

**Automatic Generation of
Polynomial Loop Invariants:
Algebraic Foundations**

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Overview of the Talk

1. **Motivation** for automatically generating invariants
2. Simple loops with **sequences of assignments**
3. Loops including **conditional statements**
4. **Algorithm** for generating polynomial invariants
5. **Termination** of the algorithm

Motivation

Program Verification

- Program verification failed due to:
 - program annotation **by hand**
 - **weak** theorem provers
 - Current theorem provers are **quite powerful**
 - About program annotation:
 - Pre/postconditions: **useful** documentation
 - Loop invariants: **tedious** to write
- ⇒ **Automatic generation of loop invariants**

Sequences of Assignments

Example: Square Root Program

{Pre: $N \geq 0$ }

$a := 0; s := 1; t := 1;$

while $(s \leq N)$ do

$a := a + 1;$

$s := s + t + 2;$

$t := t + 2;$

end while

{Post: $a^2 \leq N < (a + 1)^2$ }

- Need invariant to verify program
- Good invariant: $a^2 \leq N \wedge t = 2a + 1 \wedge s = (a + 1)^2$

Sequences of Assignments

Generating Invariants (1)

- **Program states** \equiv solution to the recurrence

$$\begin{cases} a_{n+1} = a_n + 1 \\ s_{n+1} = s_n + t_n + 2 \\ t_{n+1} = t_n + 2 \end{cases}, \begin{cases} a_0 = 0 \\ s_0 = 1 \\ t_0 = 1 \end{cases}$$

$(a_n, s_n, t_n) \equiv$ **program state** after n loop iterations

Sequences of Assignments Generating Invariants (2)

$$\begin{cases} a_n = n \\ s_n = (n + 1)^2 \\ t_n = 2n + 1 \end{cases}$$

- The **infinite** formula

$$(a = 0 \wedge s = 1 \wedge t = 1) \vee (a = 1 \wedge s = 4 \wedge t = 3) \vee \dots \equiv$$

$$\equiv \bigvee_{n=0}^{\infty} (a = n \wedge s = (n + 1)^2 \wedge t = 2n + 1)$$

is invariant

- Want a **finite** invariant formula !

Sequences of Assignments Eliminating Loop Counters

- The infinite formula can be replaced by

$$\exists n(a = n \wedge s = (n + 1)^2 \wedge t = 2n + 1)$$

- Need for quantifier elimination

- In the example it is obvious:

$$a = n \implies s = (a + 1)^2 \wedge t = 2a + 1 \text{ is loop invariant}$$

- **Gröbner bases** can be used to eliminate auxiliary variables such as **loop counters**

Polynomial Invariants Form an Ideal

- For any program state (a, s, t) ,

$$s - (a + 1)^2 = 0$$

$$t - (2a + 1) = 0$$

- For any polynomials p, q ,

$$p(a, s, t)(s - (a + 1)^2) + q(a, s, t)(t - (2a + 1)) = 0$$

- In general polynomial invariants form an **ideal**

Handling Conditional Statements

Example: Factor Program

{Pre: $N \geq 1 \wedge N \bmod 2 = 1 \wedge R^2 \geq N > (R - 1)^2$ }

$x := R; y := 0; r := R^2 - N;$

while ($r \neq 0$) **do**

if ($r < 0$) **then**

$r := r + 2x + 1; x := x + 1;$

else

$r := r - 2y - 1; y := y + 1;$

end if

end while

{Post: $x \neq y \wedge N \bmod (x - y) = 0$ }

- Good invariant: $N \geq 1 \wedge N + r = x^2 - y^2$

Handling Conditional Statements

Generating Invariants (1)

- 1st idea:

1. Compute invariants for two distinct loops:

<pre>while true do r := r + 2x + 1; x := x + 1; end while</pre>	<pre>while true do r := r - 2y - 1; y := y + 1; end while</pre>
---------------------------------------------------------------------	---------------------------------------------------------------------

2. Compute *common* invariants for both loops

- Finding *common* invariants \equiv Finding *intersection* of polynomial invariant *ideals*
- Gröbner bases used to compute *intersection of ideals*

Handling Conditional Statements

Generating Invariants (2)

```
while true do  
  r := r + 2x + 1;  
  x := x + 1;  
end while
```

$\langle y, -r - N + x^2 \rangle$

```
while true do  
  r := r - 2y - 1;  
  y := y + 1;  
end while
```

$\langle x - R, r - R^2 + N + y^2 \rangle$

$\langle x^2 - r - N - y^2, yx - Ry, y^3 - R^2y + ry + Ny \rangle$

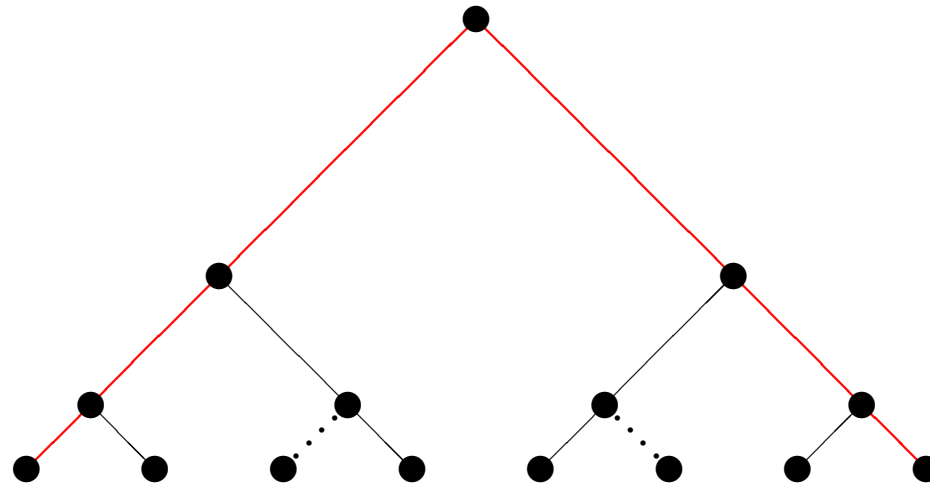
Problem: not all polynomials in the intersection are invariants

- The only invariant polynomial is $x^2 - r - N - y^2$
- Others **are not** invariants of the original loop

Handling Conditional Statements

Generating Invariants (3)

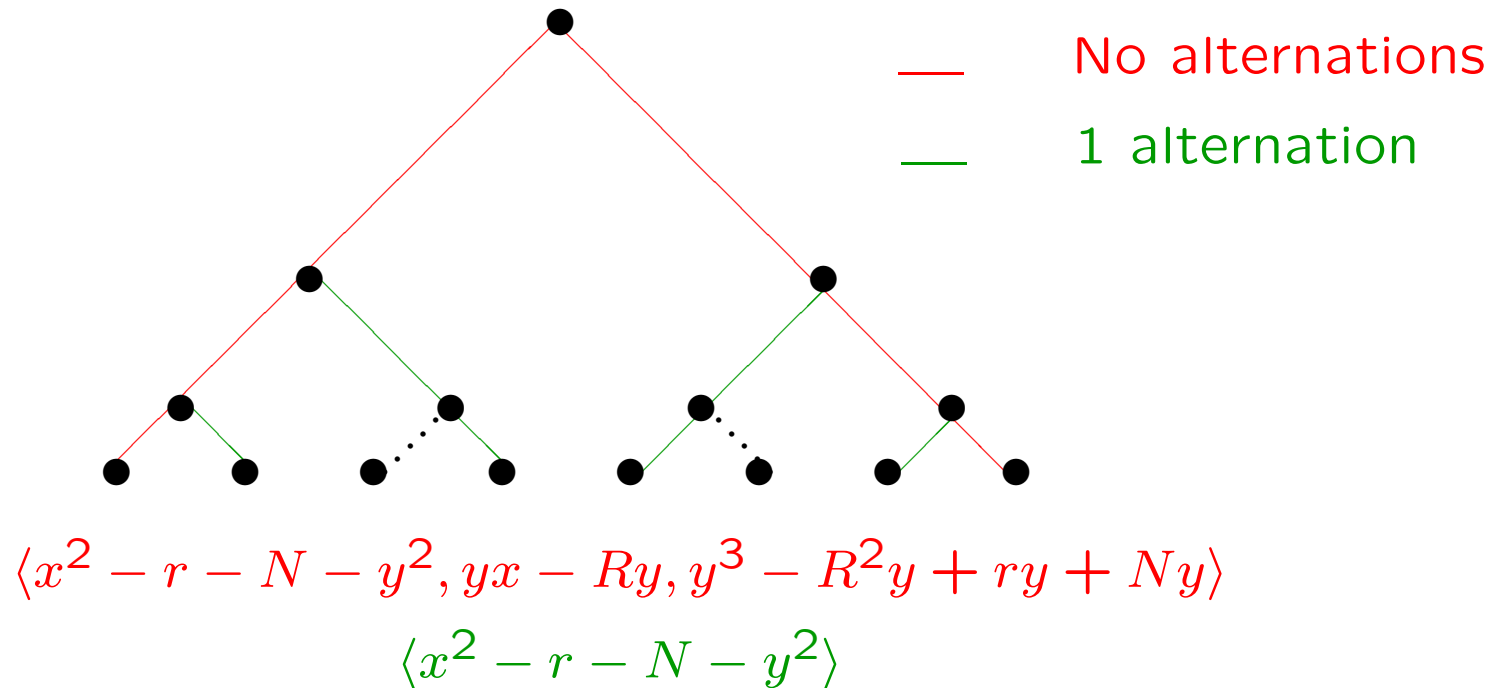
- Tree of all possible execution paths:



- Found common invariants to the *two* extreme paths
- True invariants are common to *all* paths !

Handling Conditional Statements Generating Invariants (4)

- 2nd idea: intersecting with more paths
- For example: paths with at most one alternation



Algorithm for Computing Invariants (1)

Program

```
 $x := \bar{\alpha};$   
while true do  
   $\bar{x} := f(\bar{x});$   
  or  
   $\bar{x} := g(\bar{x});$   
end while
```

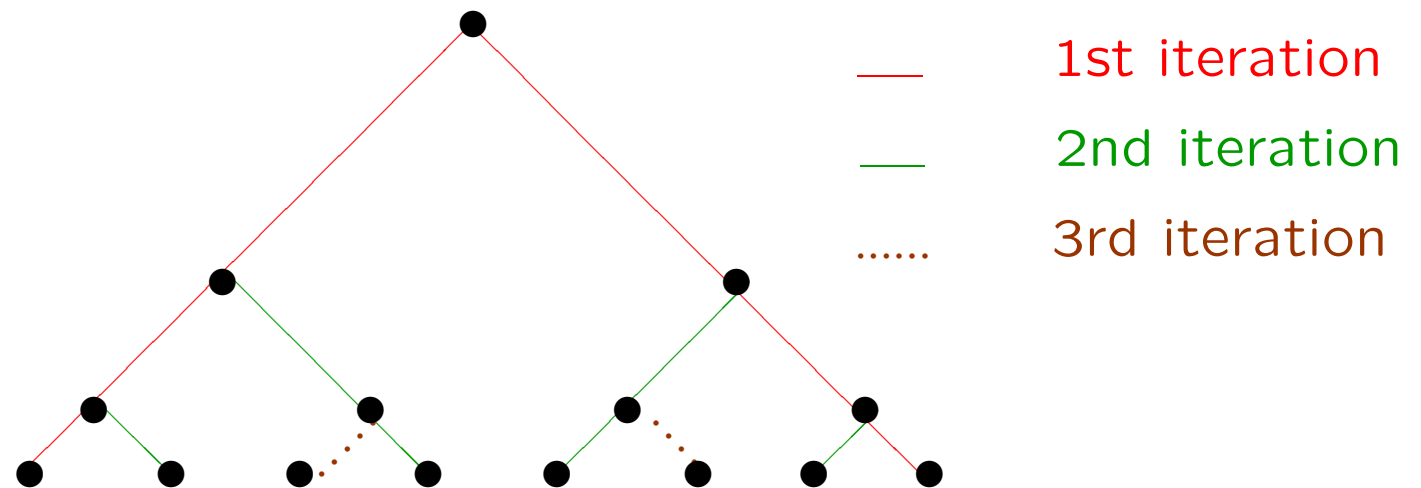
Algorithm

```
 $I' := \langle 1 \rangle; I := \langle x_1 - \alpha_1, \dots, x_m - \alpha_m \rangle;$   
while  $I' \neq I$  do  
   $I' := I;$   
   $I := \bigcap_{n=0}^{\infty} [I(\bar{x} \leftarrow f^{-n}(\bar{x}))$   
     $\cap I(\bar{x} \leftarrow g^{-n}(\bar{x}))];$   
end while
```

Algorithm for Computing Invariants (2)

- After N iterations:

$I \equiv$ intersection for all paths with $\leq N - 1$ alternations



Algorithm for Computing Invariants (3)

- The value of I stabilizes
- Termination in $O(m)$ iterations, where $m =$ number of variables
- **Correctness** and **completeness** proofs in the report
- Implemented in **Maple**:
 1. Solving recurrences
 2. Eliminating variables
 3. Intersecting ideals

} Gröbner bases

Algorithm for Computing Invariants (4)

Table of Examples

PROGRAM	COMPUTING	VARIABLES	BRANCHES	TIMING
freire1	$\sqrt{\quad}$	2	1	< 3 s.
freire2	$\sqrt[3]{\quad}$	3	1	< 5 s.
cohencu	cube	4	1	< 5 s.
cousot	toy	2	2	< 4 s.
divbin	division	3	2	< 5 s.
dijkstra	$\sqrt{\quad}$	3	2	< 6 s.
fermat2	factor	3	2	< 4 s.
wensley2	division	4	2	< 5 s.
euclidex2	gcd	6	2	< 6 s.
lcm2	lcm	4	2	< 5 s.
factor	factor	4	4	< 20 s.

PC Linux Pentium 4 2.5 Ghz

Termination (1)

Toy program

```
 $x := 0; y := 0;$   
while true do  
     $x := x + 1;$   
    or  
     $y := y + 1;$   
end while
```

- Program states $\equiv \mathbb{N} \times \mathbb{N}$
- Assignments:

$$f(x, y) = (x + 1, y)$$

$$g(x, y) = (x, y + 1)$$

- Initial state $(x, y) = (0, 0) \longrightarrow$ initial ideal $\langle x, y \rangle$

Termination (2)

- 1st iteration of the algorithm

1st branch: $f(x, y) = (x + 1, y)$

$$\begin{cases} x_{n+1} = x_n + 1 \\ y_{n+1} = y_n \end{cases}, \begin{cases} x_0 = 0 \\ y_0 = 0 \end{cases} \longrightarrow \begin{cases} x_n = n \\ y_n = 0 \end{cases}$$

Invariant ideal 1st branch: $\langle y \rangle$

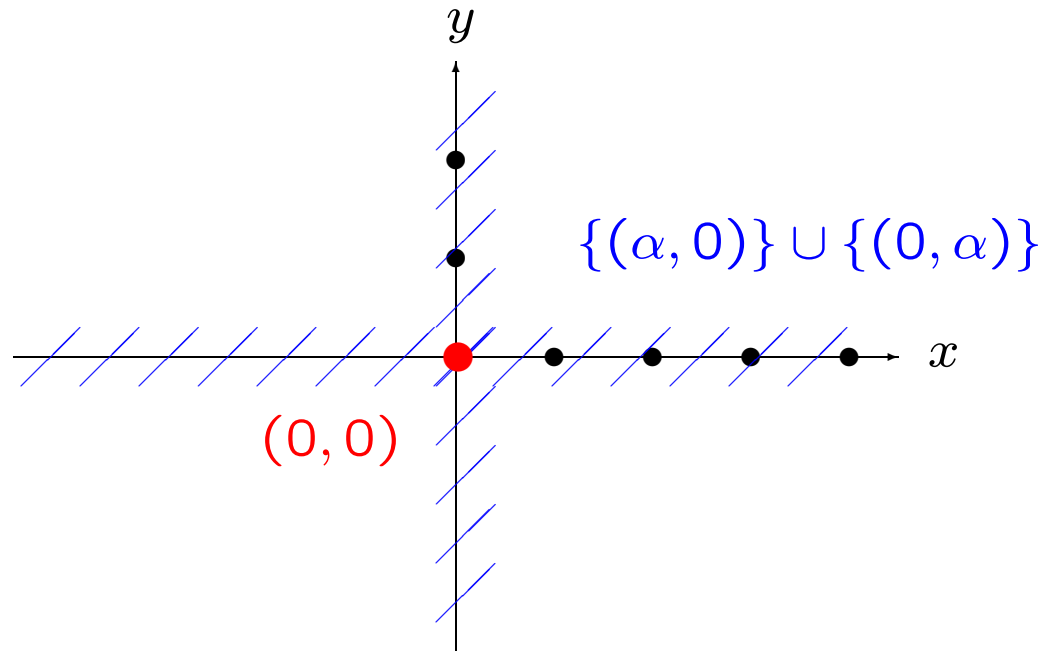
2nd branch: $g(x, y) = (x, y + 1)$

$$\begin{cases} x_{n+1} = x_n \\ y_{n+1} = y_n + 1 \end{cases}, \begin{cases} x_0 = 0 \\ y_0 = 0 \end{cases} \longrightarrow \begin{cases} x_n = 0 \\ y_n = n \end{cases}$$

Invariant ideal 2nd branch: $\langle x \rangle$

Intersection ideal: $\langle xy \rangle$

Termination (3)



- **Step 0:** $\langle x, y \rangle \rightarrow \{(0, 0)\}$, dimension 0
- **Step 1:** $\langle xy \rangle \rightarrow \{(\alpha, 0)\} \cup \{(0, \alpha)\}$, dimension 1

The dimension has increased !

Termination (4)

- 2nd iteration of the algorithm
 - Ideal computed: $\{0\}$
 - Solution space: \mathbb{R}^2 , dimension 2

The dimension has increased again !

- At each step of the algorithm, the **dimension increases**
- If there are m variables, it terminates in $O(m)$ steps

Related Work (1)

- Karr (1976): *linear equalities*
- Cousot, Halbwachs (1978): *linear inequalities*
- Colón, Sankaranarayanan, Sipma (2003): *linear inequalities*
- Müller-Olm, Seidl (2003): *polynomial equalities*
- Sankaranarayanan et al (2004): *polynomial equalities*
- Müller-Olm, Seidl (2004): *polynomial equalities*
- Rodríguez-Carbonell, Kapur (2004): *polynomial equalities*

Related Work (2)

Overview Polynomial Invariants

Work	Restrictions	Nesting	Conditions	Complete	Application
[MOS03]	bounded degree	yes	no	yes	<i>intraprocedural</i>
[SSM03]	prefixed form	yes	yes	no	<i>interprocedural</i>
[MOS04]	prefixed form	yes	yes	yes	<i>interprocedural</i>
[RCK04]	bounded degree	yes	yes	yes	<i>interprocedural</i>
[RCK04]	no restriction	no	no	yes	<i>interprocedural</i>

Conclusions

- **Correct** and **complete** algorithm for **polynomial** invariants
- **First** method not bounding *a priori* degree of invariants
- Applicable to loops **without nesting**
- Terminates in $O(m)$ iterations, where m = number of variables
- Implemented and being integrated into a verifier
- Part of a **general framework** for generating invariants
 - Rich theory in algebraic geometry and polynomial ideals
 - Beyond numbers and polynomials we need:
 - solving recurrences
 - eliminating variables
 - ...