

Parameterization: Kernelization

AiC FME, UPC

Fall 2023

- 1 Kernelization
- 2 p-vertex cover
- 3 p-MaxSat
- 4 Crown decomposition
- 5 Summary

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So, it is an FPT algorithm provided the problem is decidable.

k-Vertex Cover: reduction rules?

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p -VERTEX COVER

Input: a graph G and an integer k ,

Parameter: k

Question: $\exists S \subseteq V(G) \mid |S| = k$ and $\forall \{u, v\} \in E(G) \mid \{u, v\} \cap S \geq 1$?

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- recall: Two instances x_1 and x_2 of decision problem P are **equivalent** when " $x_1 \in P$ iff $x_2 \in P$ ".

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- How big is (G', k') ?

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- So, we can filter as NO instances those leading to reduced instances with a high number of edges!
- By Obs 3, if $|E(G')| > k^2$, we replace (G', k') by a trivial small NO-instance, which is again equivalent.

Kernel

Theorem

Let (G, k) be an instance to **P-VC**. In polynomial time we can obtain an equivalent **P-VC** instance (G', k') with $|V(G')|, |E(G')| \leq O(k^2)$.

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 - has size bounded by a **function of the parameter**

Kernelization algorithm

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- Assume that KER-P is a polynomial time algorithm computing a kernel for a given instance of problem P and that ALG-P is an exact (exponential time) algorithm for P .

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function ALGKERNEL-P( $x$ )
   $z = \text{KER-P}(x)$ 
  return ( $\text{ALG-P}(z)$ )
  
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Kernelization algorithm

- Assume that KER-P is a polynomial time algorithm computing a kernel for a given instance of problem P and that ALG-P is an exact (exponential time) algorithm for P .

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function ALGKER-P( $x$ )
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- ALGKER-P-VC is an FPT algorithm for P .

A kernelization algorithm for p-VC

```

function ALGKERNEL-P-VC( $G, k$ )
  ( $G', k'$ ) = Iteratively remove isolated vertices and vertices
    with degree at least  $k + 1$ , decreasing the parameter
    by one in the second case.
  if  $|E(G')| > k^2$  then return NO
  for each  $S \subseteq V'$  with  $|S| = k'$  do
    if  $S$  is a vertex cover then return SI
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A kernelization algorithm for p-VC

function ALGKERNEL-P-VC(G, k)

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ALGKERNEL-P-VC runs in $O(n^c + k^{2k}k^2) = O(n^c) + O(k^{2k+2})$

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Input: a Boolean CNF formula F and an integer k .

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Recall that the size of a CNF formula is the sum of clause lengths (# literals); we ignore as usual log-factors.

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- A clause in F is **trivial** if it contains both a positive and negative literal in the same variable.

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Obs 1

Let F' be obtained from formula F by removing all t trivial clauses. $(F', k - t)$ and (F, k) are equivalent.

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- A clause in (F, k) is **long** if it contains at least k literals, and **short** otherwise.

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Obs 2

Let F_s be obtained from formula F by removing all $\ell < k$ long clauses. $(F_s, k - \ell)$ and (F, k) are equivalent.

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If F contains at least $2k$ clauses, (F, k) is a YES instance of **P-MAXSAT**.

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Proof.

Take an arbitrary truth assignment x and its complement \bar{x} obtained by flipping all variables. Every clause of F is satisfied by x or by *overlinex* (or by both). The one that satisfies most clauses satisfies at least k clauses. □

A kernelization algorithm for p-MaxSat

```

1: function ALGKERNEL-P-MAXSAT( $F, k$ )
2:   Remove from  $F$  all  $t$  trivial clauses and set  $k = k - t$ 
3:   if  $F$  has at least  $k$  long clauses then return YES
4:   Remove from  $F$  all  $\ell$  long clauses and set  $k = k - \ell$ 
5:   if  $F$  has at least  $2k$  clauses then return YES
6:   for each set of  $k$  clauses do
7:     for each selection of one literal per clause in the set do
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After step 5, F contains at most $2k'$ clauses with at most k' literals, for $k' = k - t - \ell$.

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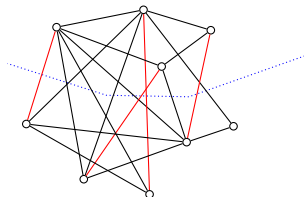
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ALGKERNEL-P-MAXSAT is an FPT algorithm for p-MAXSAT.

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- *Crown decomposition* is a general kernelization technique based on some results on matchings.

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- For disjoint vertex subsets U, W of a graph G , M is a **matching of U into W** if every edge of M connects a vertex of U and a vertex of W and every vertex of U is an endpoint of some edge of M . We also say that **M saturates U** .



If M saturates U , $|U| \leq |W|$

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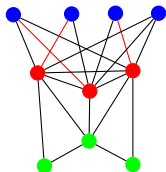
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Removing H separates C from R .

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Computing a crown decomposition

Theorem (König's theorem)

In every undirected bipartite graph the size of a maximum matching is equal to the size of a minimum vertex cover.

Theorem (Hall's theorem)

Let $G = (V_1, V_2, E)$ be an undirected bipartite graph. G has a matching saturating V_1 iff for all $X \subseteq V_1$, we have $|N(X)| \geq |X|$.

Can you obtain a minimum vertex cover in a bipartite graph in polynomial time?

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Can you obtain a minimum vertex cover in a bipartite graph in polynomial time? **YES!**

Computing a crown decomposition

Theorem (Hopcroft-Karp, SIAM J. Computing 2, 225–231 (1973))

Let $G = (V_1, V_2, E)$ be an undirected bipartite graph on n vertices and m edges. Then we can find a maximum matching as well as a minimum vertex cover of G in time $O(m\sqrt{n})$. Furthermore, in time $O(m\sqrt{n})$ either we can find a matching saturating V_1 or an inclusion-wise minimal set $X \subseteq V_1$ such that $|N(X)| < |X|$.

Crown lemma

Lemma

Let $G = (V, E)$ be a graph without isolated vertices and with at least $3k + 1$ vertices. There is a polynomial-time algorithm that either

- finds a matching of size $k + 1$ in G ; or
- finds a crown decomposition of G .

Proof

We compute a maximal matching M in G .

If $|M| \geq k + 1$, we are done.

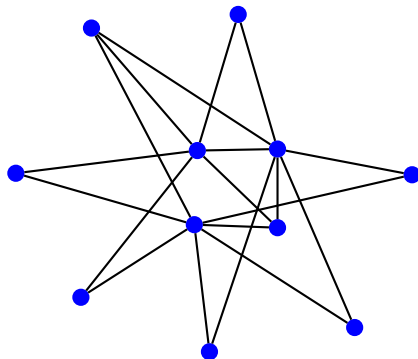
Now, $1 \leq |M| \leq k + 1$.

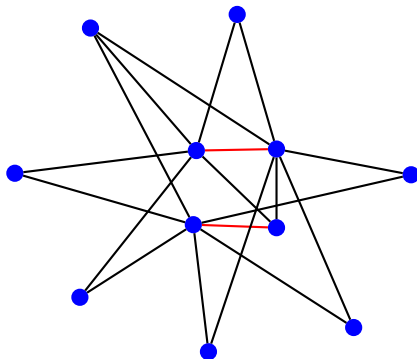
Let V_M be the end points of M and $I = V - V_M$.

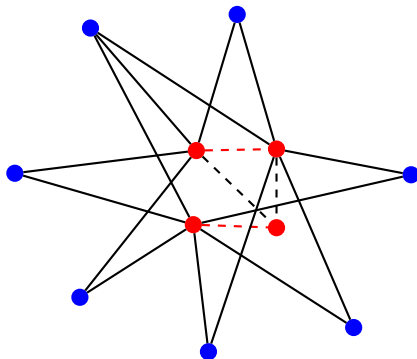
- M is a maximal matching, so I is an independent set.
- Let G_{I, V_M} be the bipartite subgraph induced in G by I and V_M .
- In polynomial time, we compute a minimum size vertex cover X and a maximum matching M' in G_{I, V_M} .
- If $|M'| \geq k$, we are done. From now on, $|M'| \leq k$ and also $|X| \leq k$.
- If $X \cap V_M = \emptyset$, $X = I$. Then, $|I| = |X| \leq k$ and $|V| = |I| + |X| \leq k + 2k \leq 3k!$
- Then, $X \cap V_M \neq \emptyset$

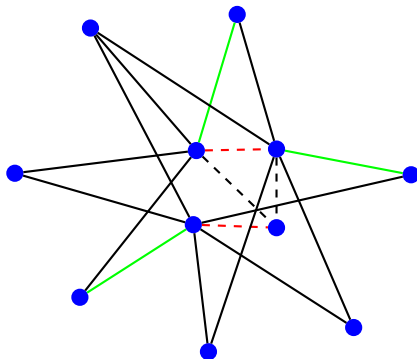
- We obtain a crown decomposition (C, H, R) as follows.
- Since $|X| = |M'|$, every edge of the matching M' has exactly one endpoint in X .
- Let M^* be the subset of M' such that every edge from M^* has exactly one endpoint in $X \cap V_M$ and let V_{M^*} denote the set of endpoints of edges in M^* .
- Set head $H = X \cap V_M = X \cap V_{M^*}$, crown $C = V_{M^*} \cap I$, and the remaining part is R .
- C is an independent set and, by construction, M^* is a matching of H into C .
- Since X is a vertex cover of G_{I, V_M} , every vertex of C can be adjacent only to vertices of H .

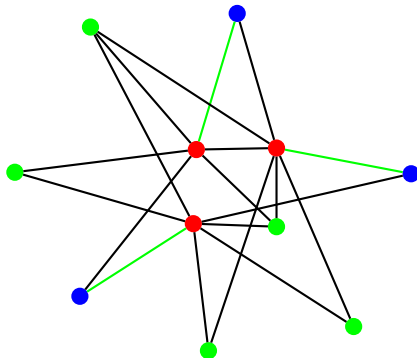
End proof

An example with $k = 3$ 

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Crown decomposition: Vertex cover

Consider a Vertex Cover instance (G, k) .

- By an exhaustive application of the isolated vertex reduction rule, we may assume that G has no isolated vertices.
- If $|V(G)| > 3k$, we use the crown lemma to get either
- a matching of size $k + 1$, (so (G, k) is a no-instance) or a crown decomposition C, H, R .

Crown decomposition: Vertex cover

From the crown decomposition C, H, R of G , let M be a matching of H into C .

- The matching M witnesses that, for every vertex cover X of G , X contains at least $|M| = |H|$ vertices of $H \cap C$ to cover the edges of M .
- H covers all edges of G that are incident to $H \cup C$.
- So, there exists a minimum vertex cover of G that contains H , and we may reduce (G, k) to $(G - H, k - |H|)$.
- Further, in $(G - H, k - |H|)$, $c \in C$ is isolated and can be eliminated.

Crown decomposition: Vertex cover

As the crown lemma promises that $H \neq \emptyset$, we can always reduce the graph as long as $|V(G)| > 3k$.

Lemma

Vertex Cover admits a kernel with at most $3k$ vertices.

Crown decomposition: Max SAT

Lemma

Max SAT admits a kernel with at most k variables and $2k$ clauses.

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- These are preprocessing algorithms that can add to any algorithmic method (e.g. approximation/exact algorithms).
- Kernelization algorithms usually consist of reduction rules, which reduce simple local structures (degree 1 vertices / high degree vertices / long clauses, etc), and a bound $f(k)$ for irreducible instances (X, k) that allows us to

Kernelization: summary

- For parameterized problems, kernelization algorithms are a method to obtain FPT algorithms.
- These are preprocessing algorithms that can add to any algorithmic method (e.g. approximation/exact algorithms).
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 - return NO if $|X| > f(k)$, for minimization problems, or
 - return YES if $|X| > f(k)$, for maximization problems.

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- We would like to get a kernel as small as possible.
- Statements like: (L, κ) does not admit a linear (quadratic) kernel unless **some complexity assumption fails** are the kind of results showing kernelization hardness.