

Multiagent Systems Sistemas Multiagente

SMA-UPC

Introduction



Knowledge Engineering and Machine Learning Group
UNIVERSITAT POLITÈCNICA DE CATALUNYA
<https://kemig.upc.edu>

Aims of the course

- To provide the student with the knowledge to design and program **distributed multi-agent systems** using **intelligent agents**.
 - What is an agent?
 - What is an intelligent agent?
 - How can intelligent agents be used in distributed problems?
- During the course we will see how to:
 - apply several Artificial Intelligence techniques in Agents,
 - model knowledge in distributed problems,
 - design systems able to distribute decision making and tasks among agents.

Course Contents (1 of 7)

1. Introduction
 - 1.1. Origins
 - 1.2. Agent types
 - 1.3. Agent Architectures
 - 1.3.1. Deliberative Architectures
 - 1.3.2. Reactive Architectures

Course Contents (2 of 7)

2. Knowledge Representation and Communication
 - 2.1. Knowledge Representation
 - 2.1.1. Ontologies: design, methodologies
 - 2.1.2. Mark-up Languages (XML, RDF, DAML+OIL)
 - 2.2. Agent Communication
 - 2.2.1. Communication Protocols
 - 2.2.2. Communication Languages and Performatives (KQML, FIPA ACL)

Course Contents (3 of 7)

- 3. Reasoning in Agents
 - 3.1. Introduction to reasoning
 - 3.2. Deductive Reasoning Agents
 - 3.3. Practical Reasoning Agents. BDI agents

Course Contents (4 of 7)

- 4. Multiagent Systems Design
 - 4.1. Agent-Oriented Software Engineering methodologies
 - 4.1.1. Introduction to Agent-Oriented Software Engineering
 - 4.1.2. GAIA methodology
 - 4.1.3. Prometheus Methodology

Course Contents (5 of 7)

- 4.2. Coordination Models
 - 4.2.1. Introduction to Coordination.
 - 4.2.2. Social Models
 - 4.2.2.1. Reputation and Trust. Social Roles.
 - 4.2.2.2. Electronic Organizations
 - 4.2.2.3. Electronic Institutions
 - 4.2.3. Non-social Models
 - 4.2.3.1. Explicit Coordination
 - 4.2.3.2. Implicit Coordination

Course Contents (6 of 7)

- 5. Situated Agents (robots)
 - 5.1. Perception Problems
 - 5.2. Problems on action execution
 - 5.3. Situated Agents' Architectures
 - 5.3.1. Reactive Architectures
 - 5.3.2. Deliberative Architectures
 - 5.3.3. Hybrid Architectures
 - 5.4. Knowledge Representation and Uncertainty
 - 5.5. Planning and Uncertainty
 - 5.6. Multi-Robot Systems

Course Contents (7 of 7)

6. Other applications for SMA

6.1. Interacting with humans

6.1.1. Adjustable Autonomy

6.1.2. User Modelling

6.2. Simulations

6.3. Multiagent Systems for videogames

Course Material

- No need to buy books, but if you want to buy one:
 - Wooldridge, M. **“Introduction to Multiagent Systems”**. John Wiley and Sons, 2002.
- If you feel that your knowledge on AI is not in good condition, have a look to:
 - Russell, S. & Norvig, P. **“Artificial Intelligence: A Modern Approach”** Prentice-Hall Series in Artificial Intelligence. 2009
- References to papers and other on-line documents will be provided during the course.
- Most of the material will be made available at the course’s website:
 - <http://www.lsi.upc.edu/~jvazquez/teaching/sma-upc/>

Who am I?

- Javier Vázquez-Salceda
 - Doctor in AI at UPC
 - Associate Professor at the Knowledge Engineering and Machine Learning Group (KEMLg)
- Research interests: theoretical and applied issues of **Multiagent Systems (MAS)**.
- specially interested in
 - the conflict between Autonomy and Control in agents,
 - the relation between agent goals&behaviour vs. the social expectations and/or regulations,
 - the use of norms to provide flexible specifications of accepted behaviour
- Where am I?
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11

Who are you?

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12

References

- Luck, M., McBurney, P., Shehory, Onn, Willmott, S. “Agent Technology: Computing as interaction. A Roadmap to Agent Based Computing”. Agentlink, 2005. ISBN 085432 845 9
- Wooldridge, M. “Introduction to Multiagent Systems”. John Wiley and Sons, 2002.
- Russell, S. & Norvig, P. “Artificial Intelligence: A Modern Approach” Prentice-Hall Series in Artificial Intelligence. 2009 ISBN 0-13-103805-2
- Weiss, G. “Multiagent Systems: A modern Approach to Distributed Artificial Intelligence”. MIT Press. 1999. ISBN 0262-23203