \dots
 - and the $a \in$ predicate.
 - Quantifiers \forall, \exists
 - MSO₁ logic: we can quantify over sets of vertices only
 - MSO₂ logic: we can quantify over sets of edges
- Example: 2-coloring

$$\exists V_1 \exists V_2 \forall x \forall y E(x, y) \rightarrow (x \in V_1 \leftrightarrow y \in V_2)$$

Algorithmic meta theorems

- All **Monadic Second Order logic (MSO)** expressible problems are solvable in linear time on graphs of constant treewidth.
- All **minor closed** optimization problems can be solved in sub-exponential time on planar graphs

Recall: The proof does not provide any algorithm!