

# Proving Unsatisfiability in Non-linear Arithmetic by Duality

[work in progress]

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- **Introduction**
- **Motivation**
  - Constraint-based program analysis
- **Non-linear constraint solving**
  - Related work in SMT(NA) [NA = Non-linear Arithmetic]
  - Review of [Borralleras et al., JAR'12]: pros and cons
  - Duality: Positivstellensatz
  - Proving unsatisfiability by finding solutions
- **Open questions and future work**

- **Non-linear Constraint Solving:** Given a quantifier-free formula  $F$  containing polynomial inequality atoms, is  $F$  satisfiable?
- In  $\mathbb{Z}$ : **undecidable** (Hilbert's 10th problem)
- In  $\mathbb{R}$ : decidable, even with quantifiers (Tarski).  
But traditional algorithms have **prohibitive worst-case complexity**
- Lots of applications: non-linear constraints arise in many contexts.  
Here, focus will be on **program analysis**
- **Goal:** a procedure that works well in practice for our application

# Targeted Programs

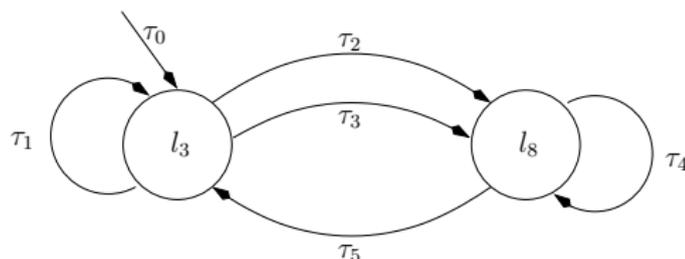
- **Imperative** programs
- **Integer variables** and **linear** expressions  
(other constructions considered unknowns)

```
int gcd ( int a, int b ) {  
    int tmp;  
    while ( a >= 0 && b > 0 ) {  
        tmp = b;  
        if (a == b)  b = 0;  
        else {  
            int z = a;  
            while ( z > b )  z -= b;  
            b = z; }  
        a = tmp; }  
    return a; }
```

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As a transition system:

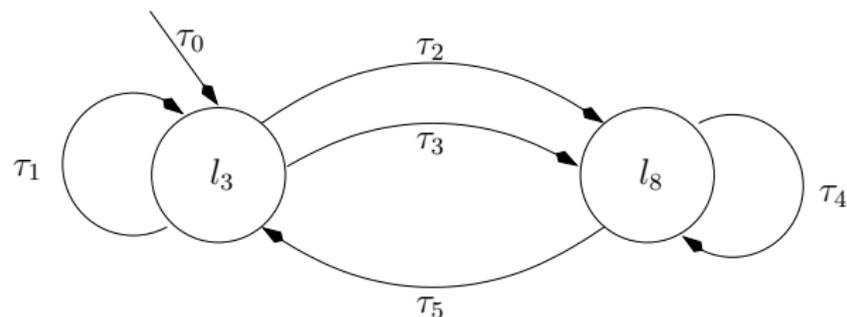


$\tau_0 :$			$a' = ?,$	$b' = ?,$	$tmp' = ?,$	$z' = ?$	
$\tau_1 :$	$b \geq 1,$	$a \geq 0,$	$a = b,$	$a' = b,$	$b' = 0,$	$tmp' = b,$	$z' = z$
$\tau_2 :$	$b \geq 1,$	$a \geq 0,$	$a < b,$	$a' = a,$	$b' = b,$	$tmp' = b,$	$z' = a$
$\tau_3 :$	$b \geq 1,$	$a \geq 0,$	$a > b,$	$a' = a,$	$b' = b,$	$tmp' = b,$	$z' = a$
$\tau_4 :$	$b < z,$			$a' = a,$	$b' = b,$	$tmp' = tmp,$	$z' = z - b$
$\tau_5 :$	$b \geq z,$			$a' = tmp,$	$b' = z,$	$tmp' = tmp,$	$z' = z$

- An **invariant** of a program at a location is an assertion over the program variables that is true whenever the location is reached
- Useful in **safety analysis**:  
if  $F$  are forbidden states, prove that  $\neg F$  is (implied by an) invariant
- An invariant is **inductive** at a program location if:
  - *Initiation condition*: it holds the first time the location is reached
  - *Consecution condition*: it is preserved by every cycle back to location

We are interested in **inductive invariants**

# Invariants



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Assertion  $b \geq 1$  is invariant at  $l_8$

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$$\alpha_1 x_1 + \dots + \alpha_n x_n \geq \beta$$

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- Impose initiation and consecution conditions obtaining  $\exists \forall$  problem
- Transform into  $\exists$  problem over non-linear arith. with **Farkas' Lemma**
- Solve resulting non-linear constraints

In matrix notation:

$$(\forall x \in \mathbb{R}^n) (Ax \geq b \Rightarrow c^T x \geq d)$$

iff

$$(\exists \lambda \in \mathbb{R}^m) (\lambda \geq 0 \wedge ((\lambda^T A = c^T \wedge \lambda^T b \geq d) \vee (\lambda^T A = 0 \wedge \lambda^T b = -1)))$$

# Particularities of Our SMT(NA) Problems

- Existentially quantified variables are:
  - **unknown template coefficients** of invariants and ranking functions
  - **Farkas' multipliers**
- Non-linear monomials are quadratic of the form

unknown template coefficient  $\cdot$  Farkas' multiplier

- Existentially quantified variables are of real type...  
But it is reasonable to assume that if satisfiable there is a solution where unknown template coefficients are integers

(when we program, we think invariants/ranking functs. with integer coefficients, right?)

# Related Work in SMT(NA)

- Methods aimed at proving **unsatisfiability**:
  - Gröbner bases [Tiwari, CSL'05; De Moura, Passmore, SMT'09]
  - Semidefinite programming [Parrilo, MP'03]
  - Mixed approaches [Platzer, Quesel, Rummer, CADE'09]
- Methods aimed at proving **satisfiability**:
  - Cylindrical Algebraic Decomposition (CAD) [Collins, ATFL'75]
  - Translating into
    - SAT [Fuhs et al., SAT'07]
    - SMT(BV) [Zankl, Middeldorp, LPAR'10]
    - SMT(LA) [Borralleras et al., JAR'12]
  - Model-constructing satisfiability calculus [De Moura, Jovanovic, IJCAR'12]

- Our method is aimed at proving satisfiability in the integers (as opposed to finding non-integer solutions, or proving unsatisfiability)
- **Basic idea:** use bounds on integer variables to **linearize** the formula
- **Refinement:** analyze **unsatisfiable cores** to enlarge bounds (and sometimes even prove unsatisfiability)

- For any formula there is an equisatisfiable one of the form

$$F \wedge \left( \bigwedge_i y_i = M_i \right)$$

where  $F$  is linear and each  $M_i$  is non-linear

- Example

$$u^4 v^2 + 2u^2 vw + w^2 \leq 4 \wedge 1 \leq u, v, w \leq 2$$

$$x_{u^4 v^2} + 2x_{u^2 vw} + x_{w^2} \leq 4 \wedge 1 \leq u, v, w \leq 2 \wedge$$

$$x_{u^4 v^2} = u^4 v^2 \wedge x_{u^2 vw} = u^2 vw \wedge x_{w^2} = w^2$$

- **Idea:** linearize non-linear monomials with case analysis on some of the variables with finite domain
- Assume variables are in  $\mathbb{Z}$
- $F \wedge x_{u^4v^2} = u^4v^2 \wedge x_{u^2vw} = u^2vw \wedge x_{w^2} = w^2$   
where  $F$  is  $x_{u^4v^2} + 2x_{u^2vw} + x_{w^2} \leq 4 \wedge 1 \leq u, v, w \leq 2$
- Since  $1 \leq w \leq 2$ , add  $x_{u^2v} = u^2v$  and  
 $w = 1 \rightarrow x_{u^2vw} = x_{u^2v}$   
 $w = 2 \rightarrow x_{u^2vw} = 2x_{u^2v}$

Applying the same idea recursively, the following linear formula is obtained:

$$x_{u^4v^2} + 2x_{u^2vw} + x_w^2 \leq 4$$

$$\wedge 1 \leq u, v, w \leq 2$$

$$\wedge w = 1 \rightarrow x_{u^2vw} = x_{u^2v}$$

$$\wedge w = 2 \rightarrow x_{u^2vw} = 2x_{u^2v}$$

$$\wedge u = 1 \rightarrow x_{u^2v} = v$$

$$\wedge u = 2 \rightarrow x_{u^2v} = 4v$$

$$\wedge w = 1 \rightarrow x_w^2 = 1$$

$$\wedge w = 2 \rightarrow x_w^2 = 4$$

$$\wedge v = 1 \rightarrow x_{u^4v^2} = x_{u^4}$$

$$\wedge v = 2 \rightarrow x_{u^4v^2} = 4x_{u^4}$$

$$\wedge u = 1 \rightarrow x_{u^4} = 1$$

$$\wedge u = 2 \rightarrow x_{u^4} = 16$$

A model can be computed:

$$u = 1$$

$$v = 1$$

$$w = 1$$

$$x_{u^4v^2} = 1$$

$$x_{u^4} = 1$$

$$x_{u^2vw} = 1$$

$$x_{u^2v} = 1$$

$$x_w^2 = 1$$

- If linearization achieves a linear formula then we have a **sound** and **complete** decision procedure

Note also that actually **not all variables need to be integers**: only enough to get a linear formula

- If we don't have enough variables with finite domain...  
... we can add bounds at cost of **losing completeness**  
We cannot trust UNSAT answers any more!

- But we can analyze **why** the CNF is UNSAT:  
an **unsatisfiable core** (= unsatisfiable subset of clauses) can be obtained from the trace of the DPLL execution [Zhang & Malik'03]

- If core contains no extra bound: truly UNSAT  
If core contains extra bound: guide to enlarge domains

# Review of [Borralleras et al., JAR'12]

- $u^4v^2 + 2u^2vw + w^2 \leq 3$  cannot be linearized
- Consider  $u^4v^2 + 2u^2vw + w^2 \leq 3 \wedge 1 \leq u, v, w \leq 2$
- The linearization is unsatisfiable:

$$\begin{aligned}x_{u^4v^2} + 2x_{u^2vw} + x_{w^2} &\leq 3 \\ \wedge 1 &\leq x_{u^4v^2} \wedge x_{u^4v^2} \leq 64 \\ \wedge 1 &\leq x_{u^2vw} \wedge x_{u^2vw} \leq 16 \\ \wedge 1 &\leq x_{w^2} \wedge x_{w^2} \leq 4 \\ \wedge 1 &\leq u \wedge u \leq 2 \\ \wedge 1 &\leq v \wedge v \leq 2 \\ \wedge 1 &\leq w \wedge w \leq 2 \\ \dots\end{aligned}$$

- Should decrease lower bounds for  $u, v, w$

- **In favour:** very effective when handling **satisfiable instances**
  - Best solver in QF\_NIA division in SMT-COMP'09, SMT-COMP'10
  - According to our experiments, even faster than latest version of Z3 on benchmarks coming from our application
- **Against:** often fails to detect unsatisfiability on **unsatisfiable instances** (and then keeps enlarging domains forever!)

Need more powerful non-linear reasoning than with unsat cores!

- Let's focus on **conjunctions of polynomial inequalities** from now on

# Duality: Positivstellensatz

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  - the **multiplicative monoid** generated by  $A$ ,  $\text{Monoid}(A)$ , is the set of products of zero or more elements in  $A$

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  - the **cone** generated by  $A$ ,  $\text{Cone}(A)$ , is the set of sums of products of the form  $pPQ^2$ , where  $p \in \mathbb{Q}$ ,  $p > 0$ ,  $P \in \text{Monoid}(A)$  and  $Q \in \mathbb{Q}[x]$

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  - the **ideal** generated by  $A$ ,  $\text{Ideal}(A)$ , is the set of sums of products of the form  $PQ$ , where  $P \in A$  and  $Q \in \mathbb{Q}[x]$
- **Positivstellensatz:** Let  $F_>, F_{\geq}, F_{=} \subset \mathbb{Q}[x]$ . The system

$$\{f > 0 \mid f \in F_>\} \cup \{f \geq 0 \mid f \in F_{\geq}\} \cup \{f = 0 \mid f \in F_{=}\}$$

is unsatisfiable in  $\mathbb{R}^n$  iff there are  $P \in \text{Monoid}(F_>)$ ,  
 $Q \in \text{Cone}(F_> \cup F_{\geq})$  and  $R \in \text{Ideal}(F_{=})$  such that  $P + Q + R = 0$

# Proving Unsatisfiability by Finding Solutions

We can prove a system unsatisfiable by finding a solution to another one!

Find the **Positivstellensatz witness**  $P, Q, R$  as follows:

- Set a degree bound  $d$

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- In  $P + Q + R$ , make coeffs of every monomial in the  $x$  vars equal to 0

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**Solutions to these constraints yield unsatisfiability witnesses!**

## Example

- Let us consider the system  $-x^2 - xy - x - 1 \geq 0 \wedge y = 0$ .
- Then  $F_{>} = \{\}$ ,  $F_{\geq} = \{-x^2 - xy - x - 1\}$ ,  $F_{=} = \{y\}$ .
- Set degree bound  $d = 2$ .

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- As  $F_{>} = \{\}$ , we have  $\text{Monoid}_d(F_{>}) = \text{Monoid}(F_{>}) = \{1\}$   
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- $\text{Monoid}_d(F_{>} \cup F_{\geq}) = \{1, -x^2 - xy - x - 1\}$ .

$$Q \equiv \underbrace{(\gamma_{x^2}x^2 + \gamma_{xy}xy + \gamma_{y^2}y^2 + \gamma_x x + \gamma_y y + \gamma_0)}_{\Gamma(x,y)} + \gamma'_0(-x^2 - xy - x - 1)$$

where  $\gamma_*$  are unknowns s.t.  $\Gamma(x, y)$  is a sum of squares, and  $\gamma'_0 \geq 0$

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- Hence  $P + Q + R$  is:  $(\gamma_{x^2} - \gamma'_0)x^2 + (\gamma_{xy} - \gamma'_0)xy + \dots$   
yielding equations  $\gamma_{x^2} - \gamma'_0 = \gamma_{xy} - \gamma'_0 = \dots = 0$

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- Let us consider the system  $-x^2 - xy - x - 1 \geq 0 \wedge y = 0$ .
- Then  $F_{>} = \{\}$ ,  $F_{\geq} = \{-x^2 - xy - x - 1\}$ ,  $F_{=} = \{y\}$ .
- Set degree bound  $d = 2$ .

•  $R \equiv (\alpha_x x + \alpha_y y + \alpha_0) y$ , where  $\alpha_x, \alpha_y, \alpha_0$  are unknowns

• As  $F_{>} = \{\}$ , we have  $\text{Monoid}_d(F_{>}) = \text{Monoid}(F_{>}) = \{1\}$

$P \equiv \beta$ , where  $\beta$  is an unknown constrained to  $\beta > 0$

•  $\text{Monoid}_d(F_{>} \cup F_{\geq}) = \{1, -x^2 - xy - x - 1\}$ .

$$Q \equiv \underbrace{(\gamma_{x^2}x^2 + \gamma_{xy}xy + \gamma_{y^2}y^2 + \gamma_x x + \gamma_y y + \gamma_0)}_{\Gamma(x,y)} + \gamma'_0(-x^2 - xy - x - 1)$$

where  $\gamma_*$  are unknowns s.t.  $\Gamma(x, y)$  is a sum of squares, and  $\gamma'_0 \geq 0$

• Hence  $P + Q + R$  is:  $(\gamma_{x^2} - \gamma'_0)x^2 + (\gamma_{xy} - \gamma'_0)xy + \dots$

yielding equations  $\gamma_{x^2} - \gamma'_0 = \gamma_{xy} - \gamma'_0 = \dots = 0$

• A solution is  $\Gamma(x, y) = (x + \frac{1}{2})^2$ ,  $\gamma'_0 = 1$ ,  $\alpha_x = 1$ ,  $\beta = \frac{3}{4}$ , rest = 0

# Sums of Squares

- How can we solve the constraint: “polynomial  $P$  is a sum of squares”?
- In [Parrilo, MP'03]: semidefinite programming. Some disadvantages:
  - Some SDP algorithms can fail to converge if the problem is not strictly feasible (= solution set is not full-dimensional).  
Some works [Monniaux, Corbineau, ITP'11] try to alleviate this problem
  - SDP algorithms use floating-point: postprocessing is needed!

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Some works [Monniaux, Corbineau, ITP'11] try to alleviate this problem
  - SDP algorithms use floating-point: postprocessing is needed!
- Let's **use an SMT(NA) solver** instead of an SDP solver!
- The **basic idea in SDP techniques** can be reused:  
polynomial  $P \in \mathbb{Q}[x]$  is a sum of squares iff there exist a vector of monomials  $\mu^T = (m_1, \dots, m_k)$  over variables  $x$ , and a **positive semidefinite matrix**  $M$  with coefficients in  $\mathbb{Q}$  such that  $P = \mu^T M \mu$ .
- Recall: a symmetric matrix  $M \in \mathbb{R}^{N \times N}$  is *positive semidefinite* if for all  $x \in \mathbb{R}^N$ , we have  $x^T M x \geq 0$ .

# Sums of Squares

- There exist several equivalent conditions that ensure that a symmetric matrix  $M \in \mathbb{R}^{N \times N}$  is positive semidefinite:
  - **Sylvester criterion:** all principal minors are non-negative
  - **Cholesky decomposition:** there exists a lower triangular matrix  $L$  with non-negative diagonal coefficients such that  $M = LL^T$
  - **Gram matrix:** there exists a matrix  $R \in \mathbb{R}^{N \times N}$  such that  $M = R^T R$

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- However, for efficiency reasons we opt for a **light-weight** approach:  
Instead of general sums of squares,  
we consider products of polys of the form  $\sum_{i=1}^n q_i(x_i)$ ,  
where each  $q_i(x_i)$  is a **univariate non-negative polynomial of degree 2**.
- A univariate polynomial  $ax^2 + bx + c$  is non-negative if and only if  
 $(a = 0 \wedge b = 0 \wedge c \geq 0) \vee (a > 0 \wedge b^2 - 4ac \leq 0)$
- In our experiments so far, we have been able to prove unsatisfiability for all problems (from our program analysis application) we tried

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- **Idea:** to exploit failed attempts with the SAT-aimed approach
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  - Let  $P$  be an (unsat) conjunction of polynomial inequalities
  - Let  $C$  be core obtained after ? iterations of [Borralleras et al., JAR'12]
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  - $P'$  is a good candidate to be unsat
- In most cases, as far as we have experimented, this procedure:
  - does reduce significantly the size of the conjunction, and
  - does preserve unsatisfiability
- If unsatisfiability of  $P'$  fails, we can always try with original  $P$

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  - Cheap way of making it **incremental**?
  - Explanations may not be minimal.  
Worth **looking for minimal explanations** (e.g., with Max-SMT)?
- We implemented a prototype in Prolog that, given a conjunction of polynomial inequalities, produces the SMT problem of finding a Positivstellensatz refutation. This is what we have used in the experiments referred here.  
**Future work:** full integration into an **SMT(NA)** system

Thank you!